



Turbulence Closure Modeling with Differentiable Physics

JULY 28, 2022

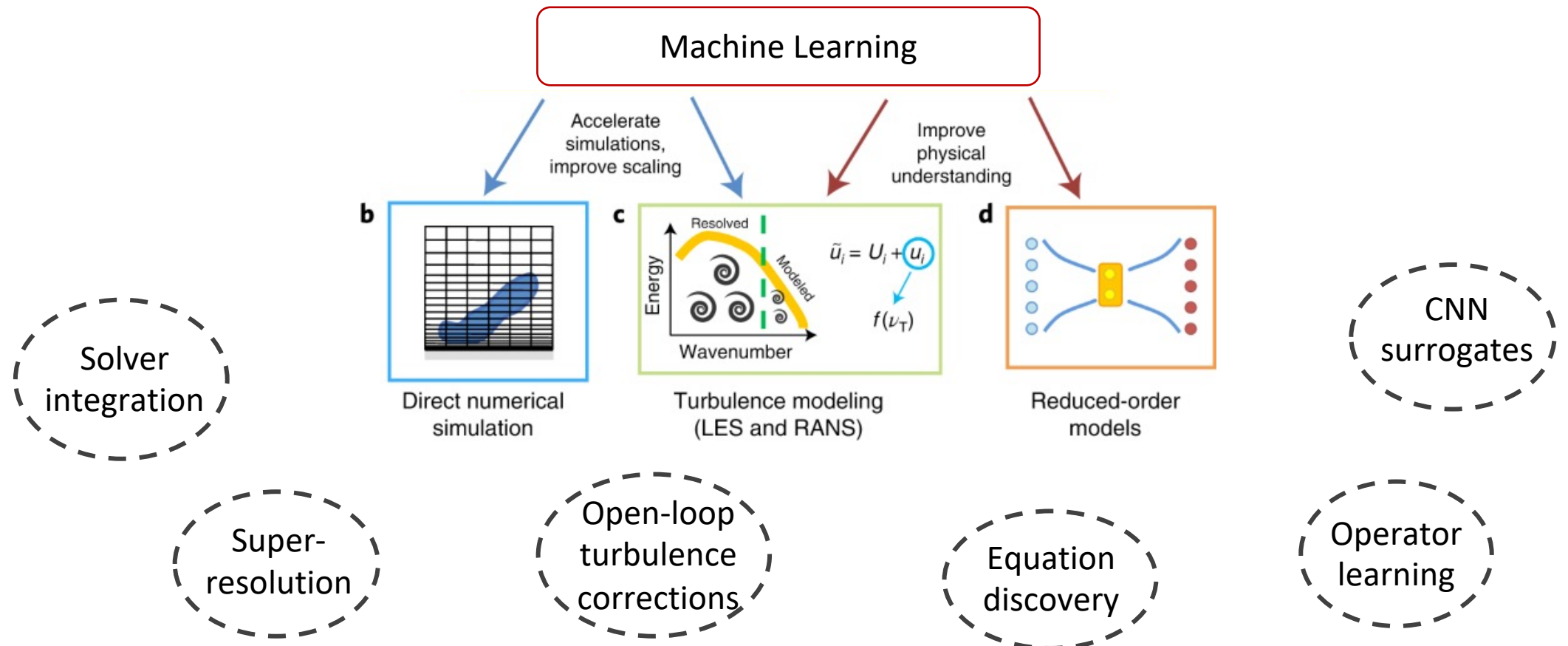
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Agenda

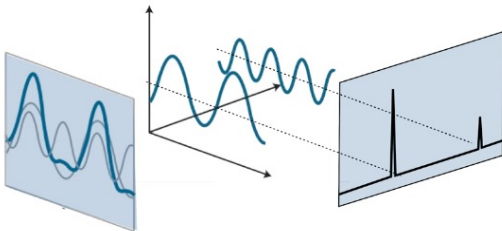
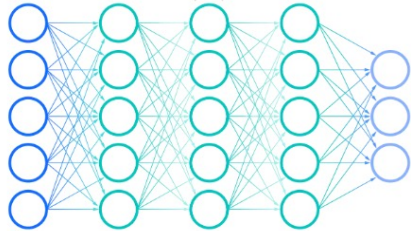
1. Motivation and background
2. Differentiable Neural Closures
 - Learning more accurate closure dynamics
3. Turbulence predictions with equivariant GNNs
 - Reducing time to solution for complex flows
4. Conclusions and future directions

State of ML in CFD



Approximation Theory and Curse of Dimensionality

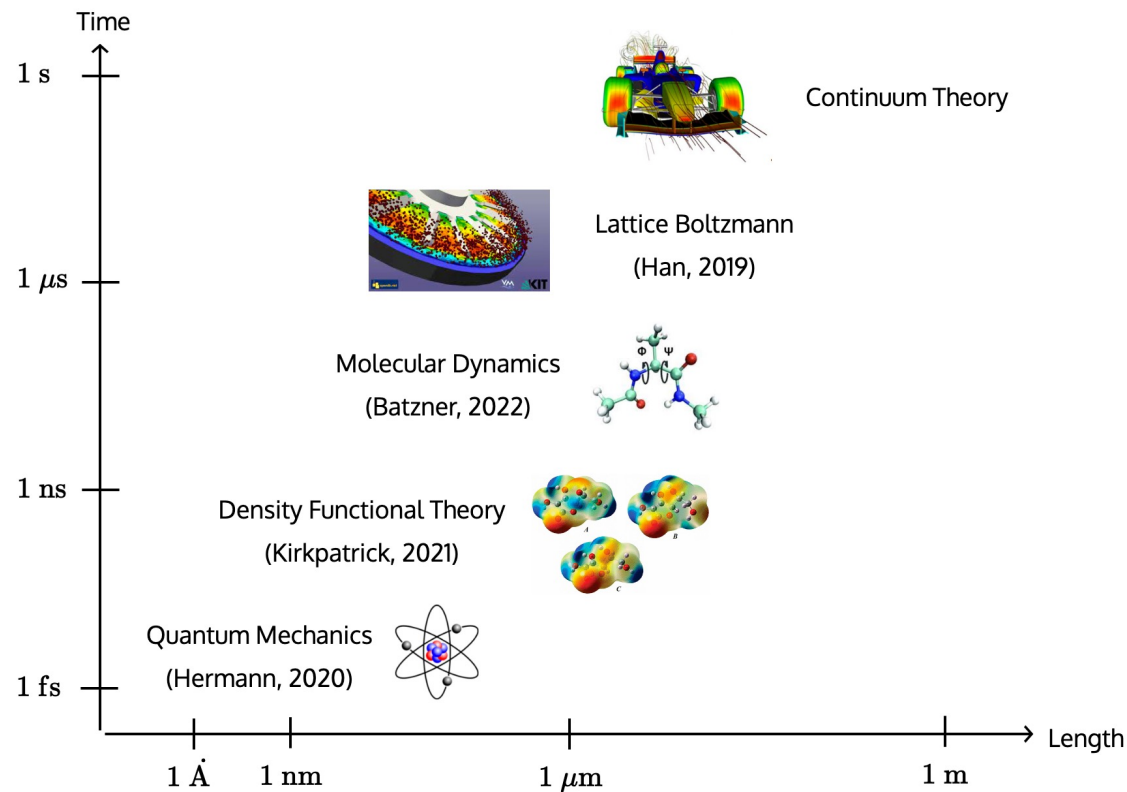
$$f = \tilde{f} + \mathcal{O}(h)$$

| Orthogonal Functions | Deep Neural Networks |
|--|---|
| $\tilde{f} = \sum_{i=1}^N f_i \phi_i(x)$  | $\tilde{f} = W_L \circ \sigma(W_{L-1} \circ (\dots (\sigma W_0 x)) + b_{L-1})$  |
| $h \sim N^{-c/d}$ | $h \sim 1/N \text{ (for 2 layer networks)}$ |

Curse of dimensionality

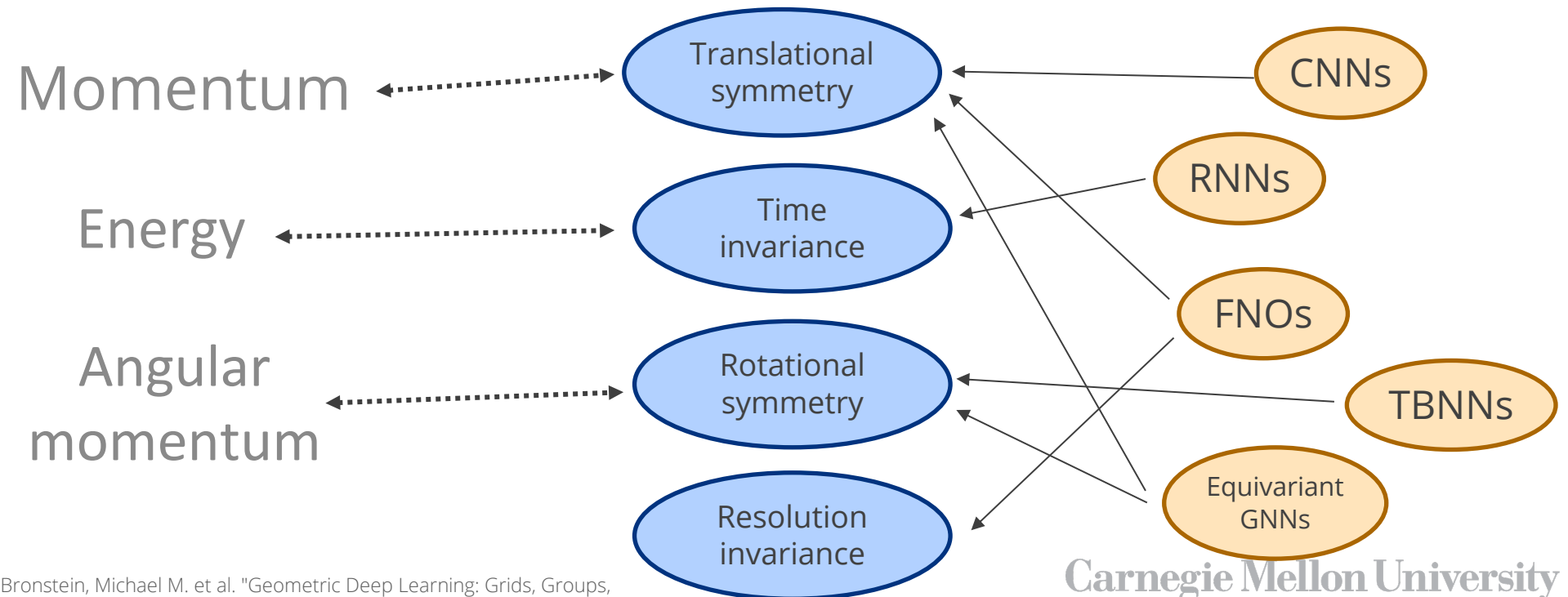
Dimension independent

Machine Learning in Physics

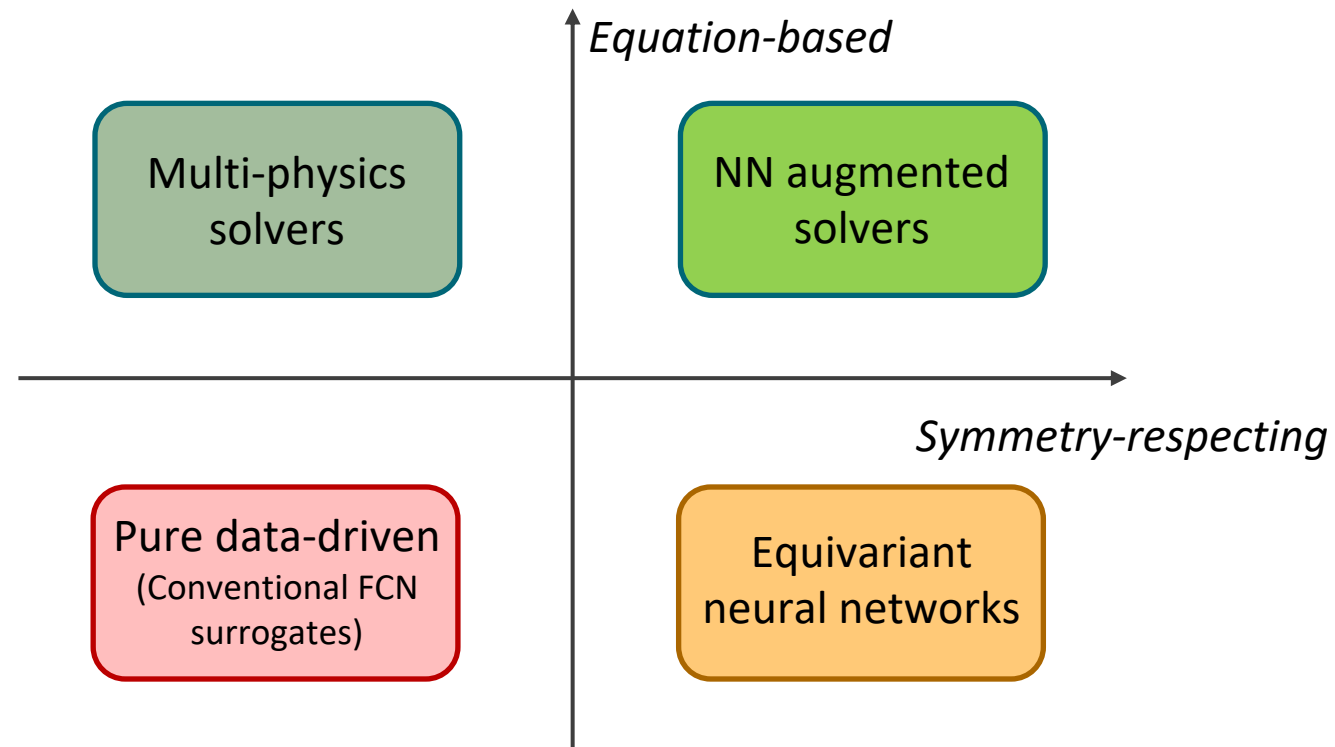


Conservation laws as embedded symmetries

Conservation laws \longleftrightarrow Symmetries (Noether's theorem)



Data-driven physics represented as symmetries and equations





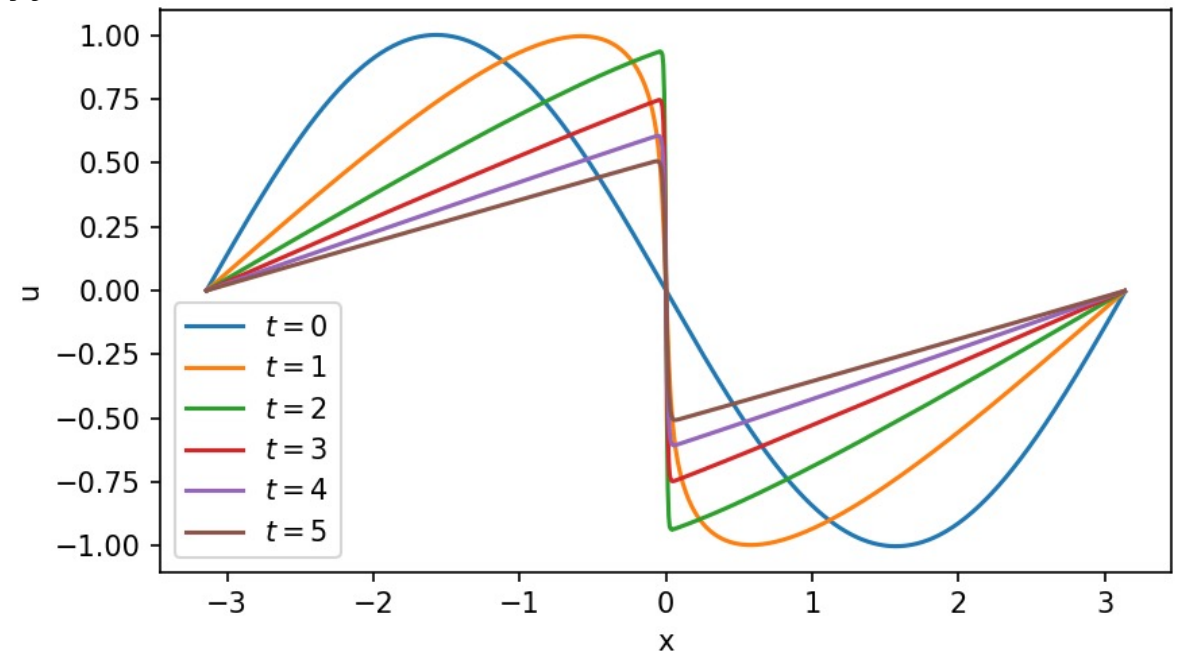
Differentiable Neural Closures

1D Viscous Burgers' Equation

$$\frac{\partial}{\partial t} u(x, t) = \nu \frac{\partial^2}{\partial x^2} u - u \frac{\partial}{\partial x} u$$

$$\bar{u}_t = \nu \bar{u}_{xx} - \bar{u} \bar{u}_x + \eta$$

$$\eta = \frac{\partial}{\partial x} \left(\nu_T \frac{\partial}{\partial x} \bar{u} \right)$$



Adding structure to the model increases interpretability

$$\eta = \cancel{f_\theta(\bar{u}; x, t)}$$

$$\dot{\bar{u}} = \nu \nabla^2 \bar{u} - \bar{u} \nabla \bar{u} + \nabla(\nu_T \nabla \bar{u})$$

$$\dot{\nu}_T = \alpha_\theta(\bar{u}_x; x, t) \cdot \nu \nabla^2 \nu_T - \beta_\theta(\bar{u}_x; x, t) \cdot \bar{u} \nabla \nu_T$$

$$\nu_T(x, 0) = \gamma_\theta(\bar{u}_0, \nu; x)$$

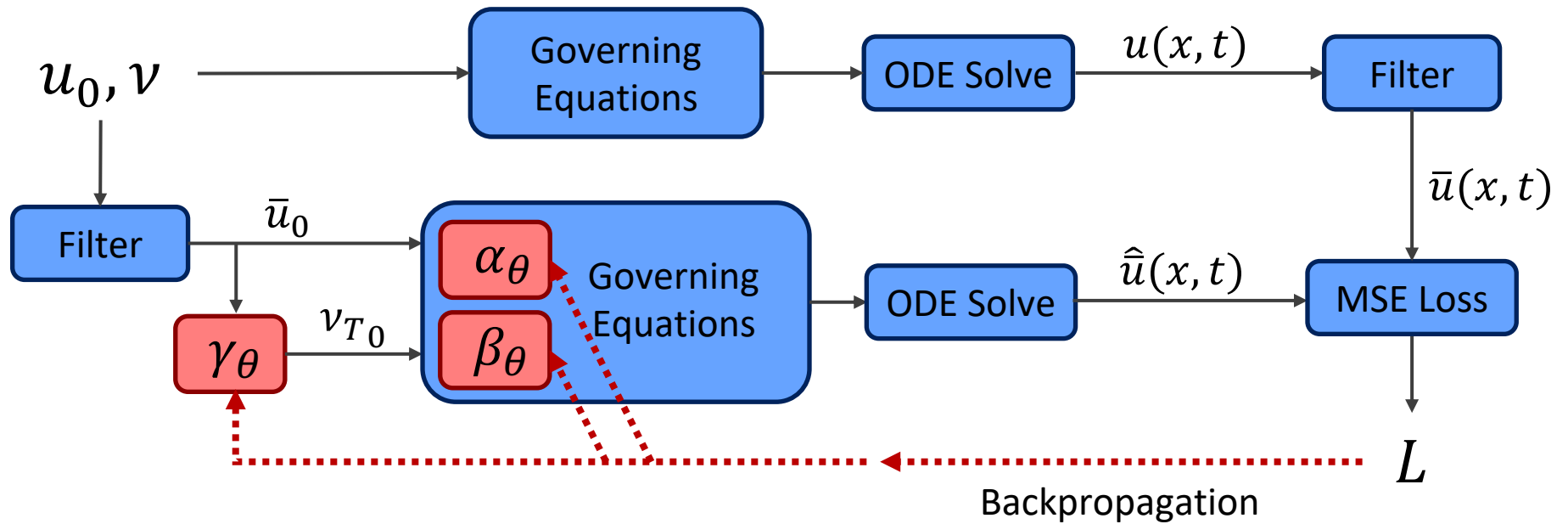
*NNs operate in Fourier space



The need for a differentiable solver

- We're learning a dynamical equation
- The simpler approach
 - Generate high-fidelity solutions
 - Filter solutions and compute closure term
 - Learn the function mapping \bar{u} to the closure term
- Want to learn a-posteriori velocity → evolve coupled system together during training

The need for a differentiable solver

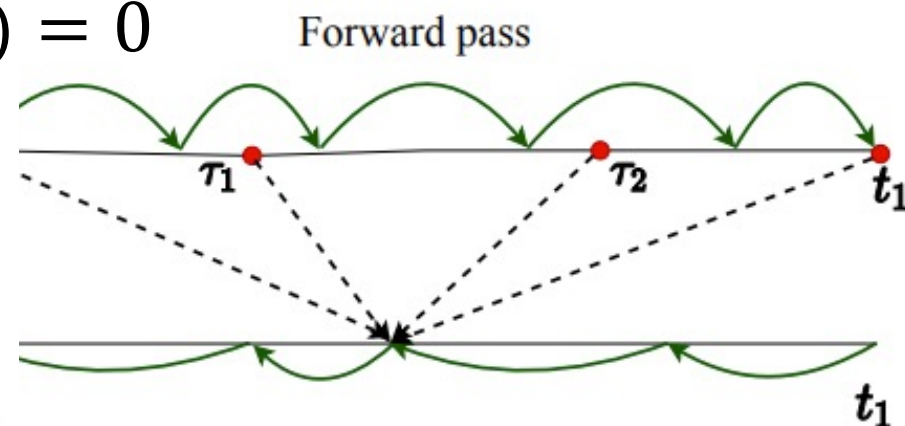


Adjoint method

$$\dot{u} = f(u, \theta) \quad L(u) = \int_0^T l(u, t) dt$$

$$\lambda(t) = \int_T^t -\lambda^T f_u + l_u dt \quad \lambda(T) = 0$$

$$\frac{dL}{d\theta} = \int_0^T -\lambda^T f_\theta dt$$

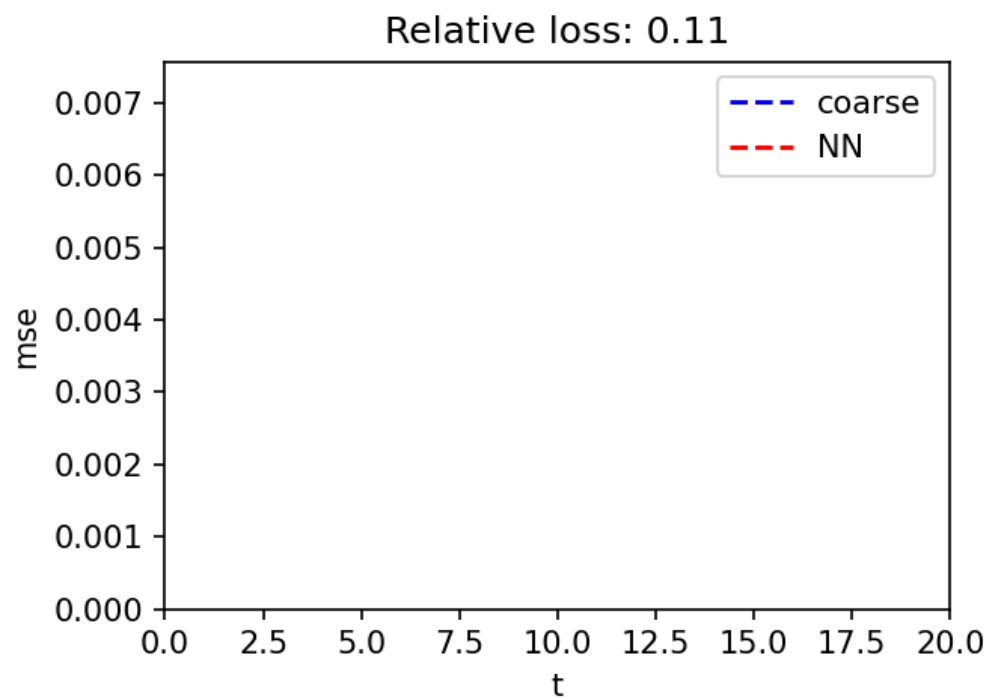
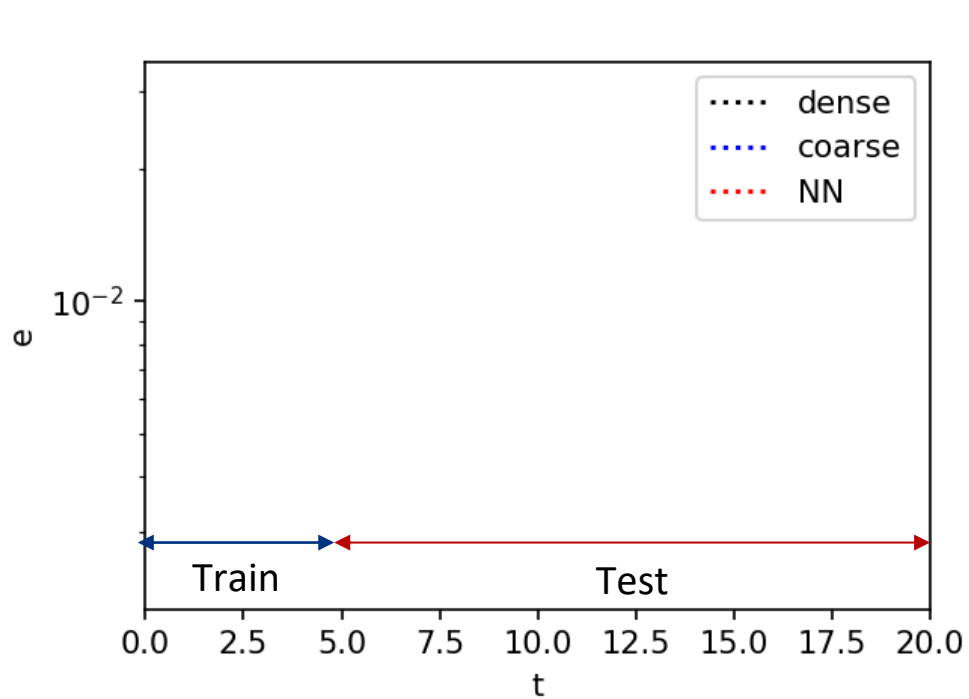
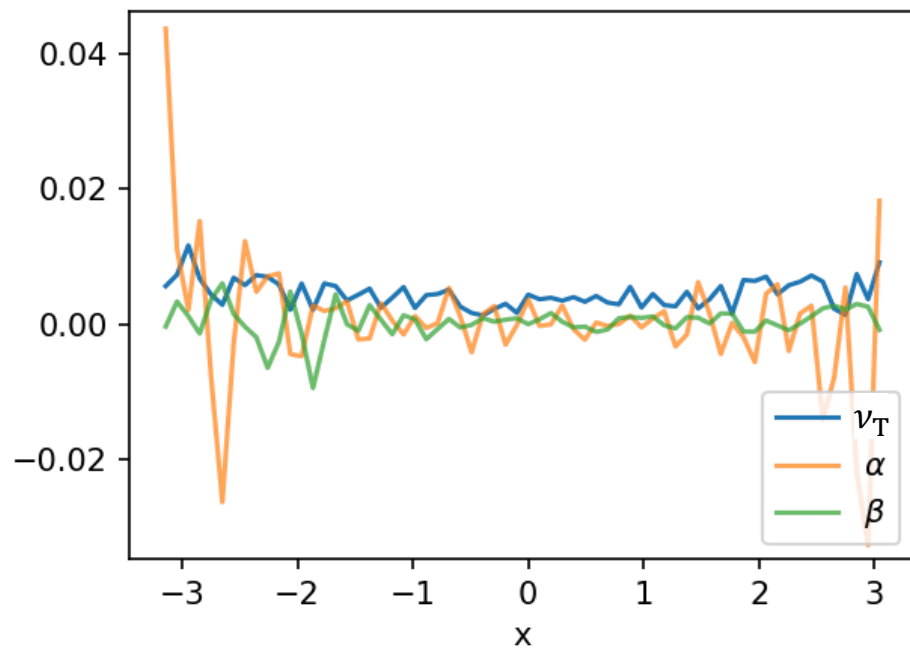
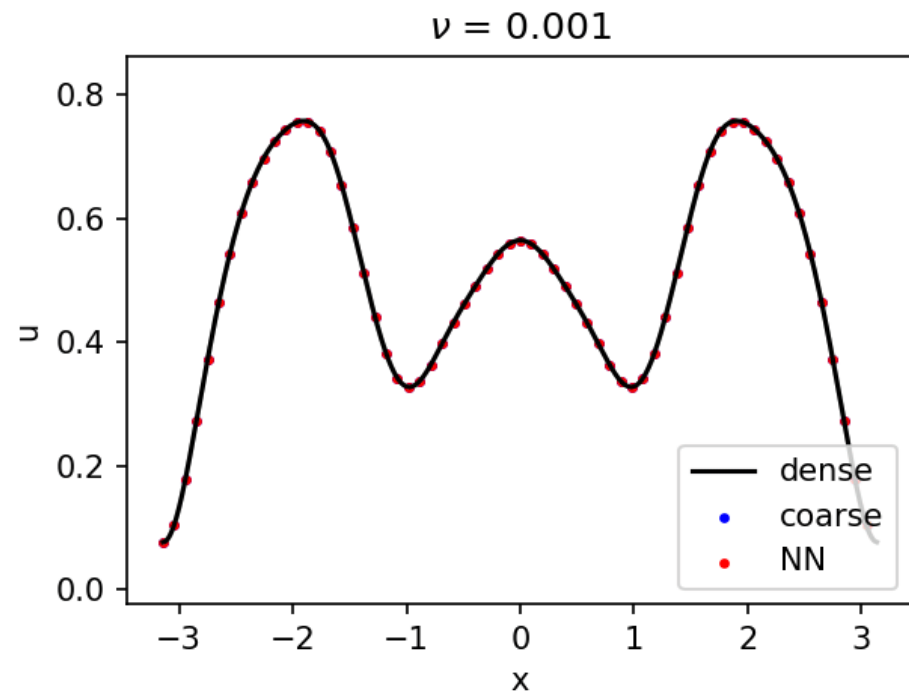


Learning methodology

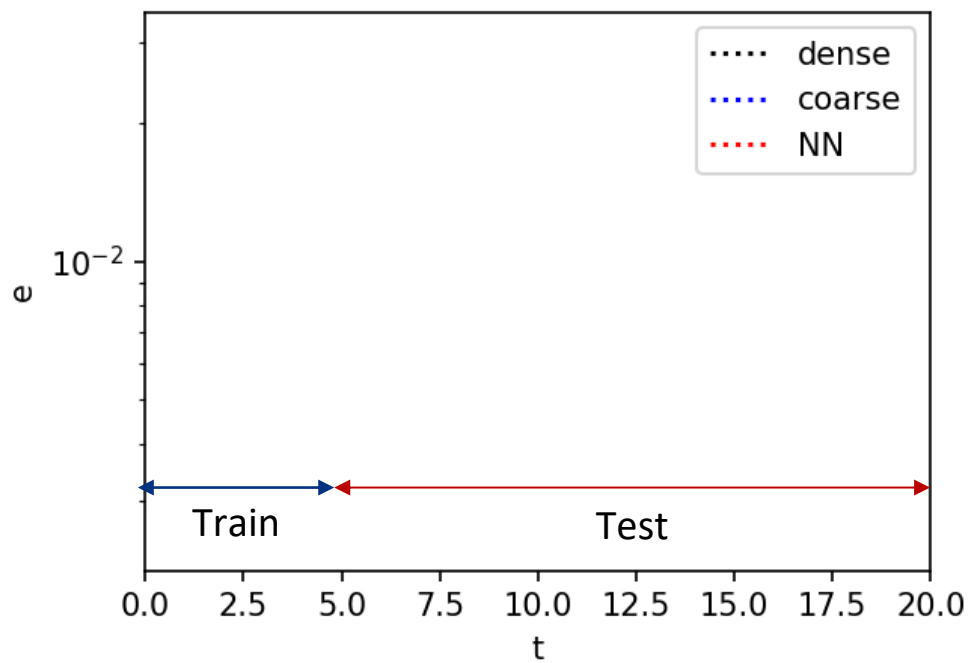
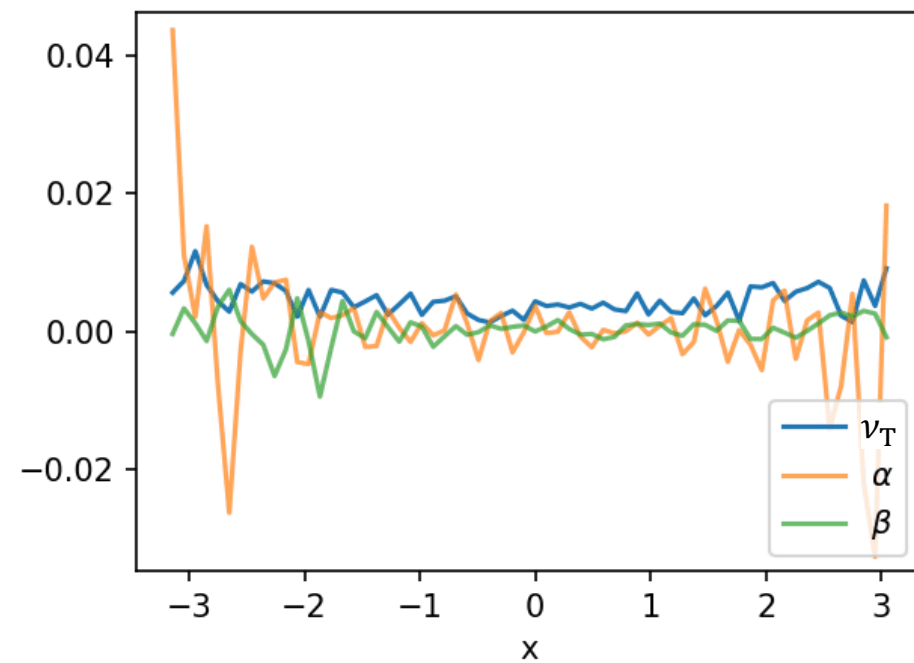
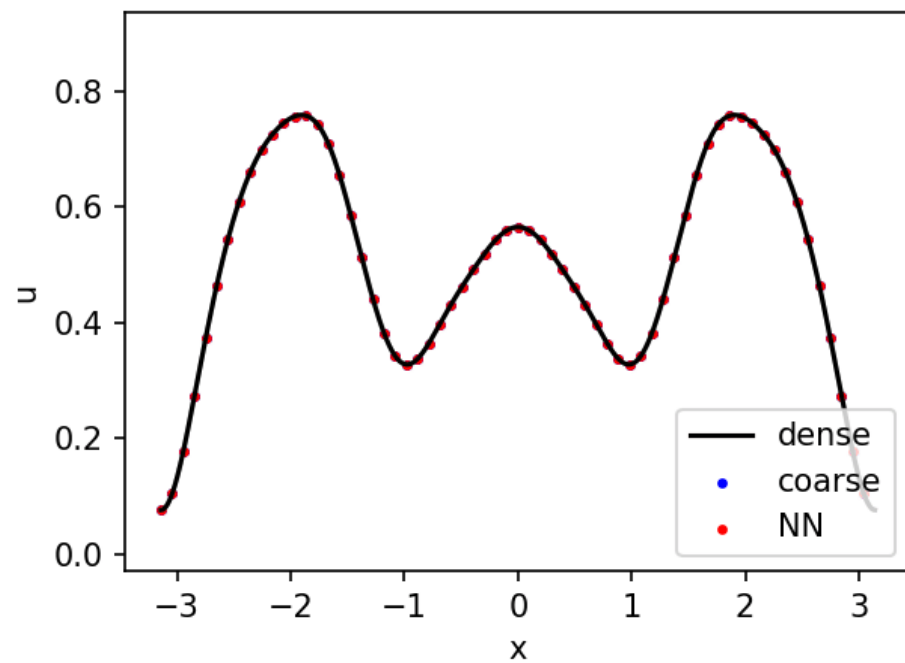
- Desire to learn a one-equation closure transport model for Burgers' equation
 - Neural network approximates ν_T IC and convection/diffusion coefficients of the transport equation in Fourier space
- Data generated on fully-resolving dense grid
- ODE system integrated to produce approximate velocity profiles
- Loss is backpropagated via adjoint method to compute NN parameter gradients

Results

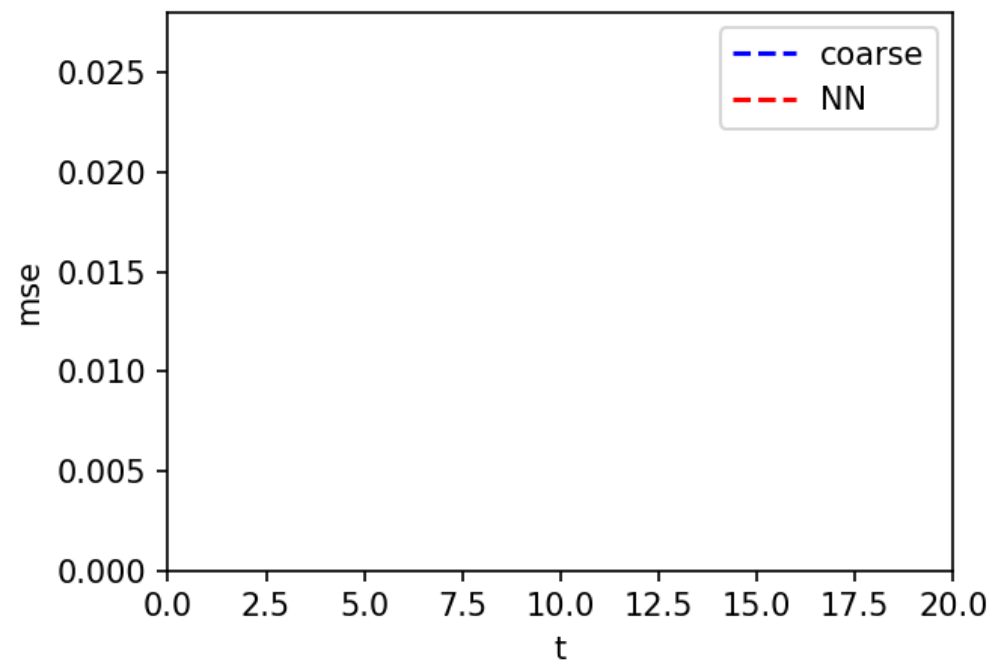
- Model training:
 - Random initial condition
 - $t = 0$ to 5
 - $\nu = 5 \times 10^{-2}$ to 5×10^{-4}

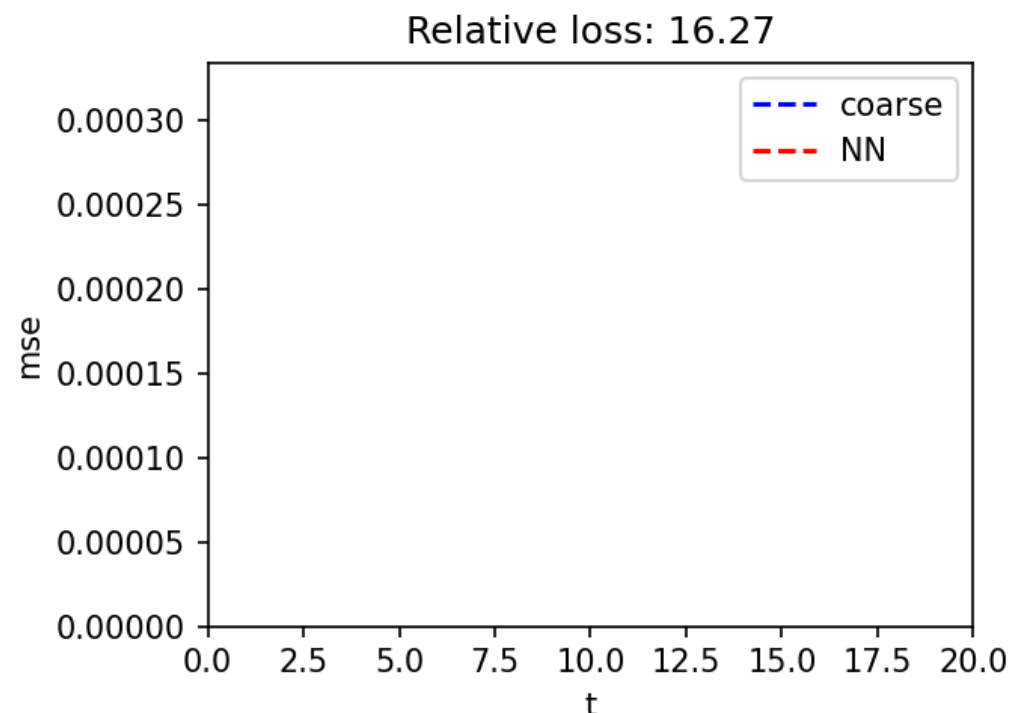
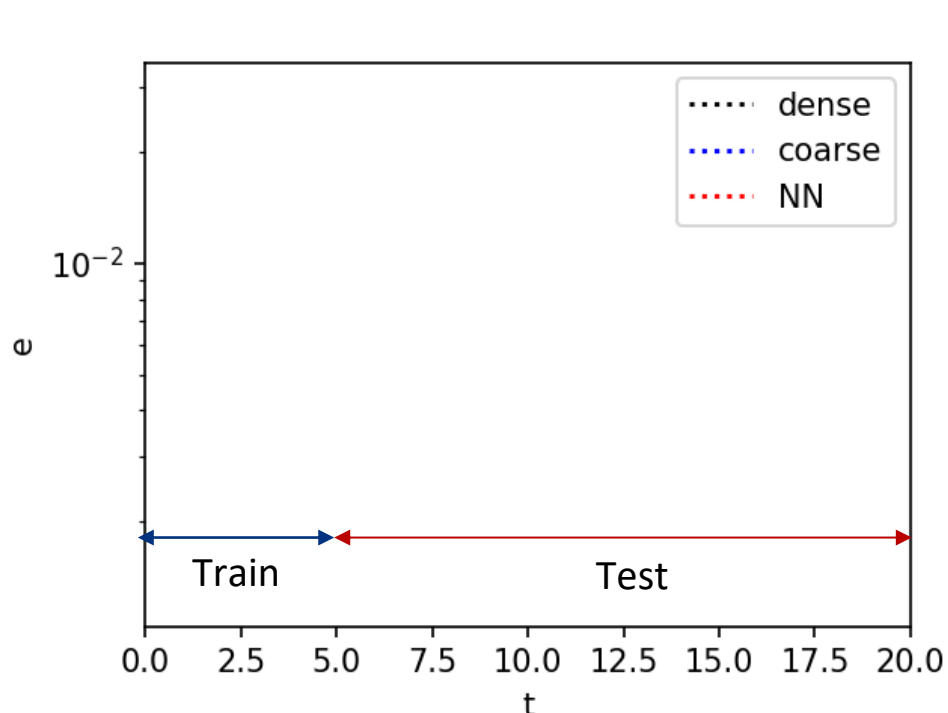
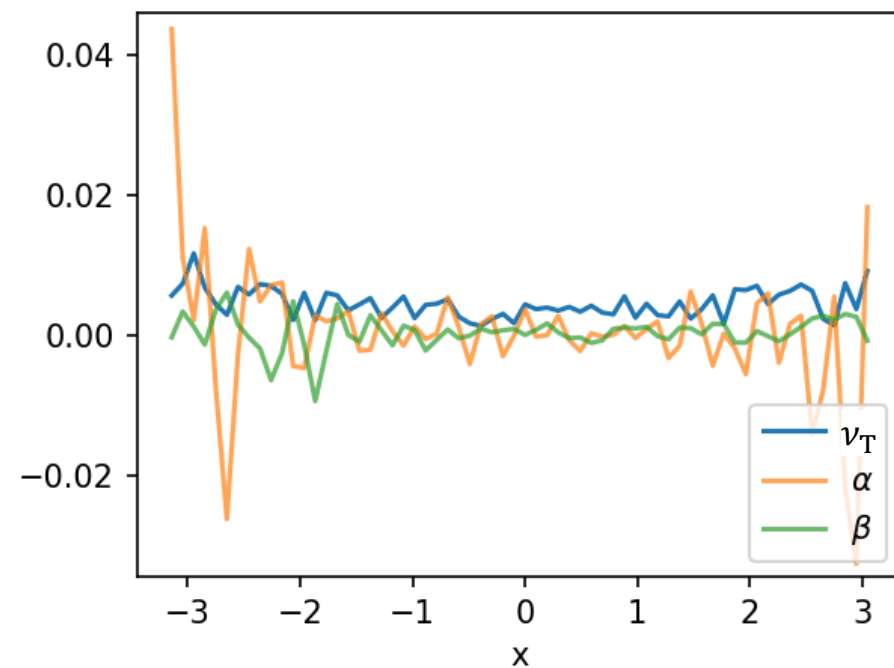
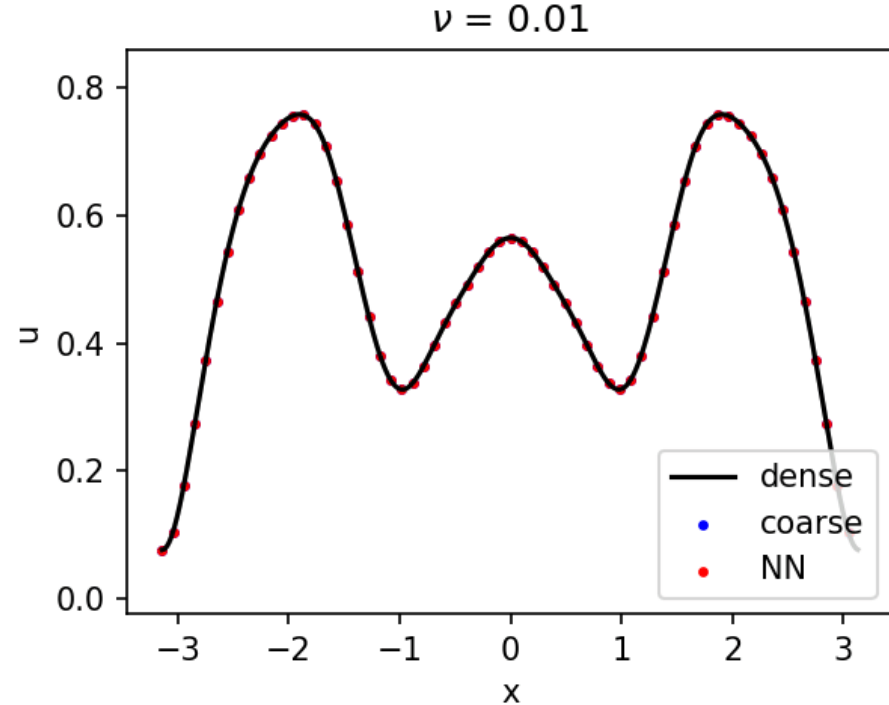


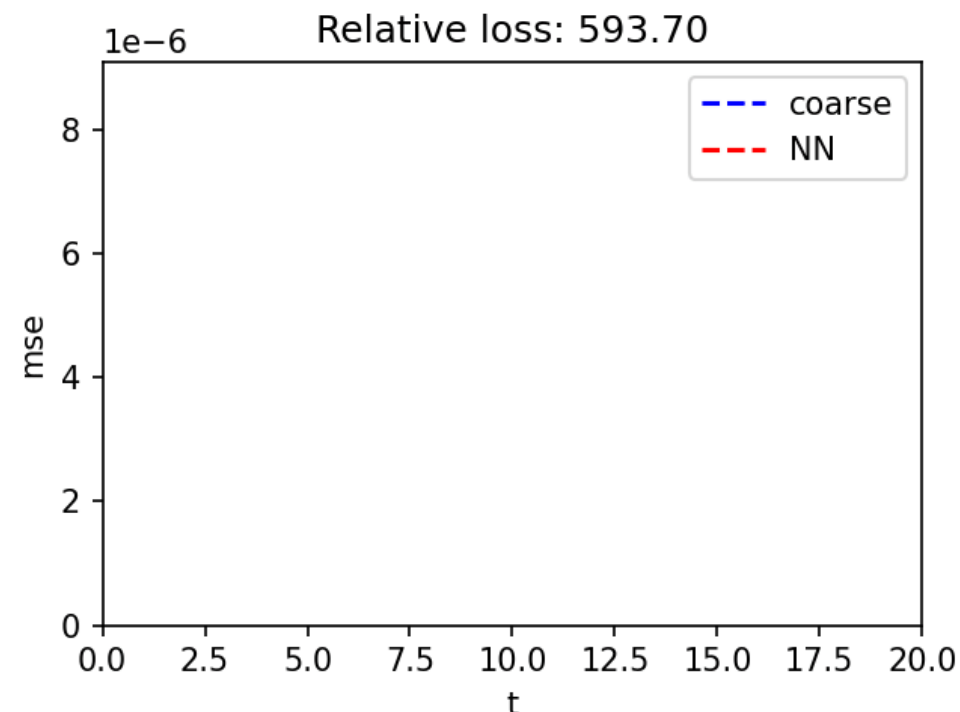
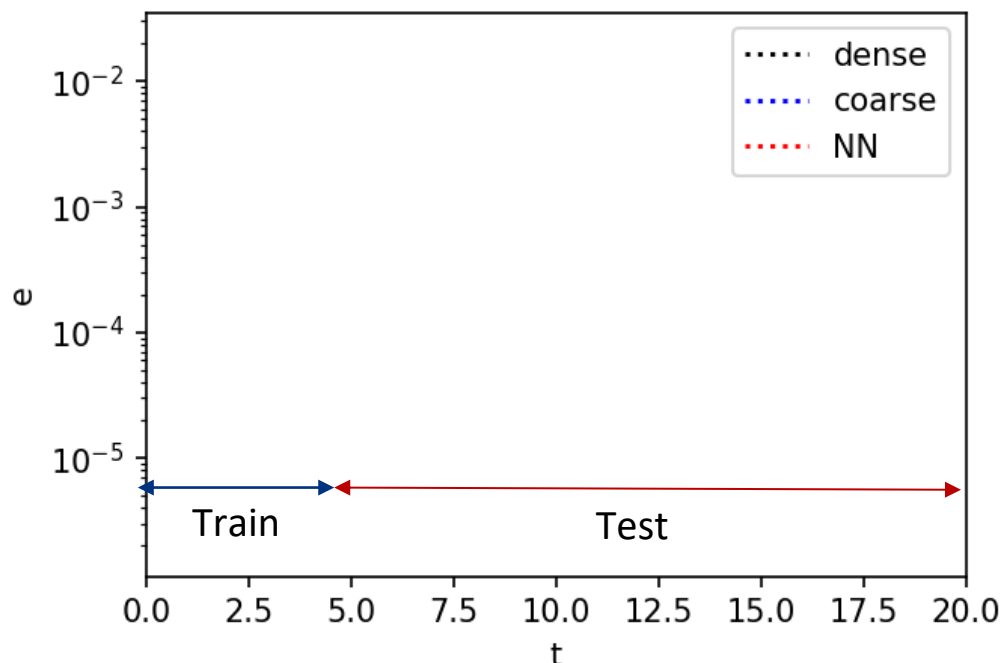
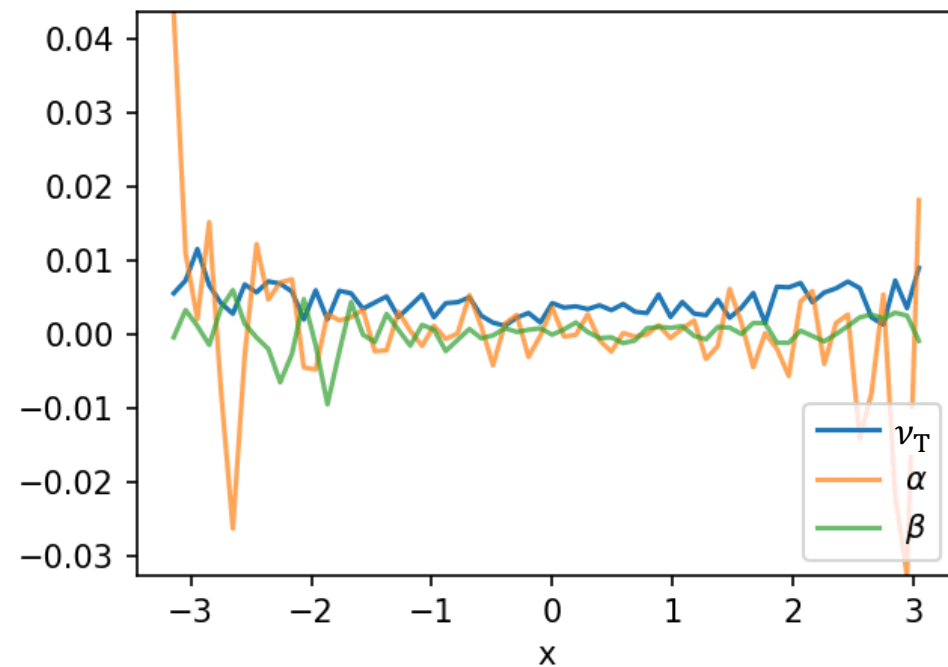
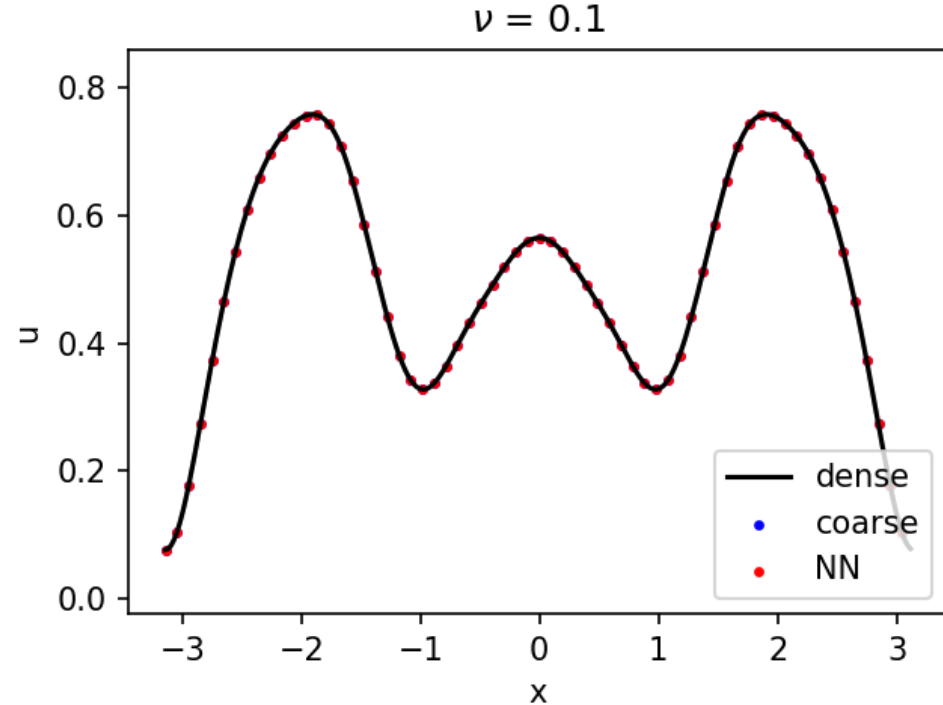
$\nu = 0.0001$



Relative loss: 0.03



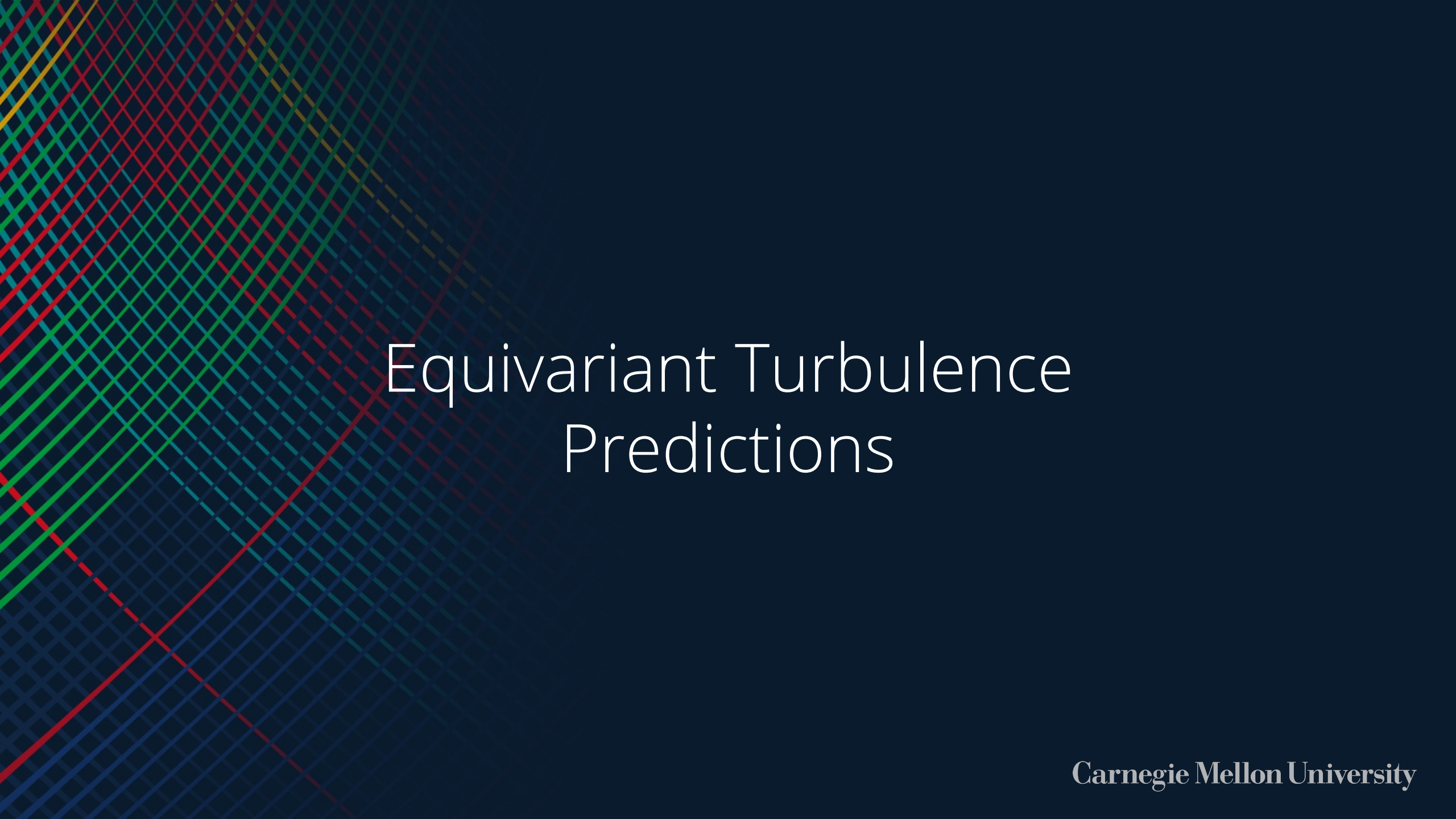






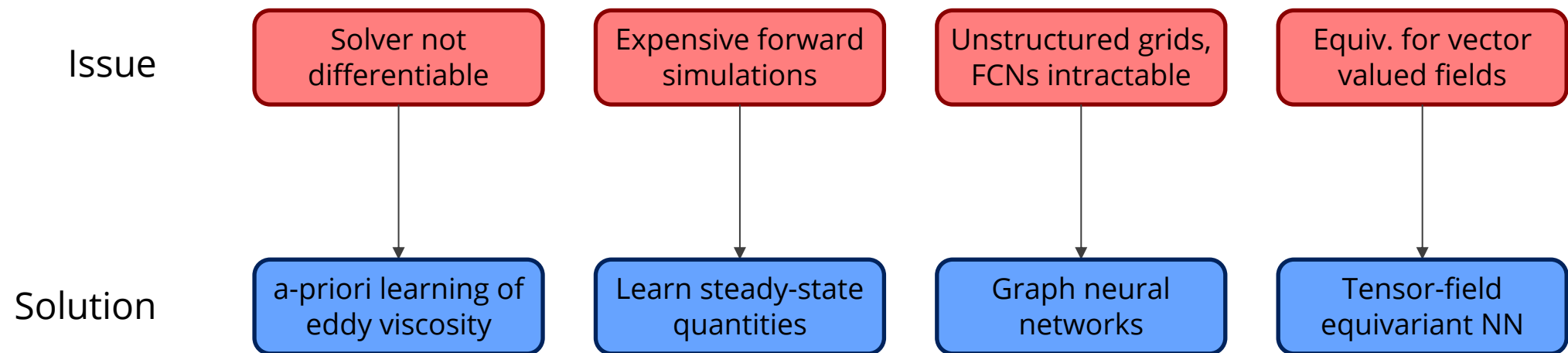
Discussion

- 1-eqn learned transport model for eddy viscosity effective for sub-grid modeling of Burgers' equation
- Interpretable model → improve physical understanding
 - Stationary eddy viscosity for time-varying system
- Model fails at high viscosities → can we learn to “switch off?”
- Scaling to higher dimensions, Navier-Stokes

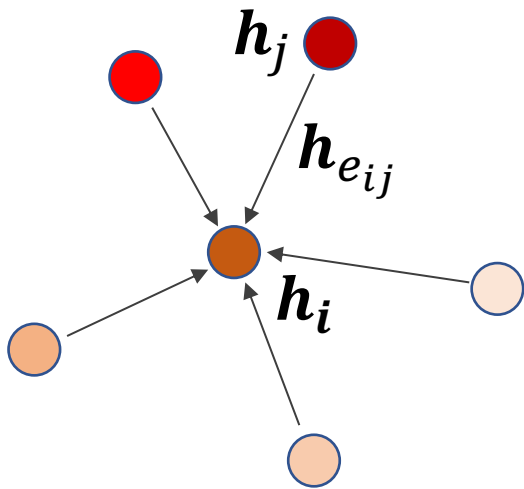


Equivariant Turbulence Predictions

Scaling up introduces challenges



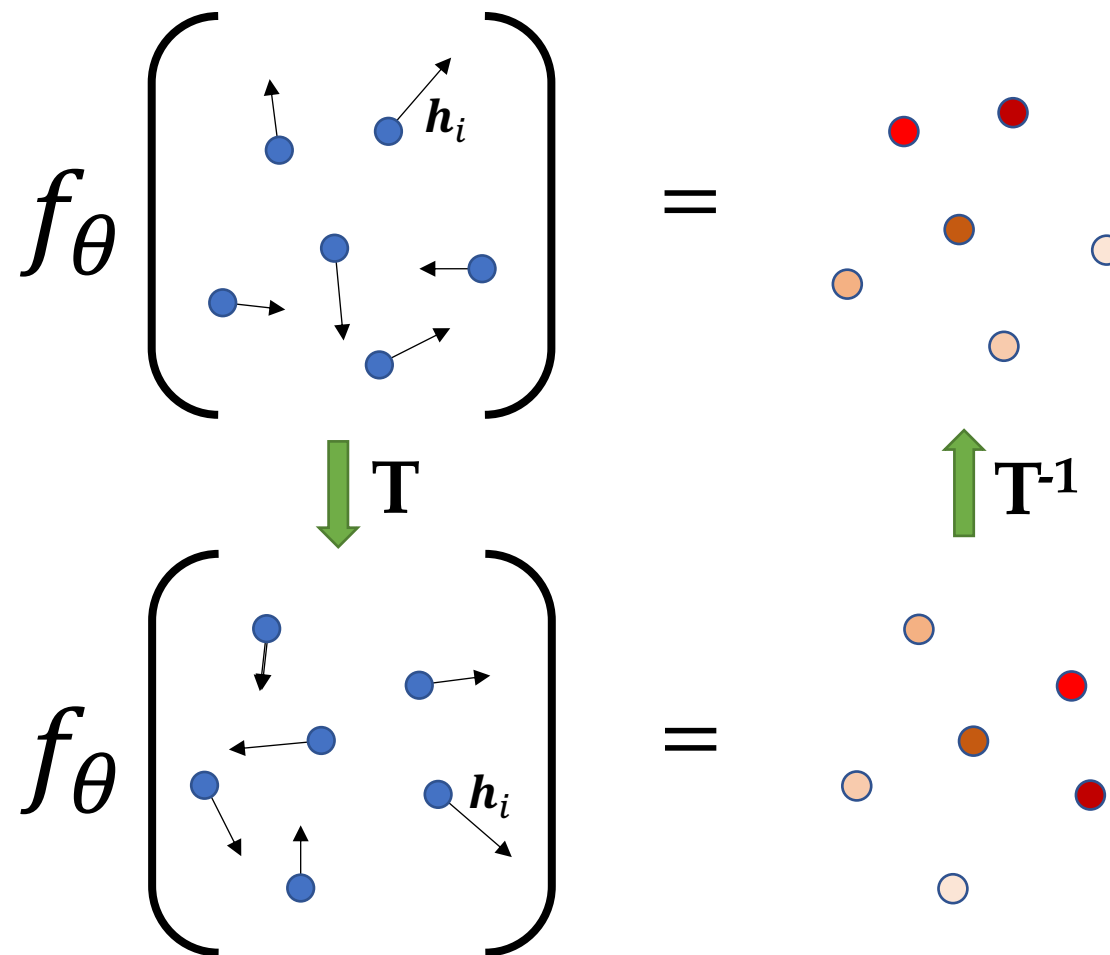
Graph Message-Passing Neural Networks



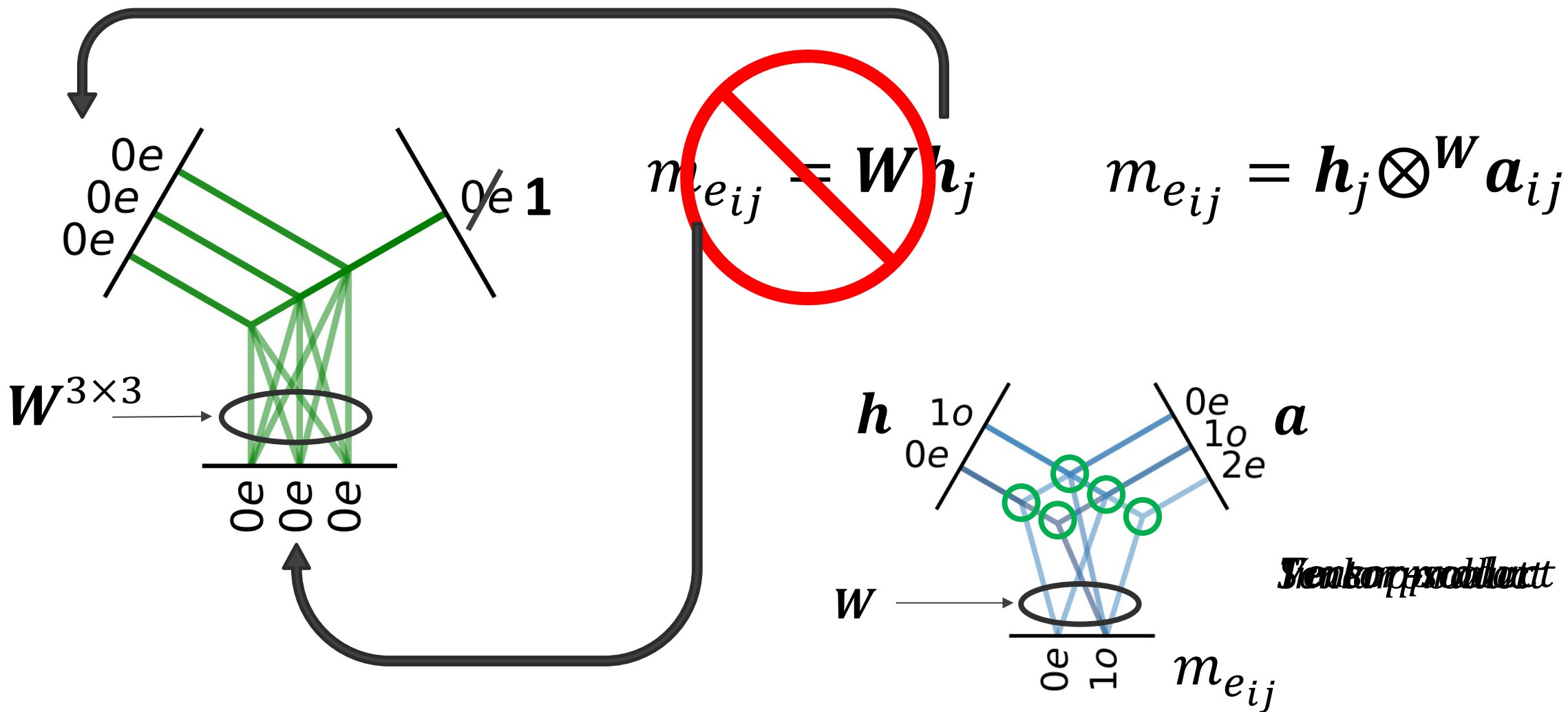
$$\mathbf{h}_{e_{ij}}^{n+1} = f_{\theta}(\mathbf{h}_{e_{ij}}^n, \mathbf{h}_i^n, \mathbf{h}_j^n)$$

$$\mathbf{h}_i^{n+1} = g_{\theta}\left(\sum_{e \in \mathcal{N}} \mathbf{h}_{e_{ij}}^{n+1}, \mathbf{h}_i^n\right)$$

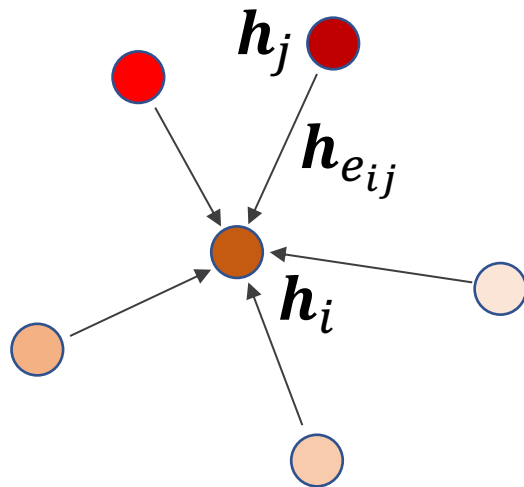
Equivariance



Tensor Products



Equivariant GNNs

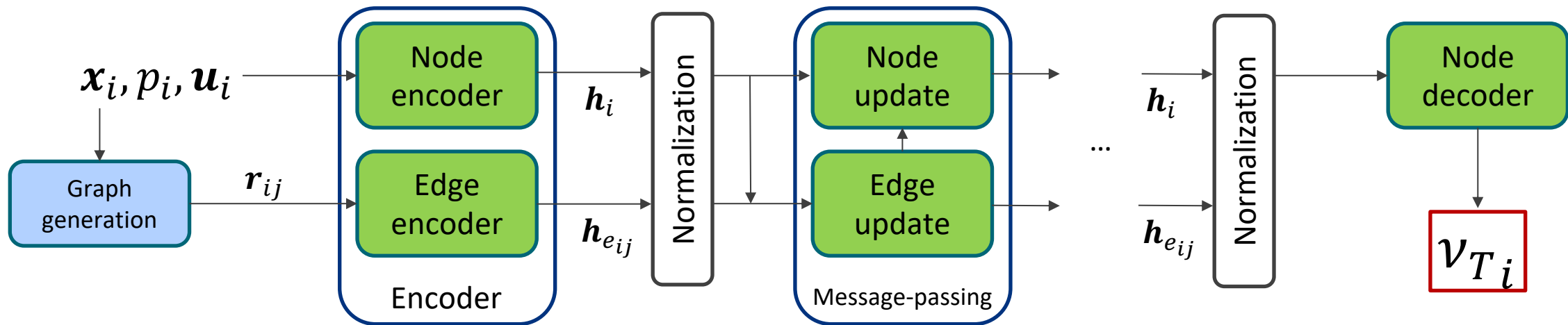


$$\mathbf{h}_{e_{ij}}^{n+1} = f_{\theta}(\mathbf{h}_{e_{ij}}^n, \mathbf{h}_i^n, \mathbf{h}_j^n)$$

$$f_{\theta} = [\mathbf{h}_{e_{ij}}, \mathbf{h}_i, \mathbf{h}_j] \otimes W(r_{ij}) Y_{sh}(\mathbf{r}_{ij})$$

$$W(r_{ij}) = MLP(\|\mathbf{r}_{ij}\|)$$

Architecture

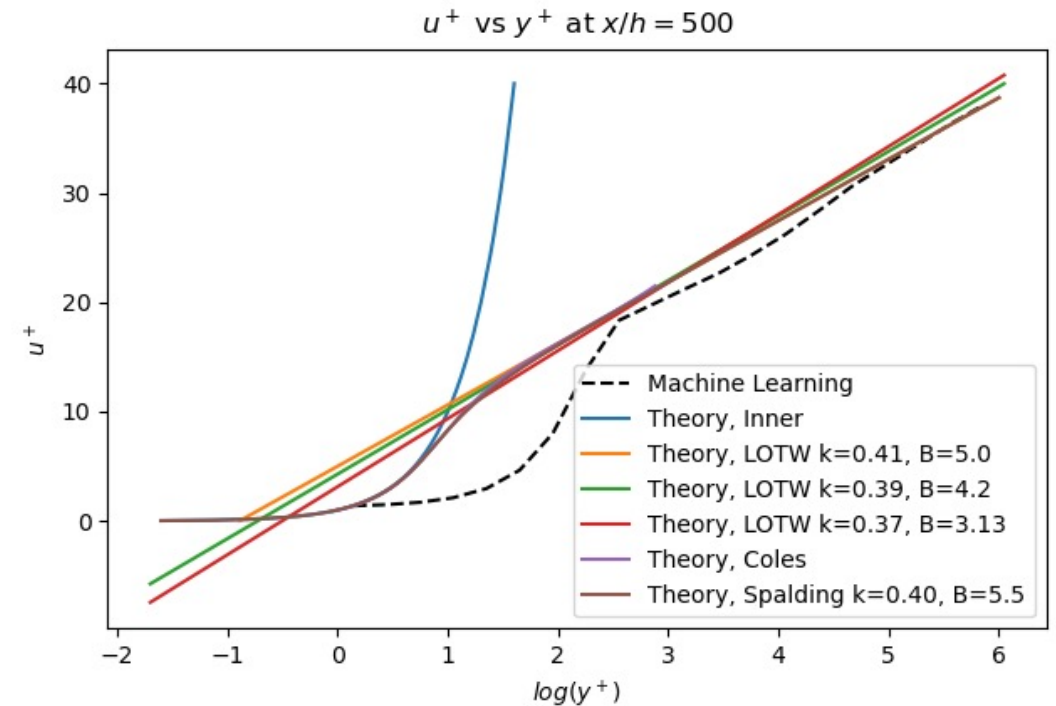
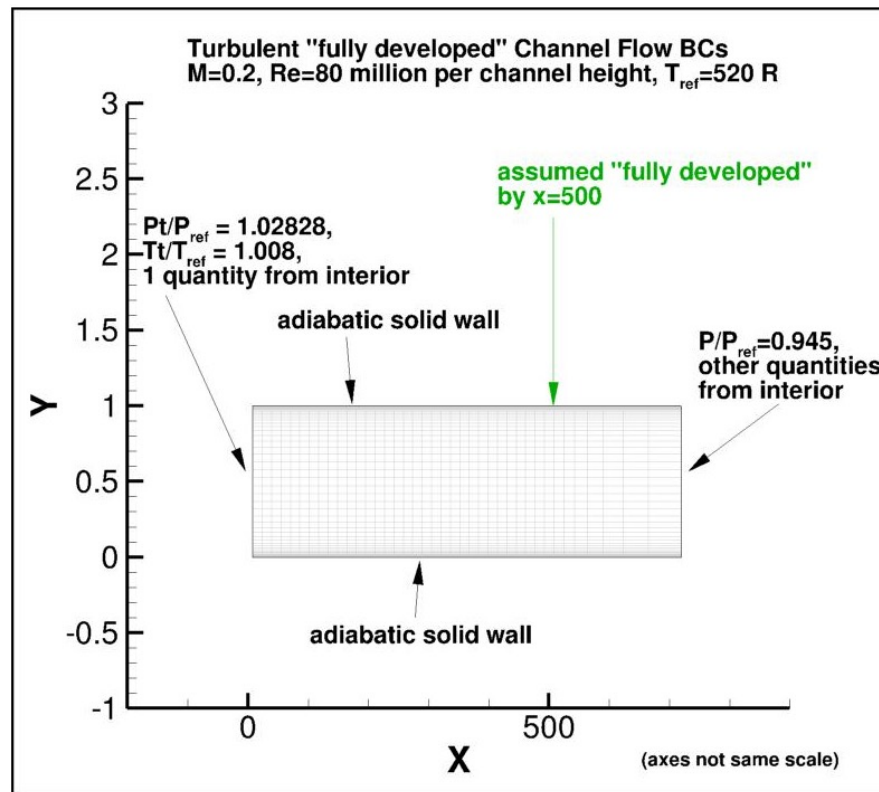




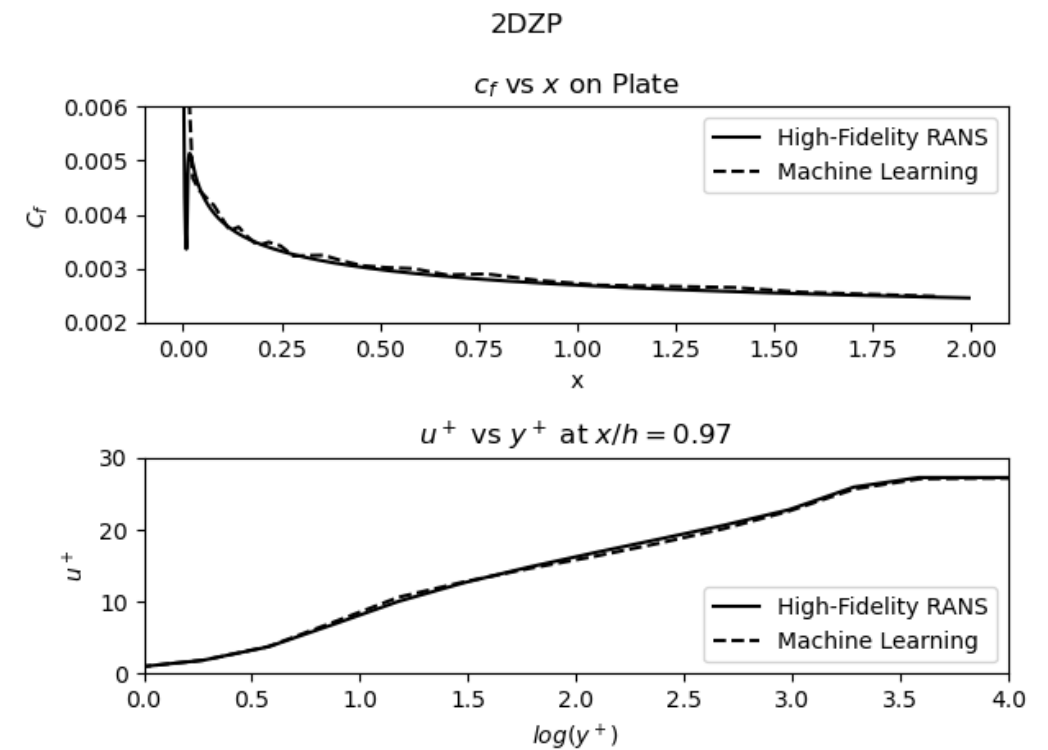
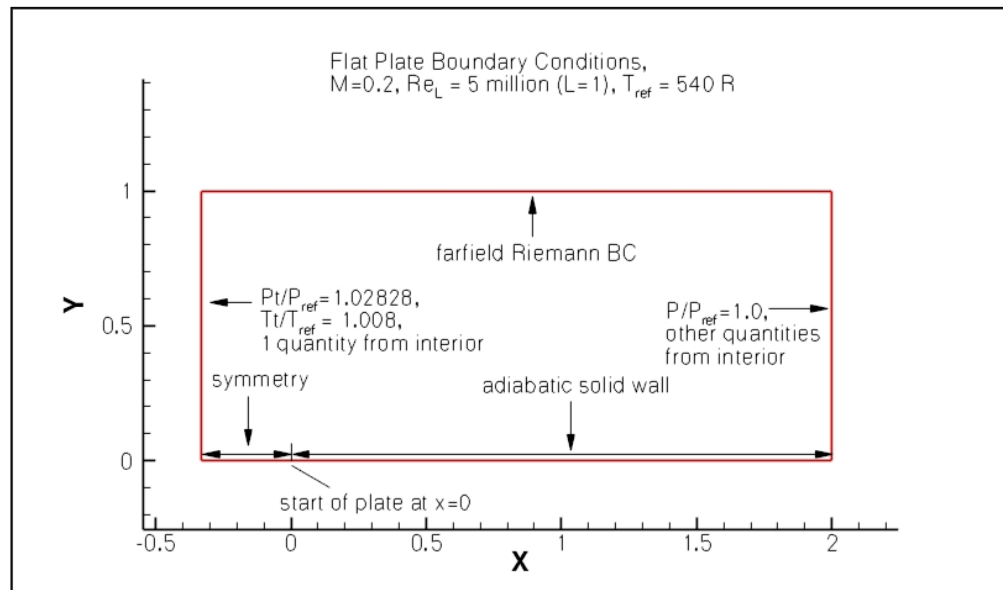
Learning Methodology

- Desire to learn steady-state eddy viscosity from mesh point cloud and initial pressure/velocity fields
 - Neural network approximates ν_T using equivariant graph network
- Data generated using Spalart-Allmaras turbulence model
- Approximate ν_T field used in incompressible solver
 - Only pressure/velocity equations solved
- A-posteriori analysis of solution fields

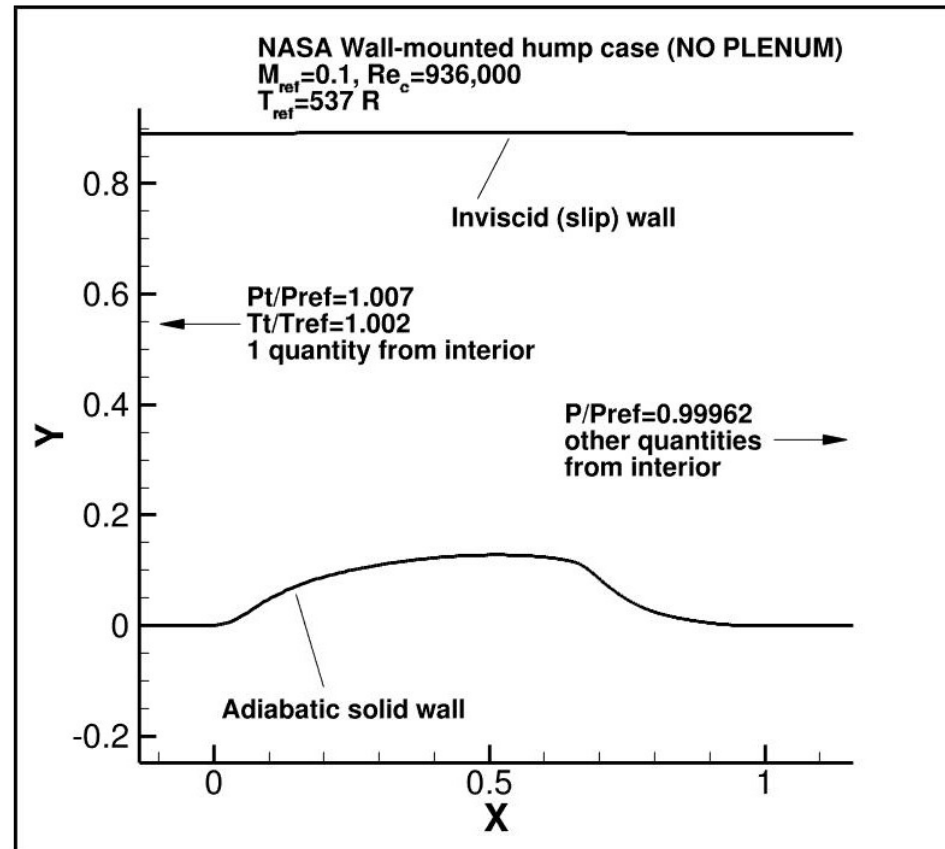
2D Fully Developed Channel Flow ($Re_h=80m$)



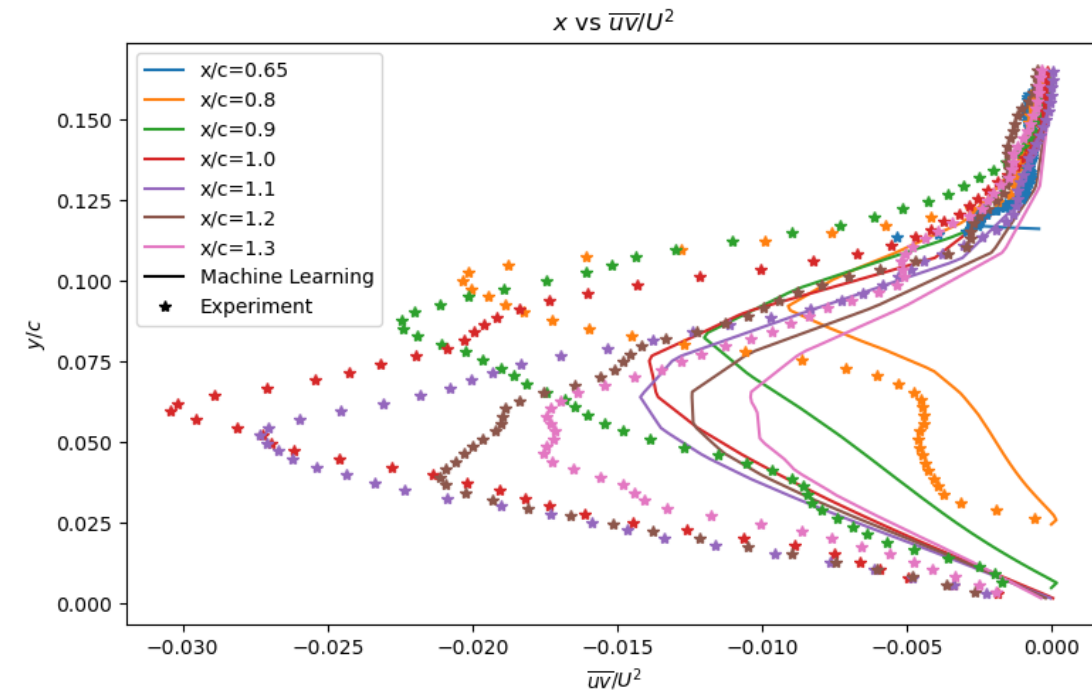
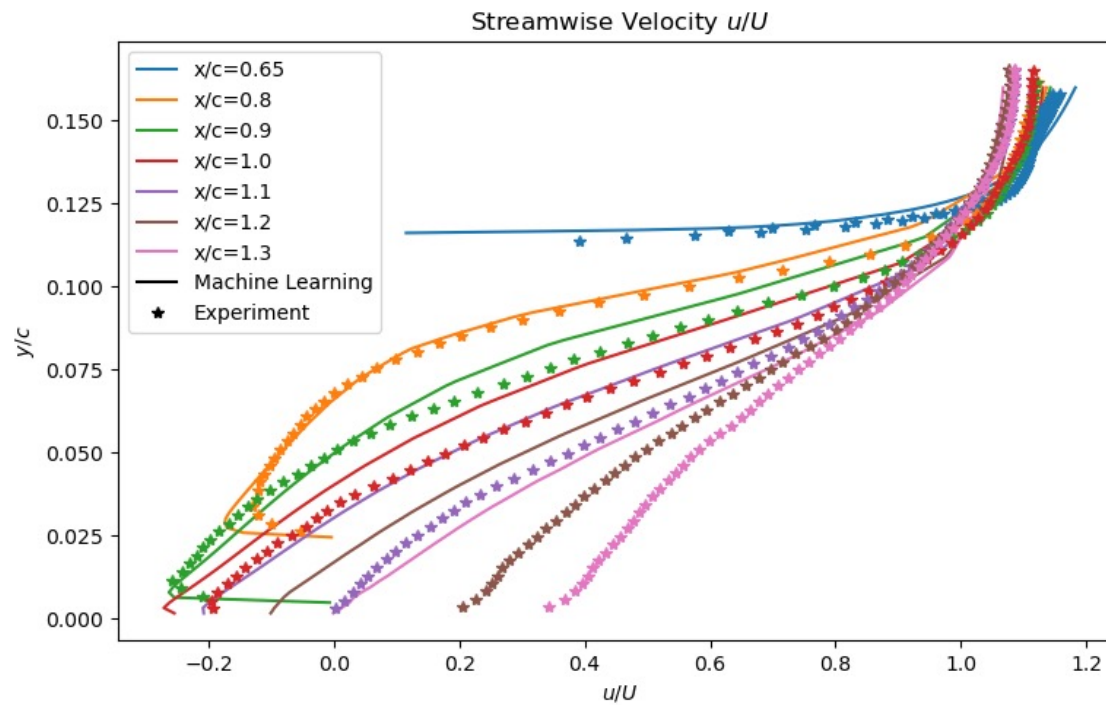
2D Zero Pressure Gradient Flat Plate ($Re_x=5m$)



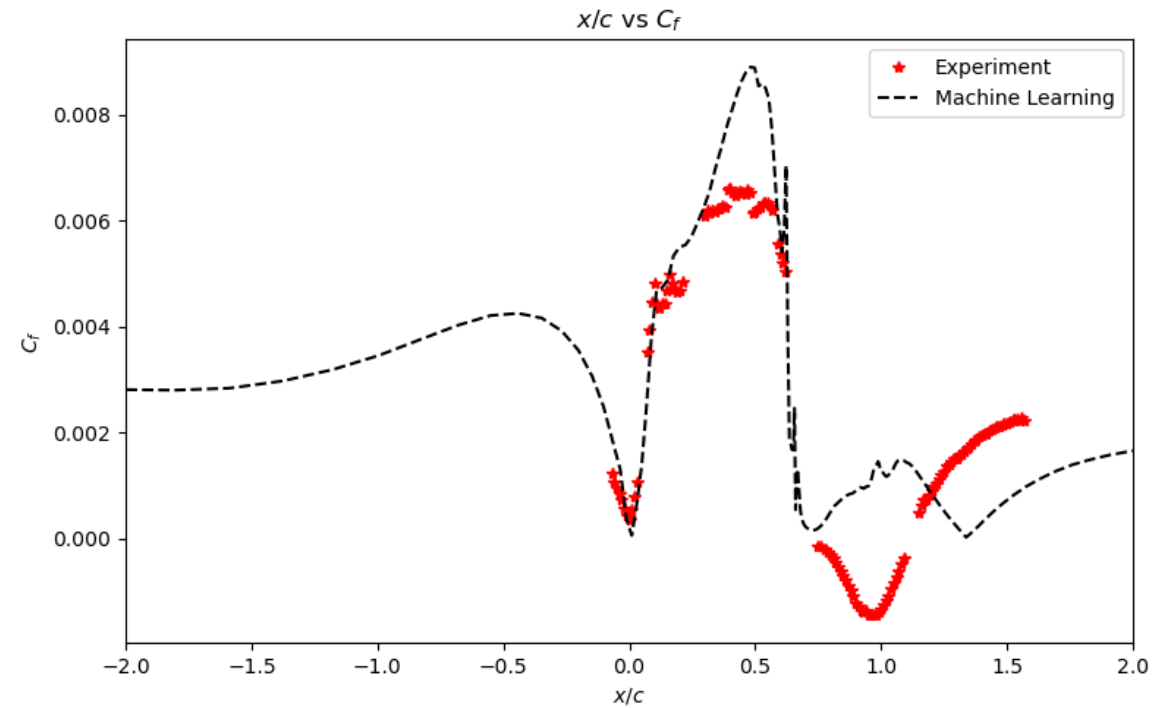
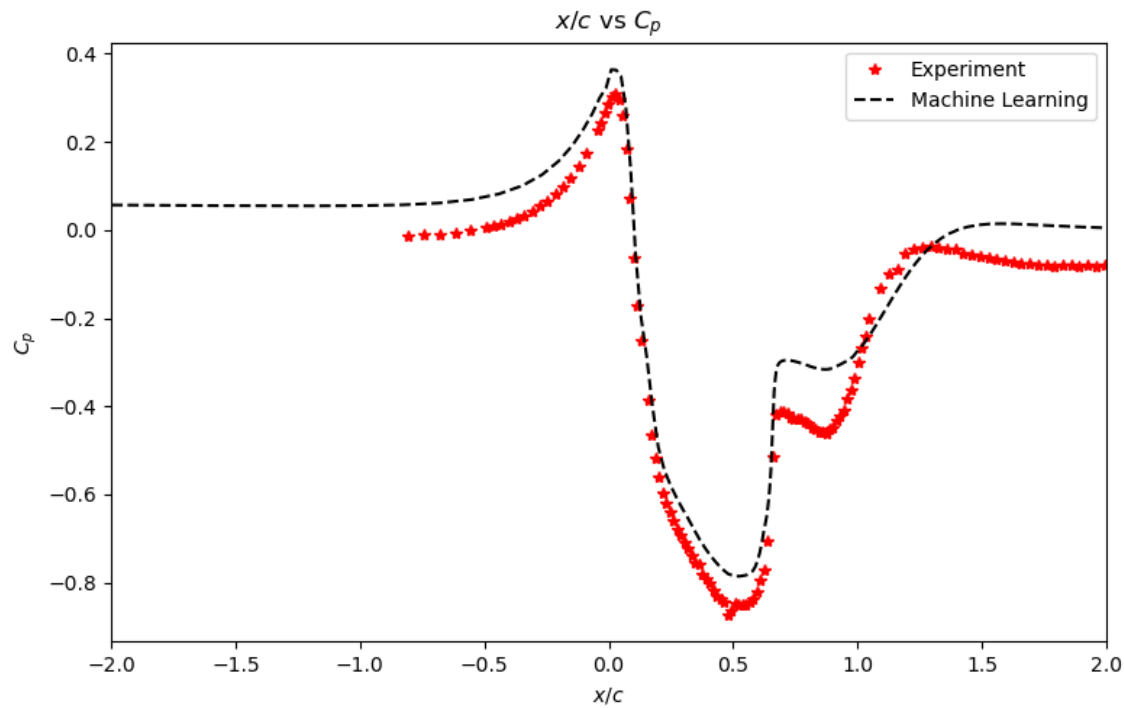
2D Wall Mounted Hump $Re_c=936k$



2D Wall Mounted Hump $Re_c=936k$



2D Wall Mounted Hump $Re_c=936k$





Conclusions and future directions

- Differentiable physics → more interpretable data-driven methods
- Symmetry-respecting architectures as best candidates for learning in the low-data regime
- Can we make strides towards fully differentiable N-S solvers?
- Can we leverage the advantages of DNN scaling and equivariant architectures to learn more robust turbulence models?

Acknowledgements

