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- Resources menu
- Community of Practice webinars

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Connecting and sharing information and lessons learned to:

- Increase the impact of suborbital flight tests
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- Let us know session topics you would like to see covered.

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TODAY'S SPEAKERS



Mark Hilburger, Ph.D.
Principal Technologist,
NASA Space Technology Mission Directorate



Laki Vlachos
Senior Payload Mission Manager,
Blue Origin



Franklin Robinson
Thermal Engineer and Technologist,
NASA's Goddard Space Flight Center



Aaron Olson, Ph.D.
ISRU & Seals Dust Mitigation Lead, Electrostatics & Surface Physics Laboratory,
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Program Manager,
Honeybee Robotics, a Blue Origin company



Nicholas Naclerio, Ph.D.
Robotics Engineer,
Honeybee Robotics, a Blue Origin company

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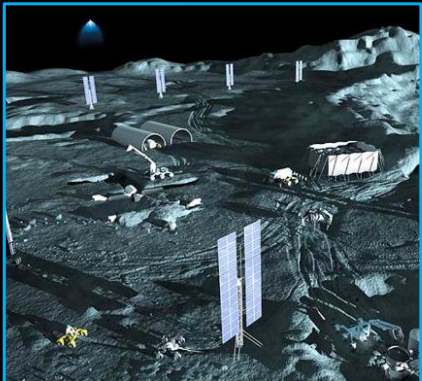


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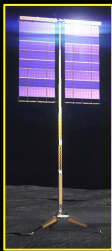
Moon to Mars Lunar Infrastructure Objectives

- **Foundational capabilities required to support continuous presence and exploration of the Moon and Mars**
 - Utilities: Power, Communications, Navigation (LI-1 – LI-3)
 - Construction, precision landing, surface transportation (LI-4 – LI-6)
 - ISRU: Commodities production & storage, sustainable construction (LI-7, LI-8)

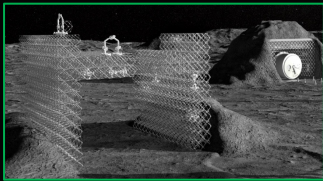
Envisioned Future Infrastructure



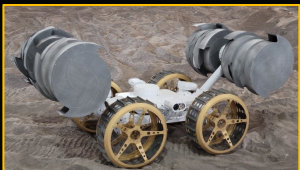
Power, Communications




Construction



Mining Systems & ISRU

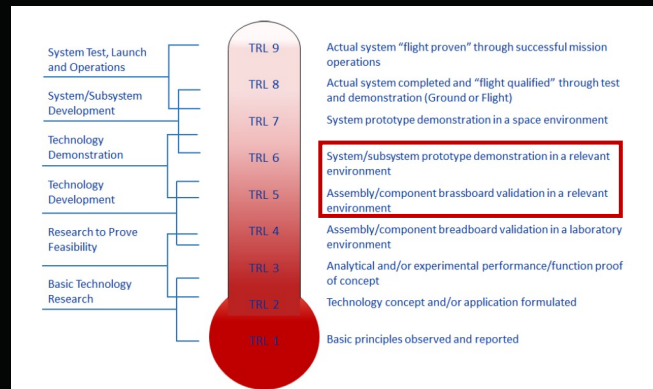




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Technology Readiness Levels and the Importance of Flight Testing

- **“Technology Readiness Level” or TRL is a scale for measuring the maturity of a technology**
 - Early basic research and concept validation happening primarily in a laboratory environment (TRL1 – TRL4)
 - Testing in a relevant environment happening in **TRL5 - TRL6** phases of development and is critical for technology infusion into future flight missions
- **Relevant environments testing includes thermal, dust & regolith, radiation, lighting, gravity**
 - 1/6g flights are a low-cost high-payoff test opportunities to simulate gravity conditions we can’t achieve on the ground. Example, regolith flow and interaction with hardware



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ISRU Pilot Excavator - TRL5 Testing Teaser Video

- Test as many of the components and systems as we can in relevant environments prior to flight demos and missions including demo mission ConOps

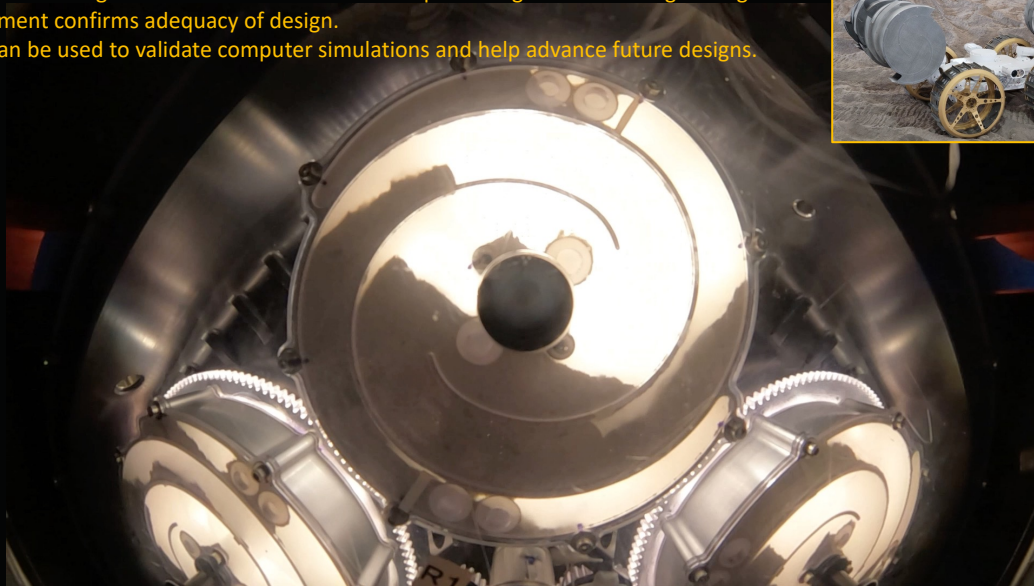


<https://www.nasa.gov/gallery/isru-pilot-excavator/>

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ISRU Pilot Excavator Bucket Drum – 1/6g Regolith Flow Experiment

- Differences in regolith flow were observed as compared to ground-based 1g testing
- Experiment confirms adequacy of design.
- Data can be used to validate computer simulations and help advance future designs.



<https://www.nasa.gov/gallery/isru-pilot-excavator/>

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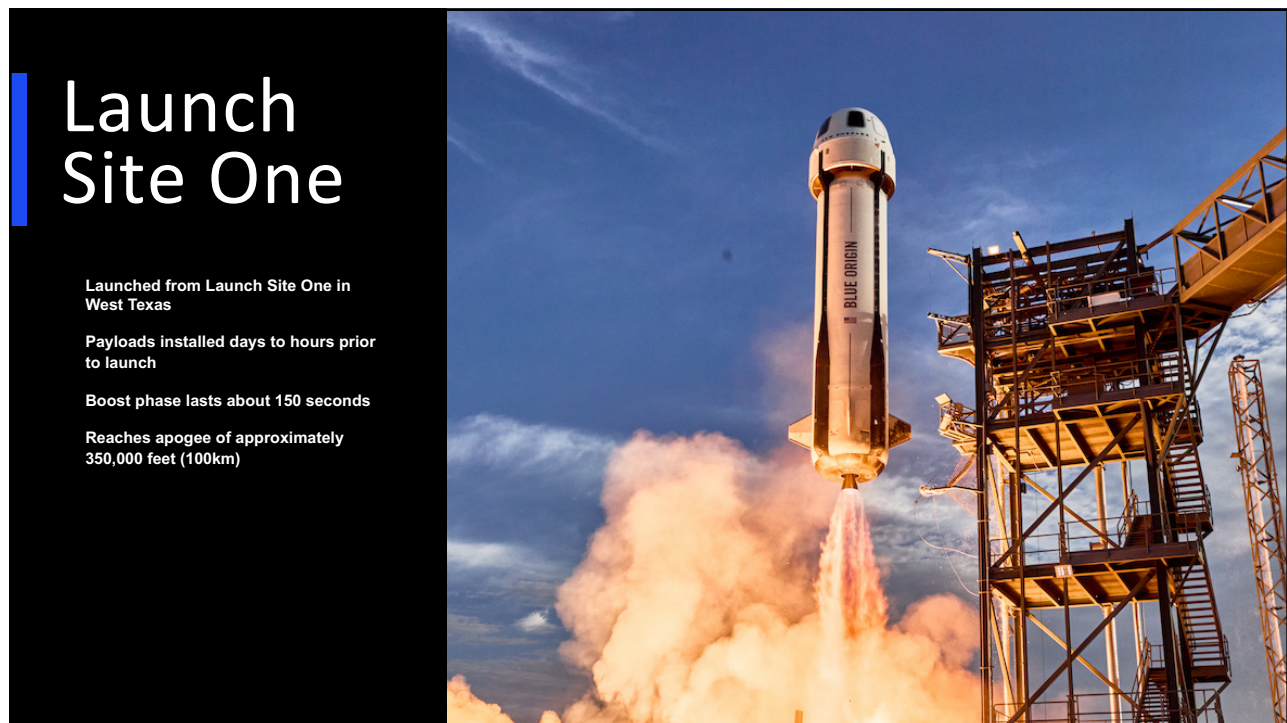
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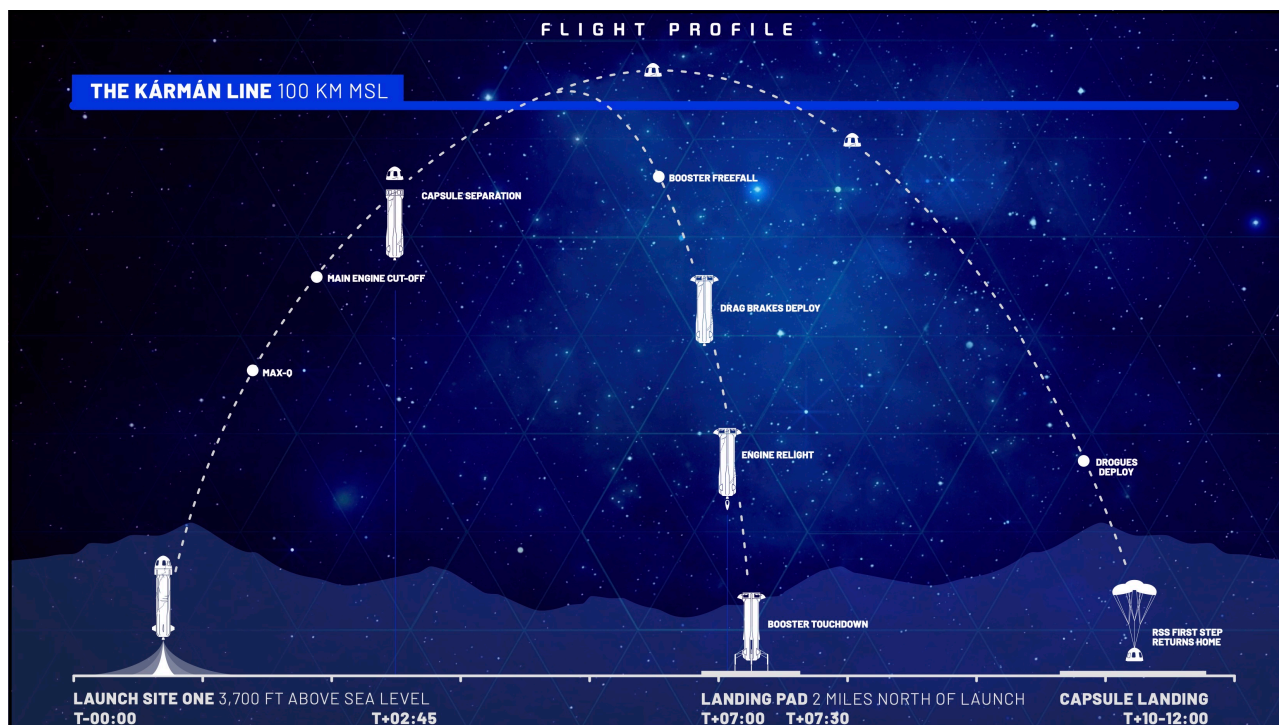
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NS-29 MISSION

After separation capsule spins up to 11rpm to create lunar gravity

Uses Capsule's Reaction Control System (RCS)

Payloads experience over 2 minutes of 0.165g accelerations

Capsule spins down after end of lunar gravity phase





BLUE ORIGIN

11 RPM

Centripetal Acceleration

Rotation



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Flow Boiling in Microgap Coolers Lunar Gravity Demonstration

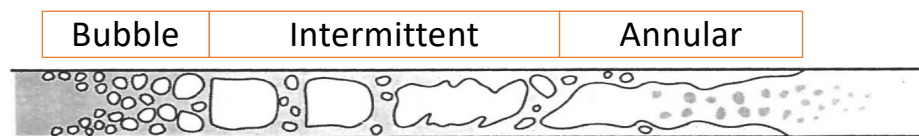
Franklin L. Robinson
NASA Goddard Space Flight Center
May 7, 2025



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Flow Boiling

- Forced flow of coolant undergoing liquid-to-vapor phase change



Carey, 1992

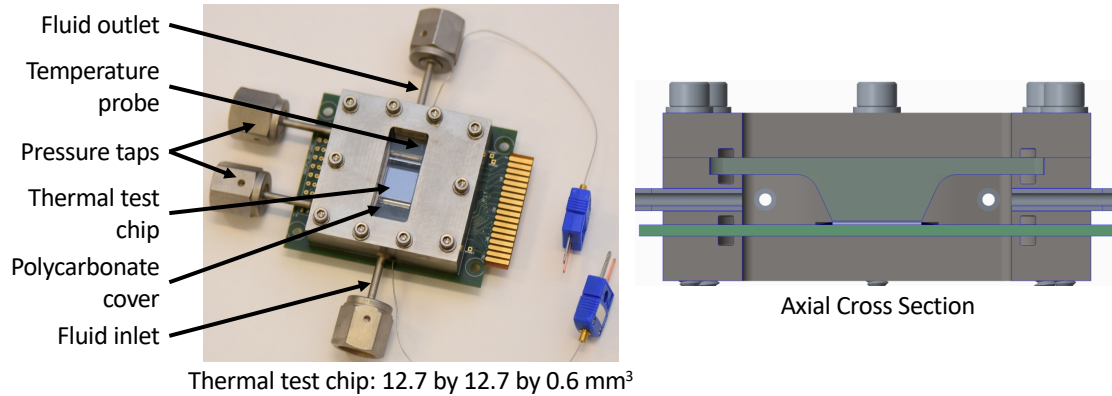
- High heat flux cooling with low pumping power
- Delivers heat to radiator with little temperature drop (T^4)
- Limited use due to complex nature, especially for microgravity and high-g applications

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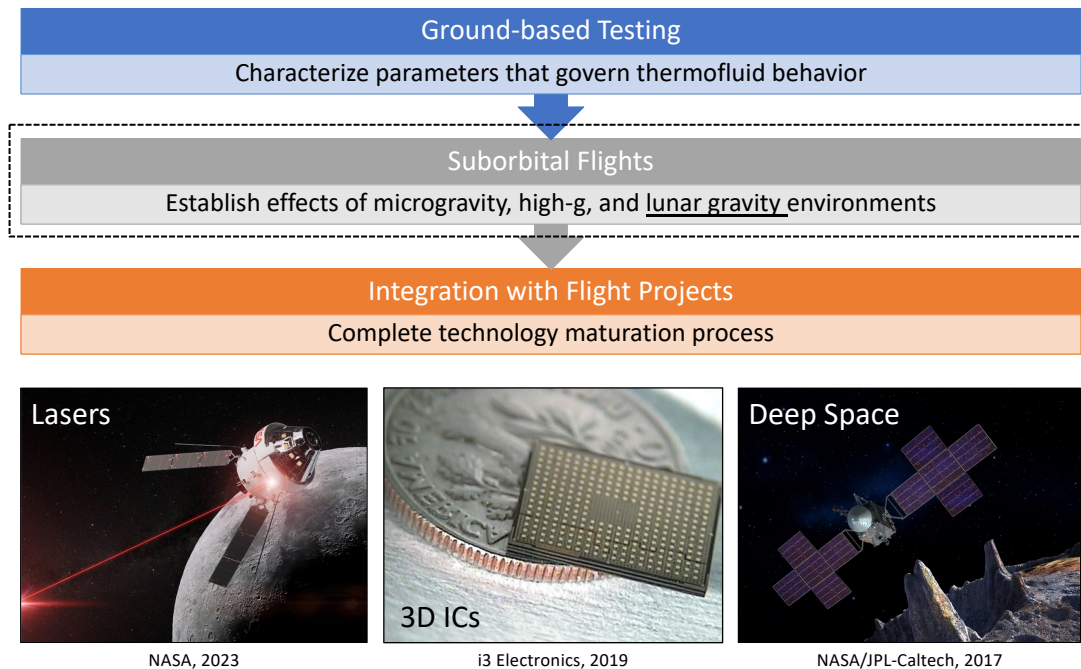
Microgap Coolers

- Low aspect ratio channel embedded within or between devices
- Direct contact between devices and coolant flow



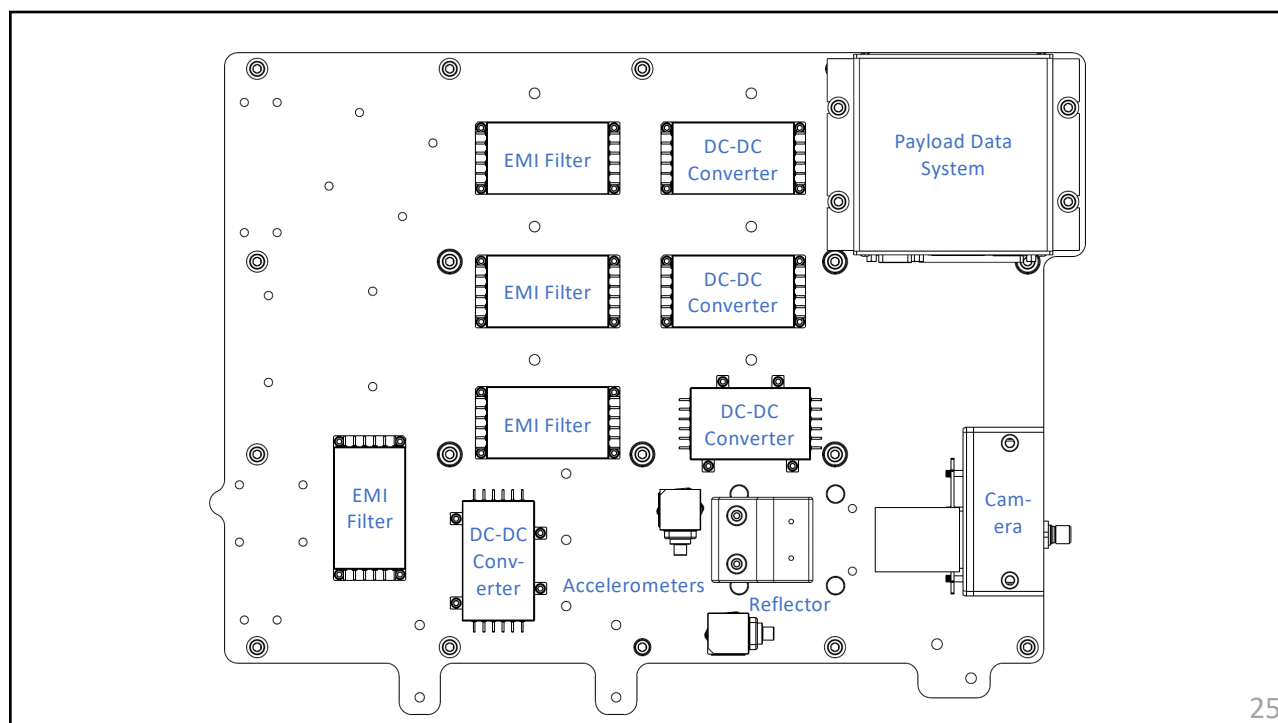
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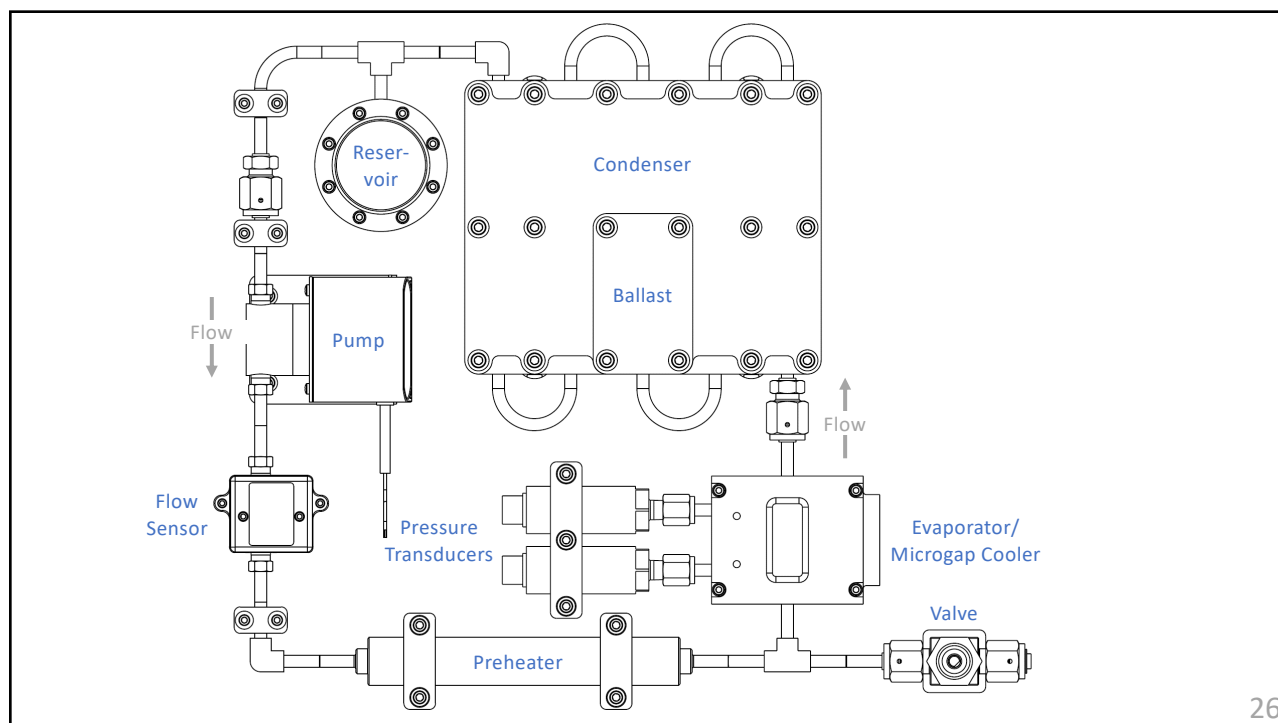


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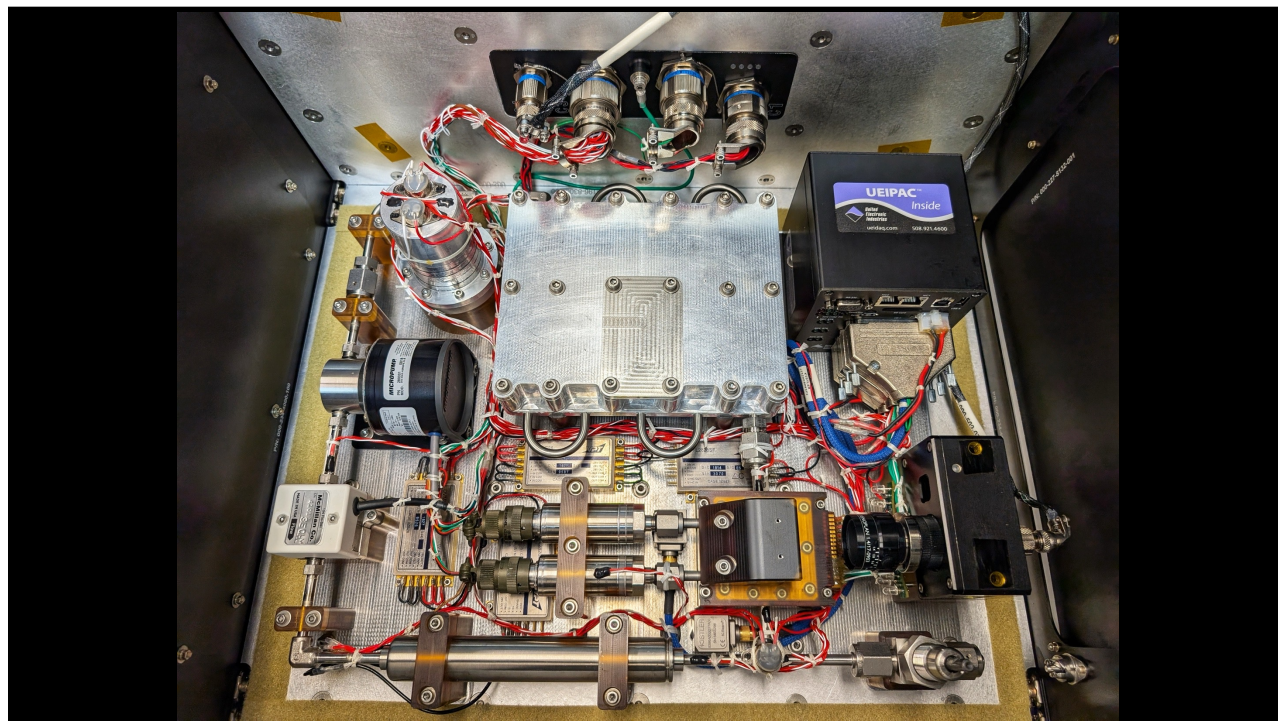
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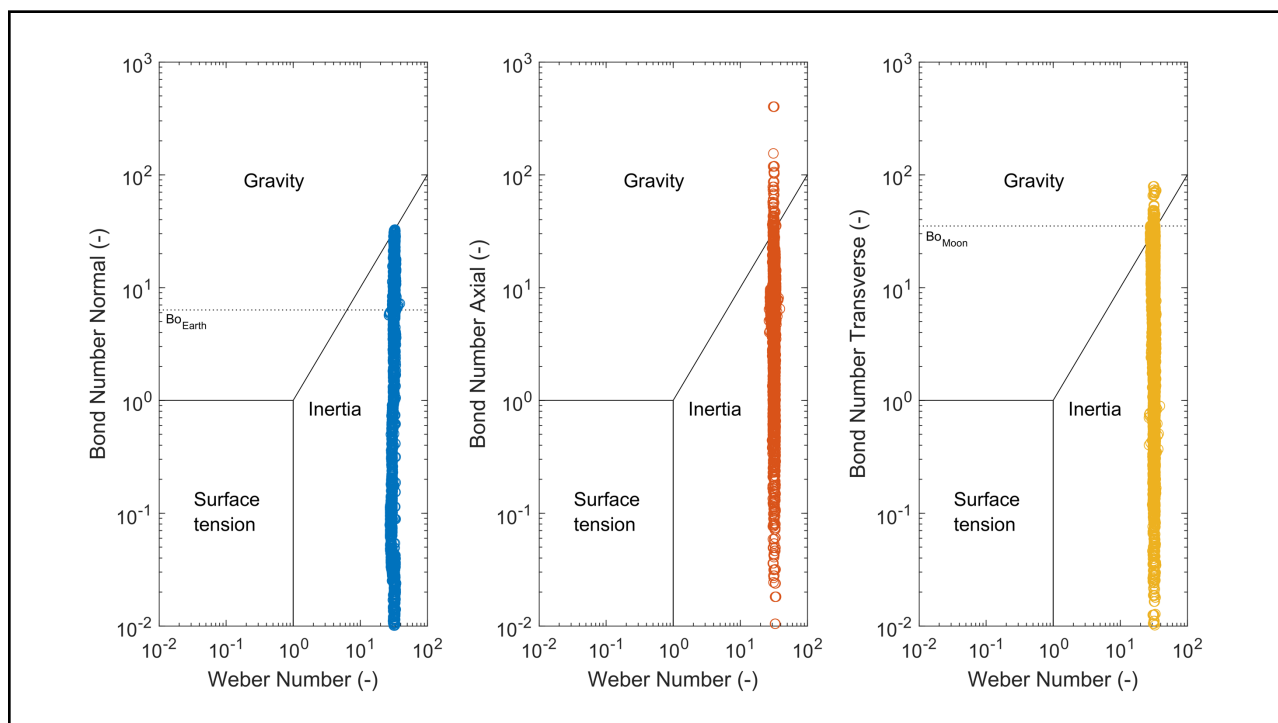
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Recommendations

1. Make critical measurements internally
2. Make use of everything offered by the flight opportunity
3. Design for multiple flights
4. Allocate resources for post-flight operations

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References and Credits

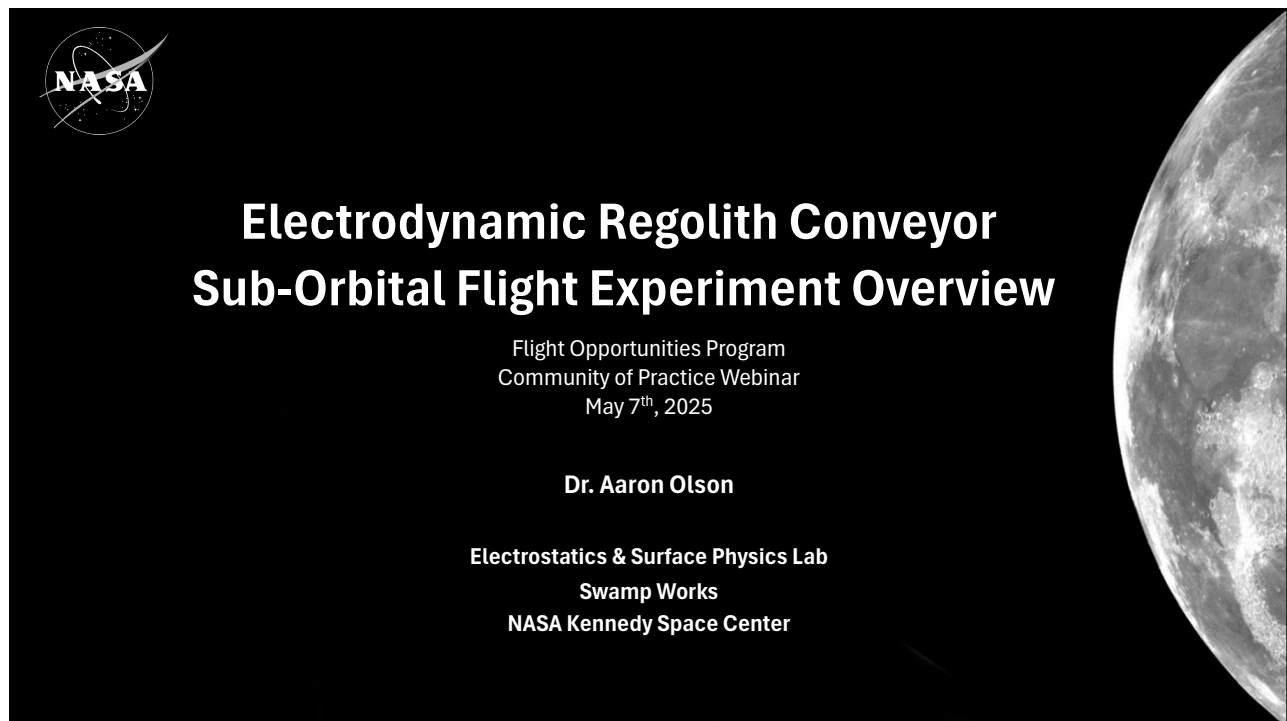
Slide	Citation or Credit
1	Photo courtesy of Blue Origin
2	Carey, V. P., 1992, <i>Liquid-Vapor Phase-Change Phenomena: An Introduction to the Thermophysics of Vaporization and Condensation Processes in Heat Transfer Equipment</i> , Hemisphere Publishing Corporation, Washington.
4	NASA, 2023, "A Visualization of the Orion Spacecraft Orbiting the Moon while Utilizing a New Cutting-Edge Technology, the Orion Artemis II Communications System (O2O)" accessed May 5, 2025, https://www.nasa.gov/directorates/somd/space-communications-navigation-program/nasa-laser-communications-terminal-delivered-for-artemis-ii-moon-mission/ .
4	i3 Electronics, "3D Stacking with Heterogeneous MCMs", accessed Aug. 8, 2019, http://i3electronics.com/what-we-do/heterogeneous-mcm/ .
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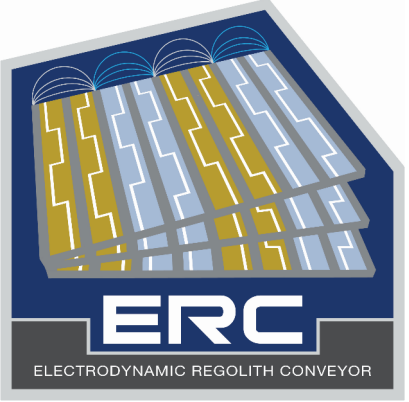


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Outline

- Introduction
- Electrodynamic Dust Shield Background
- Payload & Experiment Requirements
- System Design
- Testing & Integration
- Flight Results
- Future Work
- Acknowledgements & References



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Introduction – Electrodynamic Regolith Conveyor

- **NASA KSC is developing the Electrodynamic Regolith Conveyor (ERC) technology as a solution for conveying, directional dust mitigation, soil sampling, and beneficiation**
 - Low power, no mechanical actuation, dust tolerant regolith transport
- **Extension of the flight proven Electrodynamic Dust Shield (EDS)**
 - Developed for lenses, solar panels, radiators, seals, fabric, and foldable mats
- **The objective of the ERC sub-orbital flight experiment is to perform testing to advance the TRL of the ERC technology by:**
 - Measuring regolith transport flow rate, power consumption and range of particle trajectories at four different inclinations in a simulated lunar gravity and vacuum environment.
 - Anchoring discrete element modeling efforts with test data

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EDS Discrete Element Modeling

EDS modeling with various lunar simulant & operating parameters

$$m_i \ddot{x}_i = F_{coulomb_i} + F_{DEP_i} + F_{image_i} + F_{drag_i} + F_{friction_i} + F_{adhesion_i} + m_i g$$

$$F_{coulomb} = Eq$$

$$F_{DEP} = \frac{4\pi\epsilon_0(\epsilon - 1)R^3 E_0 \nabla E_0}{\epsilon + 2}$$

$$F_{image} = \frac{1}{4\pi\epsilon_0} \sum_{n=1}^N \left(\frac{q_i q_n}{2d} \right)^2 \left(\frac{d}{|d|} \right)$$

$$F_{drag} = -6\pi\eta R \dot{x}$$

$$F_{friction} = -\mu F_n n$$

Programs/Codes

- LIGGGHTS
- Aspherix/CFDEM

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Payload Requirements

- The ERC payload designed for a Blue Origin New Shepard capsule single size payload locker
- Launch loads, EMI/EMC, Interfaces, etc...


Payload locker type	Single
Internal dimensions	52.3 x 41.4 x 24.1 cm
Payload mass	11.34 +/- 0.045 kg
Payload power	18 V, 8 A max

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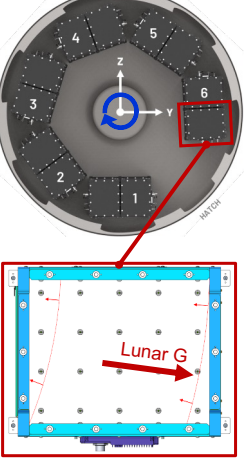
Experiment Requirements





11 RPM

Capsule simulating 1/6 gravity by spinning during freefall (Blue Origin Payload User's Guide)



Payload locker arrangement inside capsule and the associated centripetal acceleration during the spin phase of flight

Table 2. High level ERC experimental requirements


#	High level requirements
Environmental	
1	<500 mTorr experiment pressure during operation
Regolith Flow	
2	Storage of 200 or more g of < 200-micron regolith simulant
3	Feed up to 1.2 g/s of regolith simulant onto and uniformly across the conveyor surface
Conveyor Operation	
4	+/- 4 kV 10 Hz 4-phase square waveform
5	Rotating conveyor plane >10 degrees from horizontal
6	Side and top view of regolith motion
Instrumentation	
7	240 fps video recording, profile and top views
8	Lighting for general observation and particle flow tracking
9	Regolith and experiment temperature measurement
10	Pressure measurement
11	Regolith flow rate measurement
12	Power measurement (voltage and current)

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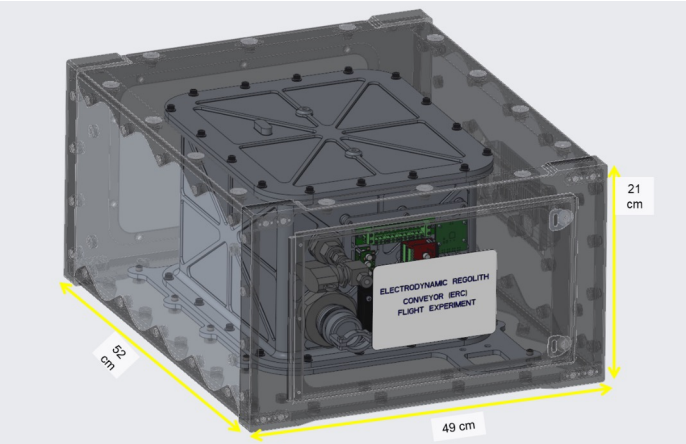
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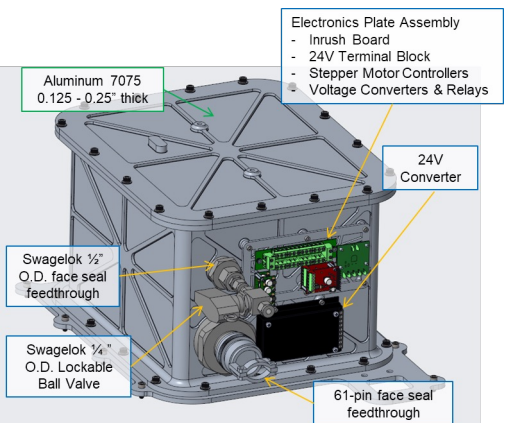
System Design



- The ERC payload's primary structure, mounted to its payload locker, is an aluminum vacuum chamber
- ERC consists of three primary internal subsystems: Feeder, Conveyor, Instrumentation



ERC payload design (inside transparent payload locker)




ERC vacuum chamber and its external components

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Subsystem Design

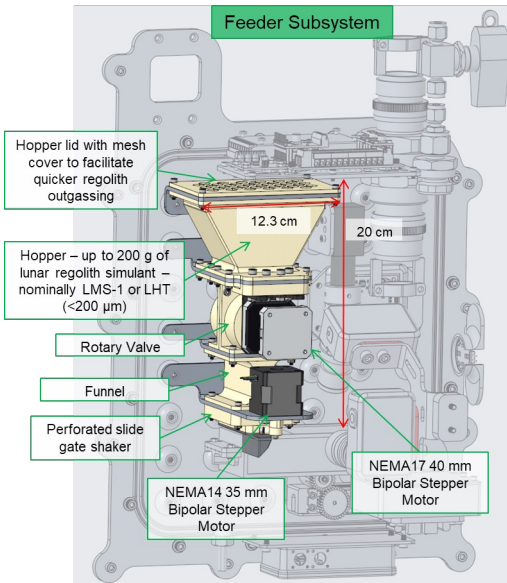
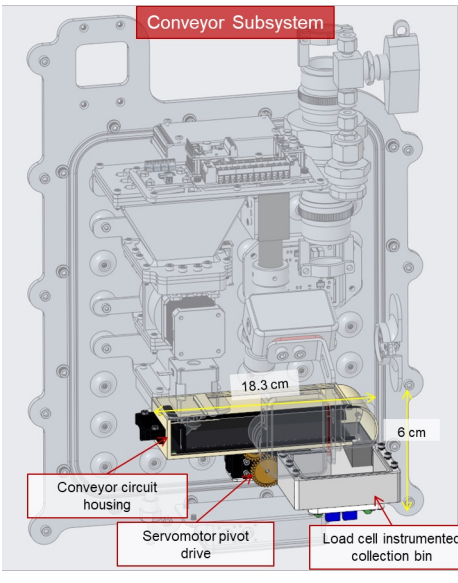


Feeder

- Stores up to 250 g of regolith
- Feeds regolith at a controllable rate onto the conveyor surface


Conveyor

- 4-phase EDS
- Transparent windows
- Pivots up to 15°
- Load cell instrumented collection bin





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Subsystem Design



Cameras

- 4K GoPro HERO 10
- Overhead view with LED light
- Profile view – used with laser

Laser

- 5 mW 532 nm line laser
- Cylindrical lens

Pressure Sensor

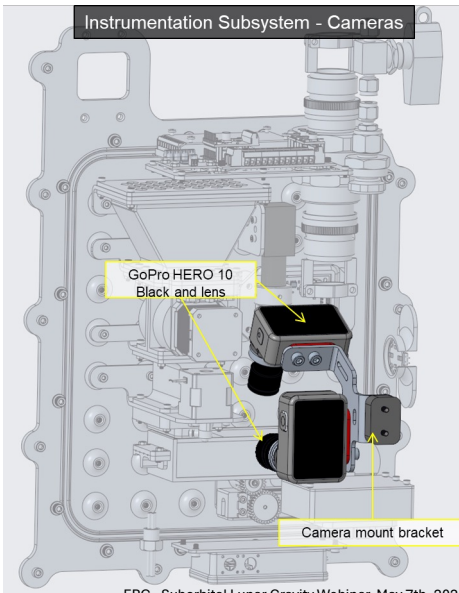
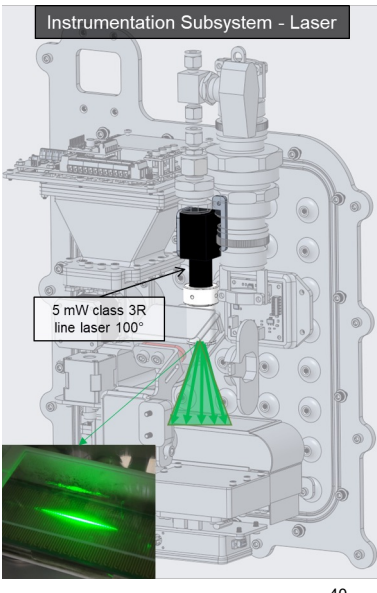
- In-vacuum Pirani

Temperature Sensors

- RTDs on chamber, largest motor


Controller Measurements

- Voltage, current
- Load cell data
- Control status
- RTDs
- Pressure





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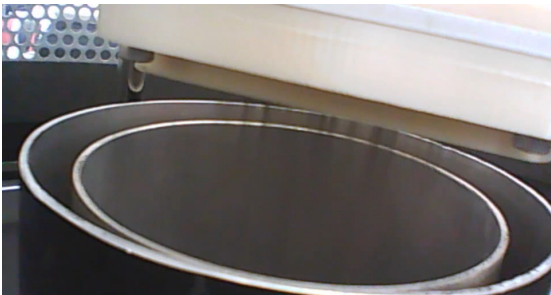


Subsystem Testing

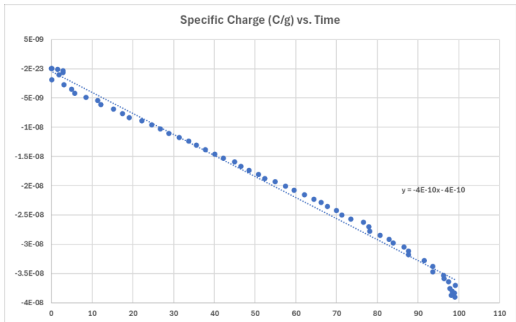


Regolith Storage & Flow

- >200 g hopper regolith storage, and >1.2 g/s flow rate demonstrated
- Charge/mass ratio recorded for post analysis (proportional to coulomb force on particles)



JSC-1A 100-200 micron regolith simulant flowing through the ERC feeder and into an electrometer instrumented faraday cup at ~1E-05 Torr




Mass normalized charge vs. time for JSC-1A 100-200 micron regolith simulant from the ERC feeder subsystem

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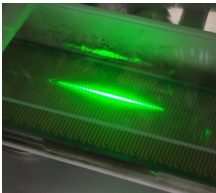



Subsystem Testing

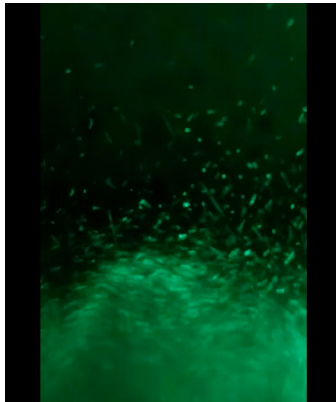


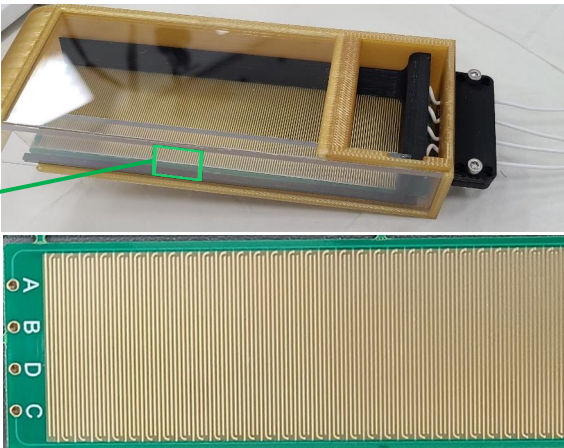
Conveyor Operation & Laser/Camera Testing

- Regolith directional conveying (power supply + circuit) and laser-based flow tracking demonstrated

Line laser impinging on conveyor circuit surface through top window (top left), high voltage power supply +/- 4 kV four phase output (bottom left) and regolith flow (right)






ERC conveyor enclosure (top) and 0.3 mm trace width x 0.3 mm gap width 4-phase circuit (bottom)

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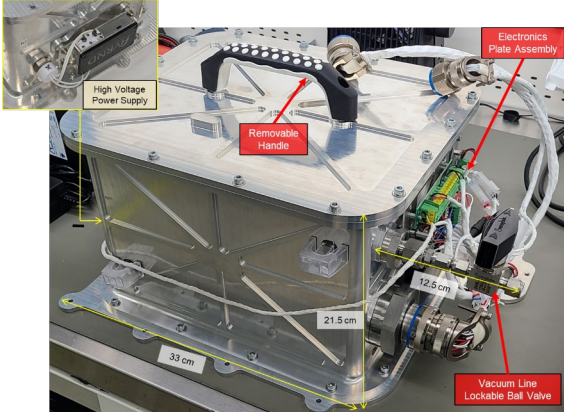
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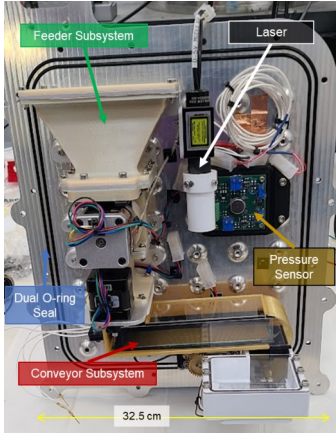


System Integration






Fully integrated ERC payload



ERC components mounted to the vacuum chamber baseplate




ERC cameras and lenses on the vacuum chamber top plate

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System Testing



Payload Interface Requirements Met

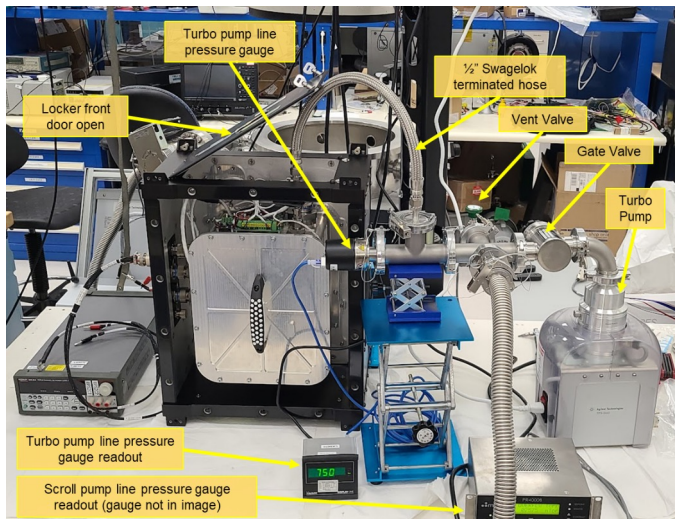
- Power, Mass, CG
- Environments

Vacuum Chamber Pressure at Flight Time

- <400 mTorr chamber pressure after 10 hr wait

ERC Experiment Requirements Met

- Regolith Storage & Flow
- 4-Phase Conveyor
- Instrumentation



Fully integrated ERC payload after a run for record test at vacuum


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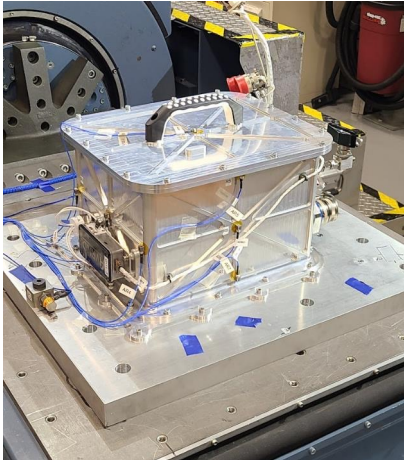
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Environmental Testing



Random vibration testing



Shock (half-sine pulse) testing




EMI/EMC testing


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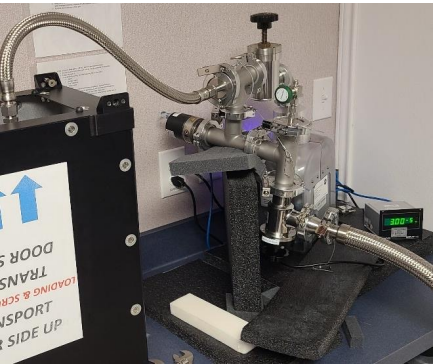
Payload Integration



Arrival at Launch Site One



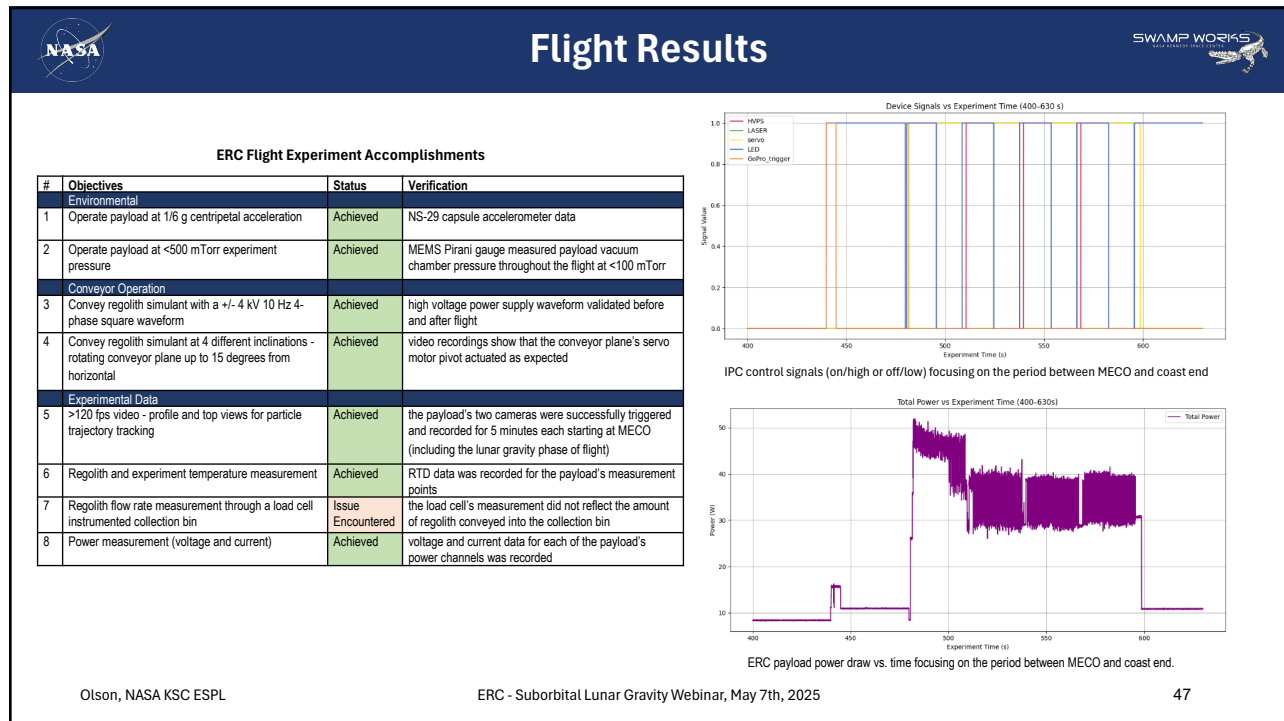
ERC payload checkout



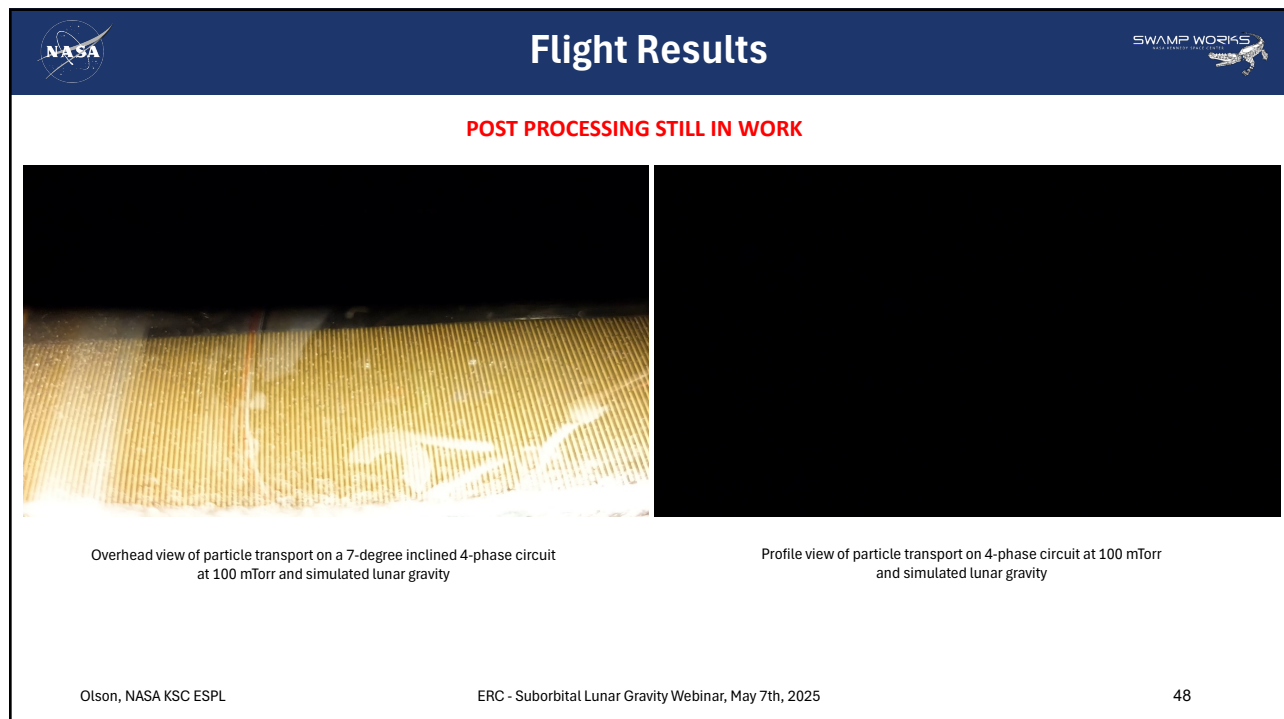
ERC payload pump down prior to flight

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Future Work



- Continued Post Flight Analysis
- Updated Discrete Element Modeling
- Journal Publication
- Technology Maturation & Infusion



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Acknowledgements





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Olson, NASA KSC ESPL


ERC - Suborbital Lunar Gravity Webinar, May 7th, 2025

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EDS on Blue Ghost Lunar Lander



1 & 2-Phase Designs Tested on the Moon at +/-2 kV

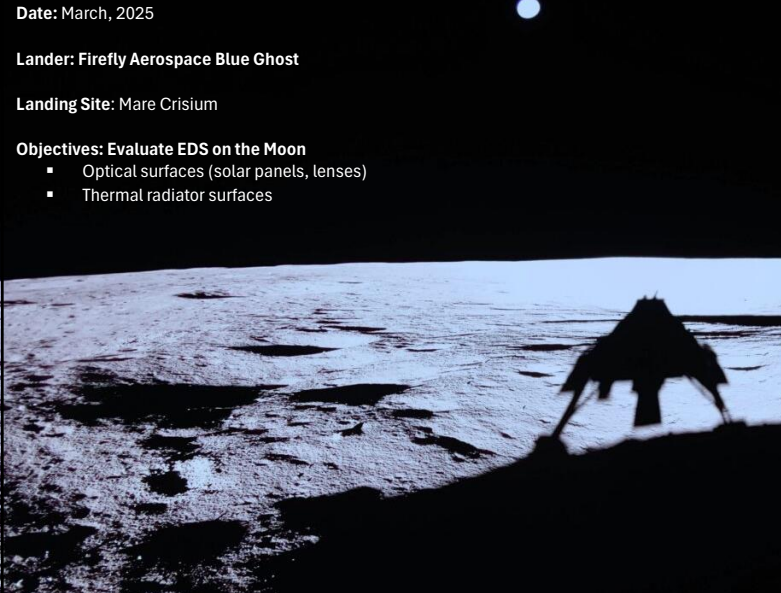
Date: March, 2025

Lander: Firefly Aerospace Blue Ghost

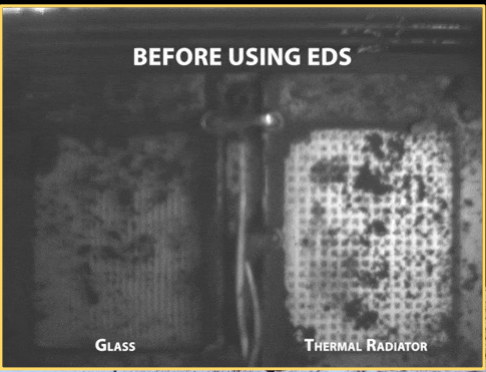
Landing Site: Mare Crisium

Objectives: Evaluate EDS on the Moon

- Optical surfaces (solar panels, lenses)
- Thermal radiator surfaces



BEFORE USING EDS



GLASS
THERMAL RADIATOR

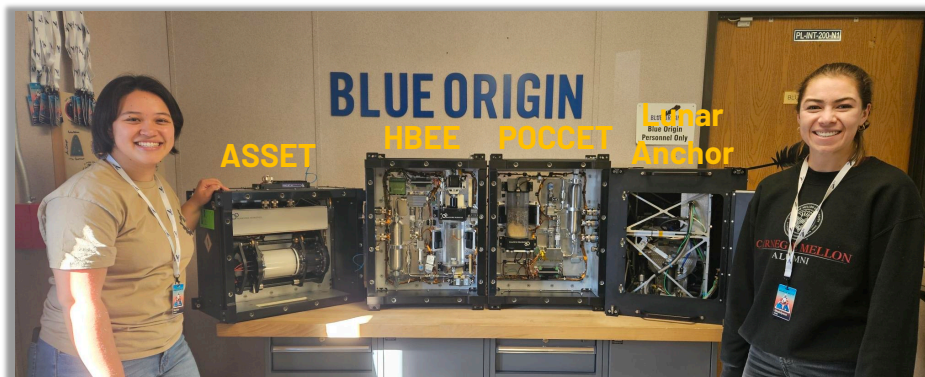
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Honeybee Robotics NS-29 Payloads

- Honeybee is subsidiary of Blue Origin
- 4 experiments funded by Tech Flight Program
- Focused on lunar g, but applicable elsewhere
- Overcame Eaton Fire to deliver on time



BLUE ORIGIN

8 MAY 2025

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ASSET

ASTEROID SOIL STRENGTH EVALUATION TEST

1. Description

Soil mechanics experiment designed to evaluate bearing capacity of granular materials.

2. Significance

Helps in design of footpads, structures, asteroid landers interacting with regolith.

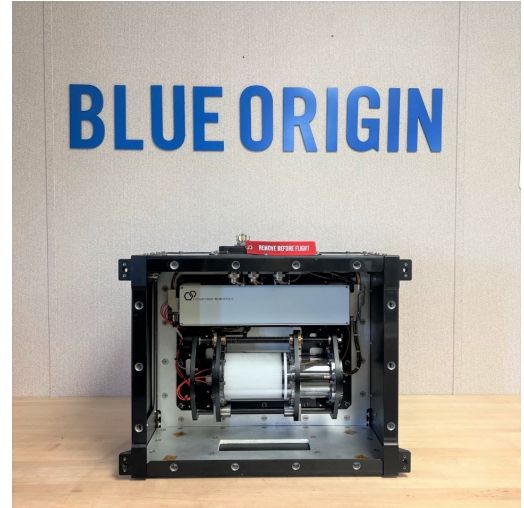
3. Experiment

Glass beads compressed in a cylinder. Penetrometer driven into the simulant to measure force vs penetration curve.

4. Results

Bearing capacity is ~30% lower at 1/6th g in non-cohesive soil (glass beads).

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HBEE

HONEYBEE BUBBLE EXCITATION EXPERIMENT

1. Description

Observes bubble formation and propagation in a viscous fluid.

2. Significance

Helps in design of In Situ Resource Utilization processes such as Oxygen generation during Molten Regolith Electrolysis.

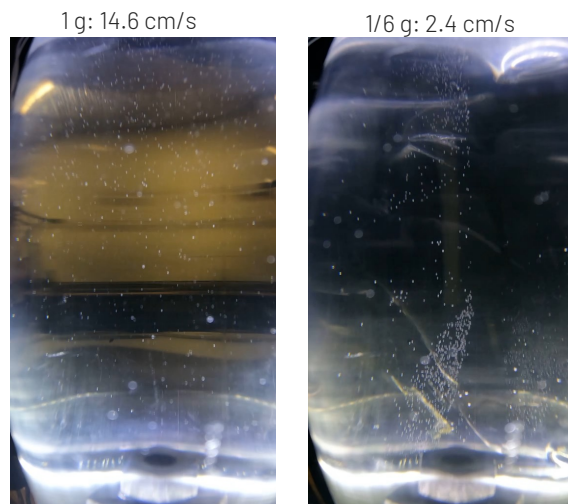
3. Experiment

N₂ bubbles introduced into a container with corn syrup

4. Results

Bubbles move 6x slower in lunar g (as predicted). This will affect rate of ISRU, boiling etc.

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POCCET

PUFFER-ORIENTED COMPACT CLEANING AND EXCAVATION TOOL

1. Description

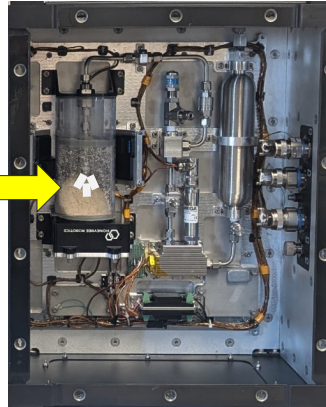
Uses puff of air to excavate a hole in cohesive regolith simulant.

2. Significance

Will help evaluate effectiveness of pneumatic trenching for LISTER pneumatic drill (onboard Firefly Blue Ghost lander), and rocket-plume interaction.

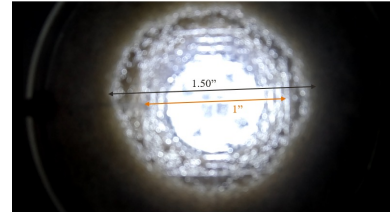
3. Experiment

Puff of N₂ into kinetic sand (silicone oil and play sand)

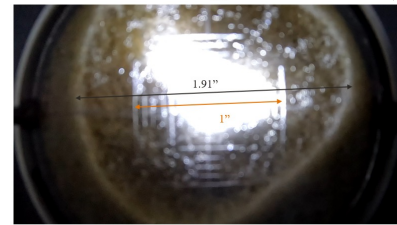


4. Results

Excavates faster and 50% wider at 1/6th g. Rocket plume would make larger holes.



1G



1/6 G

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Lunar Anchor

ROOT-INSPIRED LUNAR ANCHORING

1. Description

Demonstrates performance of an inflatable, low-reaction-force anchor that grows into the ground like a plant root.

2. Significance

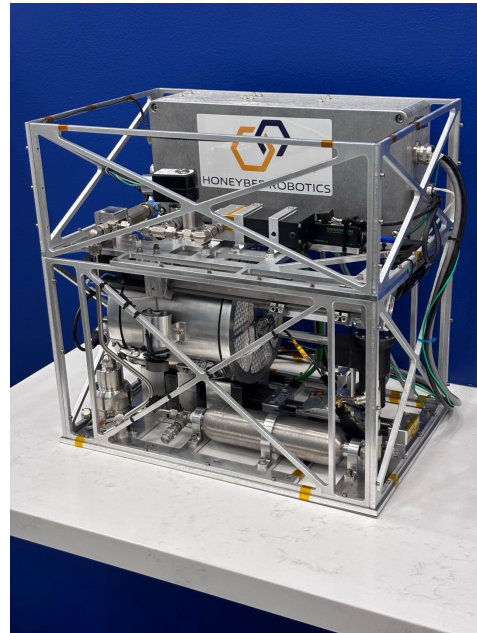
Anchor may be required for stabilizing landers, rovers etc. on small planetary bodies.

3. Experiment

Measure insertion and extraction force.

4. Results

Anchor generates high extraction force while requiring little to no insertion force.



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WHAT QUESTIONS DO YOU HAVE?

Please put your questions in the chat

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NASA.GOV/FLIGHTOPPORTUNITIES

Our June webinar will be a regolith roundtable.

Visit our websites for more information and resources, including our newsletter and monthly Community of Practice webinars.

Reach out:

NASA-FlightOpportunities@mail.nasa.gov



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