



Change Summary

Published Date	Edition	Chapter	Description of Changes
May 2026	2026	Complete Spacecraft Platforms	Entire chapter updated.
		Power	Entire chapter updated.
		In-Space Propulsion	Entire chapter updated.
		Guidance Navigation & Control	Updates to Rendezvous, Proximity, Operations, and Docking section.
		Structures, Materials, and Mechanisms	Minor edits throughout chapter.
		Thermal Control	Minor edits throughout chapter.
		SmallSat Avionics	Entire chapter updated.
		Communications	Free Space Optical Communications and Future Communications Technology Sections updated.
		Launch, Integration, Deployment, and Orbital Transport	Updates to Launch Paradigm; Included hardware tables; Orbital Maneuvering Vehicle section updated.
		Ground Data Systems and Mission Operations	Updated content in Ground Segment Services, Ground Station Components, Ground Data and Supporting Systems sections.
		ID and Tracking	Minor edits throughout chapter.
		Deorbit Systems	Minor edits throughout chapter.



Preface

NASA's *Small Spacecraft Technology State-of-the-art* report is updated annually to capture new information on publicly available small spacecraft systems from NASA and other sources. Each chapter captures the development status of current state-of-the-art SmallSat technologies, along with design considerations for readers when identifying components for a mission. The organizational approach for each chapter includes an introduction to the technology, the current development status of procurable systems, and summary tables of the technologies surveyed. In this way, each chapter presents a stand-alone report on the given spacecraft subsystem, with updated information on new and maturing technologies and reference missions as applicable.

When the first edition of this report was published in 2013, 247 CubeSats and 105 other non-CubeSat small spacecraft under 50 kilograms (kg) had been launched worldwide representing less than 2% of the total mass launched into orbit over multiple years. Small satellite flight heritage has greatly increased since then, with small spacecraft becoming the primary means for commercial, government, private, and academic institutions to access space. Since 2023, there has been an influx of mini-class small spacecraft constellations with a mass of 201–600 kg, as well as a new generation of larger small spacecraft constellations weighing 600–1,200 kg (1). While updates in all chapters reflect this growth in the small spacecraft market, a focused effort was made to update areas reflecting recent technology developments that may ultimately bridge existing technology gaps.

This edition features updates that reflect the next generation of small spacecraft missions. Demands for larger platforms are discussed in the *Complete Spacecraft Platforms* chapter and expanded upon in the *Integration, Launch, Deployment, and Orbital Transport* chapter. This new launch paradigm indicates an increase in Orbital Maneuvering/Transport Vehicle (OMV/OTV) services as well as in autonomous spacecraft capabilities to support higher payload data throughput. The *SmallSat Avionics* chapter received a complete rewrite that expands on the increasing onboard processing capabilities of SmallSats and CubeSats. Future RF and Optical Communications technologies and missions are highlighted in the *Communications* chapter, and in the *Guidance, Navigation, and Control* chapter, the RPOD section was updated to reflect recent interest and developments. All content in the *Power Systems* and *In-Space Propulsion* chapters was updated to reflect continued progression toward more capable SmallSats.

This report should not be considered a comprehensive overview of all technologies, but rather a general overview of current state-of-the-art SmallSat technologies and their development status. It should be noted that technology maturity designations may vary with changes to payload, mission requirements, reliability considerations, and/or the environment in which performance was demonstrated. Readers are highly encouraged to contact companies for further information regarding the performance and maturity of the described technology. Any companies mentioned in this report are for informational purposes only and do not constitute an endorsement by NASA.

References

- (1) Bryce and Space Technology. "SmallSat by the Numbers, 2025." Accessed March 14, 2026. [Online] Available at: https://brycetek.com/reports/report-documents/Bryce_SmallSats_2025.pdf



Chapter Glossary

(EELV)	Evolved Expendable Launch Vehicle
(ESPA)	EELV Secondary Payload Adapter
(FASTSAT)	Fast, Affordable, Science and Technology Satellite
(LADEE)	Lunar Atmosphere and Dust Environment Explorer
(LCROSS)	Lunar Crater Observation and Sensing Satellite
(NODIS)	NASA Online Directives Information System
(SSDS)	Small Spacecraft & Distributed Systems
(SST)	Small Spacecraft Technology
(STMD)	Space Technology Mission Directorate
(TMA)	Technology Maturity Assessment
(TRL)	Technology Readiness Level
(U)	Unit



1.0 Introduction

1.1 Objective

The objective of this report is to assess and provide an overview of the state of the art in small spacecraft technologies for use by mission designers, project managers, technologists, and students, connecting current small spacecraft missions to available technologies. This report focuses on the spacecraft system in its entirety, provides current best practices for integration and key considerations for the reader where possible, and presents devices from publicly available sources for each specific spacecraft subsystem.

This report is a survey of small spacecraft technologies sourced from open literature; it is not an original source. In addition, this report only considers literature in the public domain. Information presented in this report is limited to SmallSat technology that is publicly available as of April 1, 2026. It does not include information on instrumentation, science payloads, or advances or developments that have not been publicly disclosed. Commonly used sources for data include manufacturer datasheets, press releases, conference papers, journal papers, public filings with government agencies, news articles, presentations, the compendium of databases accessed via NASA's Small Spacecraft Systems Virtual Institute (S3VI) Information Search, and engagement with companies. Data not appropriate for public dissemination, such as proprietary, export controlled, or otherwise restricted data, are not considered. We encourage the SmallSat community to publish mission outcomes and technology development milestones in publicly available conference papers, press releases, or company websites so they can be reflected in future editions of this report.

This report is funded by NASA's Space Technology Mission Directorate (STMD). It was first commissioned by the Small Spacecraft & Distributed Systems (SSDS, formerly Small Spacecraft Technology (SST) program) capability within STMD in mid-2012 in response to the rapid growth in interest in using small spacecraft for low-Earth orbit, low-cost missions. The report was subsequently updated in 2015, 2018, 2020, 2021, 2022, 2023, 2024, and 2026 to capture SmallSat technology growth and maturation. In addition to reporting currently available state-of-the-art technologies that have achieved Technology Readiness Level (TRL) 5 or above, a prognosis is provided describing technologies as "on the horizon" if they are being considered for future application.

1.2 Scope

The NASA-SmallSat era began at NASA Ames Research Center with the launch of Pioneer 10 and 11 in March 1972 and April 1973, respectively, where both spacecraft weighed < 600 kg. The NASA SmallSat mission gained momentum when NASA initiated the Small Explorer (SMEX) program in 1988 to encourage the development of small spacecraft with masses in the range of ~60–350 kg to reduce cost. In 1998 NASA Ames focused its SmallSat program on lunar exploration and launched Lunar Prospector (< 700 kg), followed by the Lunar Crater Observation and Sensing Satellite (LCROSS), (< 630 kg) in 2009, and the Lunar Atmosphere and Dust Environment Explorer (LADEE), (~380 kg) which was launched in September 2013. In late 2010, NASA launched its first minisatellite called Fast, Affordable, Science and Technology Satellite (FASTSAT), which had a launch mass ~180 kg. This decrease in spacecraft mass, reduced overall cost, and increase in science capabilities ignited interest in miniaturization and maturity of aerospace technologies which have proven to be capable of producing more complex missions for less cost.

Early efforts for this report began in 2012, when the adoption of the Evolved Expendable Launch Vehicle (EELV) Secondary Payload Adapter (ESPA) as a launch strategy for small spacecraft became regular use. The ESPA provided a modular packaging approach for six payload slots of

up to 180 kg mass allocation and was implemented by the U.S. Air Force for launching its secondary payload. To supplement the rising small spacecraft awareness and cost-effective launch mechanisms, this report focused on spacecraft technology where “180 kg mass limit” served as a convenient metric to classify the maximum “SmallSat” mass. SmallSats are generally categorized by their mass, and this report adopts the following five small spacecraft mass categories (1):

- minisatellites are spacecraft with a total mass of 100 – 180 kg;
- microsatellites have a total spacecraft mass of 10-100 kg;
- nanosatellites have a total mass of 1 – 10 kg;
- picosatellites have a mass of 0.1 –1 kg; and
- femtosatellites have a total spacecraft mass 0.01 – 0.09 kg.

Figure 1.1 offers examples of spacecraft categorized by mass. On the lower mass end, there are projects such as KickSat-2, which deployed 100-centimeter (cm) scale “ChipSat” spacecraft, or Sprites, from a 2U femtosatellite deployer in March 2019. These femtosatellite ChipSats are the size of a large postage stamp and have a mass below 10 grams.

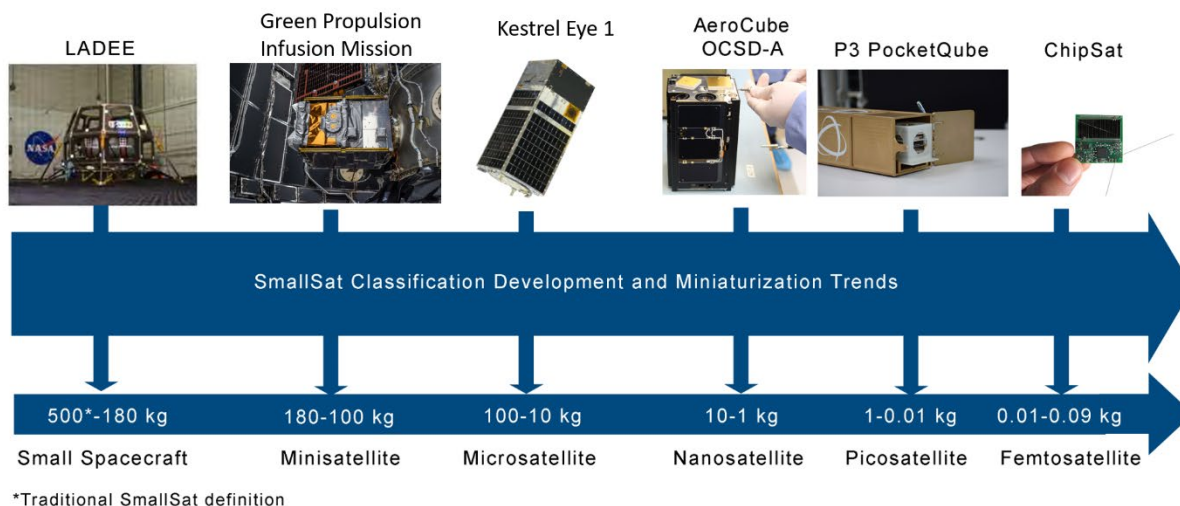


Figure 1.1: Overview of small spacecraft categories. Credit: NASA, SpaceX, Redwire Space, and Alba Orbital.

In 1999, a collaboration between California Polytechnic State University in San Luis Obispo and Stanford University in Stanford, California, developed a small educational platform called a "CubeSat" which was designed for academic space exploration and research. CubeSats are now a common form of small spacecraft that can weigh only a few kilograms and are based on a form factor of a 10 cm square cube, or unit (U) (1). While the original CubeSat was composed of a single 1U cube, in 2014 the CubeSat form factor expanded to 6U, and it is now common to combine multiple cubes to form larger units, as shown in Figure 1.3. These larger CubeSat sizes have become more standardized and popular in the past few years as much more science can be achieved at less cost with the additional volume, power, and overall increase in capability.



It is common to interchange the terms “CubeSat” and “NanoSat” (short for nanosatellite) as the original 1-3U CubeSat platforms fell under the nanosatellite category. Since the physical expansion of CubeSats now goes beyond the 6U form factor, CubeSats fall into both nanosatellite and microsatellite categories. Certain chapters of this report have a particular emphasis on CubeSat platforms as nanosatellite applications have expanded in recent years.

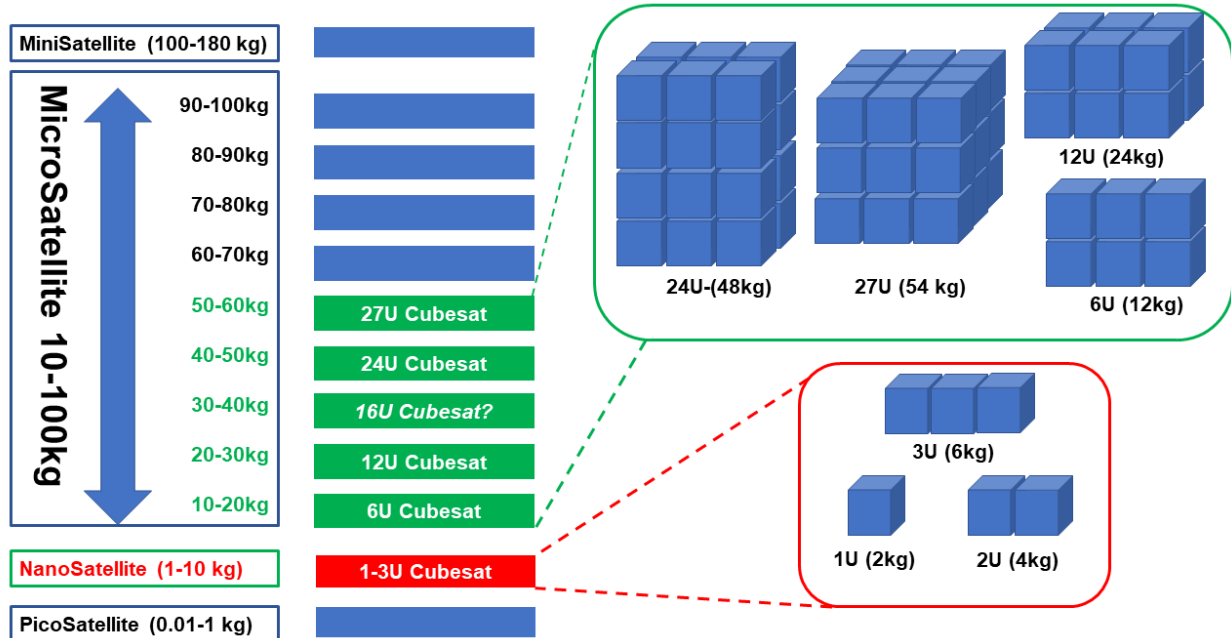


Figure 1.2: CubeSats are a class of nano- and microsatellites that use a standard size and form factor. Nanosatellite sizes compared to CubeSat containerized sizes. Credit: NASA.

1.3 Assessment

A central element of this report is to list state-of-the-art technologies by NASA standard Technology Readiness Level (TRL) as defined in NASA System Engineering Handbook. The authors have endeavored to independently verify the TRL value of each technology by reviewing and citing published test results or publicly available data to the best of their ability. Where test results and data disagree with vendors' own advertised TRL, the authors have attempted to engage the vendors to discuss the discrepancy. Readers are strongly encouraged to follow the references cited in the literature describing the full performance range and capabilities of each technology. Readers of this report should contact individual companies to further clarify information. It is important to note that this report takes a broad system-level view. To attain a high TRL, the subsystem must be in a flight-ready configuration with all supporting infrastructure—such as mounting points, power conversion, and control algorithms—in an integrated unit.

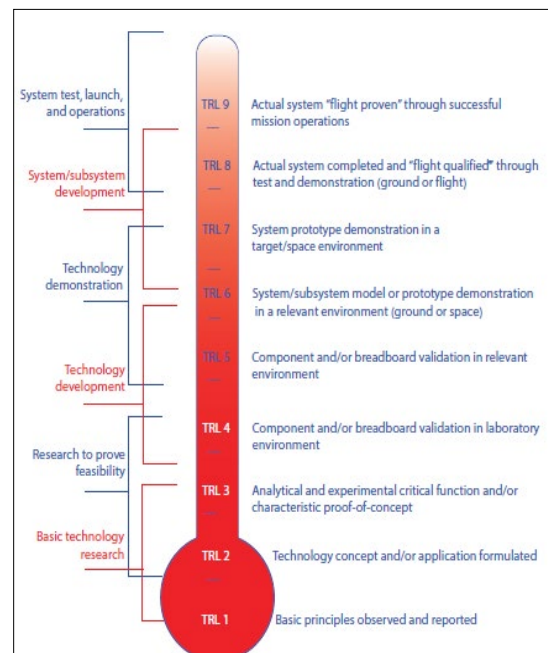


Figure 1.3: NASA's standard Technology Readiness Level scale. Credit: NASA.



While “state-of-the-art” may be defined as the most recent development stage of technology, this report defines “state-of-the-art” in the context of NASA’s TRL scale (Figure 1.3) when assessing SmallSat technology. A technology may be deemed state-of-the-art whenever its TRL is larger than or equal to 5. A TRL of 5 indicates that the component and/or breadboard with realistic support elements was built and operated for validation in a relevant environment to demonstrate overall performance in critical areas. Success criteria include documented test performance demonstrating agreement with analytical predictions and documented definition of scaling requirements. Performance predictions are made for subsequent development phases (2).

An accurate TRL assessment requires a high degree of technical knowledge on a subject device, and an in-depth understanding of the mission (including interfaces and environment) on which the device was flown. TRL values vary depending on design factors for a specific technology. For example, differences in TRL assessment based on the operating environment may result from mechanical loads, mission duration, the thermal environment, or radiation exposure. The authors believe TRLs are most accurately determined when assessed within the context of a program’s unique requirements. If a technology has flown on a mission without success, or without providing valid confirmation to the operator, such claimed “flight heritage” is discounted. Some older technologies may still be well suited to certain mission needs and still be regarded as “state-of-the-art.” For a technology to be considered obsolete, “retired”, or no longer “state-of-the-art”, its performance must have been surpassed by newer technology such that it is no longer used.

While a technology with a TRL value lower than or equal to 4 may not be state of the art, in some cases these technologies may be considered “on the horizon.” A TRL of 4 is defined as a component and/or breadboard validated in a laboratory environment with documented test performance demonstrating agreement with analytical predictions and a documented definition of the relevant environment. These promising technologies may soon be considered state-of-the-art for small spacecraft.

NASA standard TRL requirements for this report edition are stated in NPR 7123.1D, Appendix E, which is effective through July 05, 2028. The criteria for selection of appropriate TRL are described in the NASA Systems Engineering Handbook 6105 Rev 2 Appendix G: Technology Assessment/Insertion. Please refer to the NASA Online Directives Information System (NODIS) website <https://nodis3.gsfc.nasa.gov/> for NPR documentation. The following paragraphs in sections 1.3.1 and 1.3.2 of this Introduction are excerpts from the NASA Engineering Handbook 6105 Rev 2 (pp. 252 – 254). They highlight important aspects of NASA TRL guidelines in hopes of eliminating confusion on terminology and heritage systems.

1.3.1 Terminology

“At first glance, the TRL descriptions in Figure 1.3 appear to be straightforward. It is in the process of trying to assign levels that problems arise. A primary cause of difficulty is in terminology, e.g., everyone knows what a breadboard is, but not everyone has the same definition. Also, what is a “relevant environment?” What is relevant to one application may or may not be relevant to another. Many of these terms originated in various branches of engineering and had, at the time, very specific meanings to that particular field. They have since become commonly used throughout the engineering field and often acquire differences in meaning from discipline to discipline, some differences subtle, some not so subtle. “Breadboard,” for example, comes from electrical engineering where the original use referred to checking out the functional design of an electrical circuit by populating a “breadboard” with components to verify that the design operated as anticipated. Other terms come from mechanical engineering, referring primarily to units that are subjected to different levels of stress under testing, e.g., qualification, protoflight, and flight units. The first step in developing a uniform TRL assessment (see Figure 1.4) is to define the terms

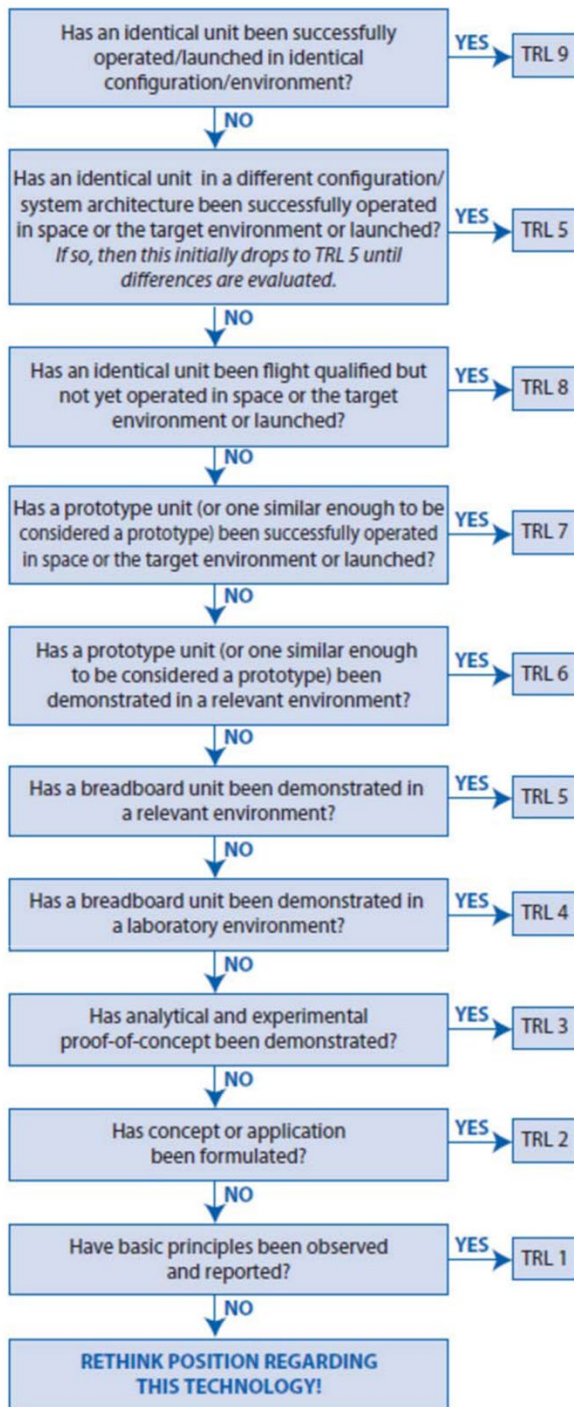


Figure 1.4: Technology Maturity Assessment thought process. Credit: NASA.

used. It is extremely important to develop and use a consistent set of definitions over the course of the program/project.”

1.3.2 Heritage Systems

“Note the second box particularly refers to heritage systems (Figure 1.4). If the architecture and the environment have changed, then the TRL decreases to TRL 5—at least initially. Additional testing may need to be done for heritage systems for the new use or new environment. If in subsequent analysis the new environment is sufficiently close to the old environment or the new architecture is sufficiently close to the old architecture, then the resulting evaluation could be TRL 6 or 7, but the most important thing to realize is that it is no longer at TRL 9. Applying this process at the system level and then proceeding to lower levels of subsystems and components identifies those elements that require development and sets the stage for the subsequent phase, determining the new TRL.”

References

- (1) NASA. What are SmallSats and CubeSats? February 26, 2015. Revised August 6, 2017. <https://www.nasa.gov/content/what-are-small-sats-and-cubesats>
- (2) NASA Systems Engineering Handbook. NASA/SP-2016 6105 Rev. 2.