



NAVAL
POSTGRADUATE
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SPACECRAFT ROBOTICS
LABORATORY

NASA Ames Research Center, February 28 2017
Astrobbee Quarterly Meeting

“ASTROBATIC MANEUVERING” OF ASTROBEE

Dr. Marcello Romano, Professor and Lab Director
Dr. Josep Virgili-Llop, NRC Postdoctoral Fellow

Spacecraft Robotics Laboratory
Mechanical and Aerospace Engineering Department
Naval Postgraduate School, Monterey CA

To Demonstrate baseline Astrobatic Maneuvers with Astrobees exploiting ARC perching arm.

- As early as possible once Astrobees reach the station, in compliance with all of the applicable constraints.
- Software-only, no additional hardware required.
- Two basic maneuvers envisioned:
 - Astrobatic Maneuver 1: Push and Stabilize
 - Astrobatic Maneuver 2: Hopping



PI - Prof. Marcello Romano

SRL-Astrobee team members:

LT Katrina Alsup, USN, MS Student

- Guidance and control.

LT Justin Komma, USN, MS Student

- Evolved perching arm design.

Dr. Josep Virgili, Postdoc

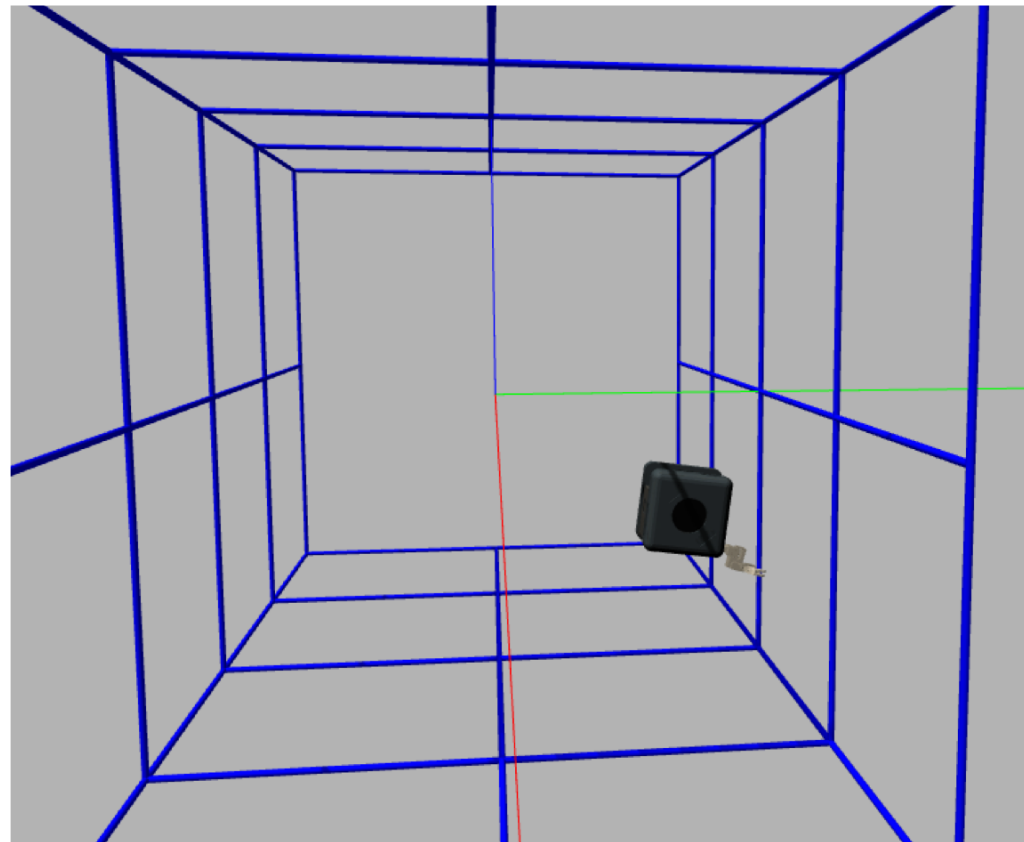
- ROS/Gazebo sim. environment.
- Flight SW.

Past SRL-Astrobee team members:

LT Andrew Bradstreet, USN, MS Student

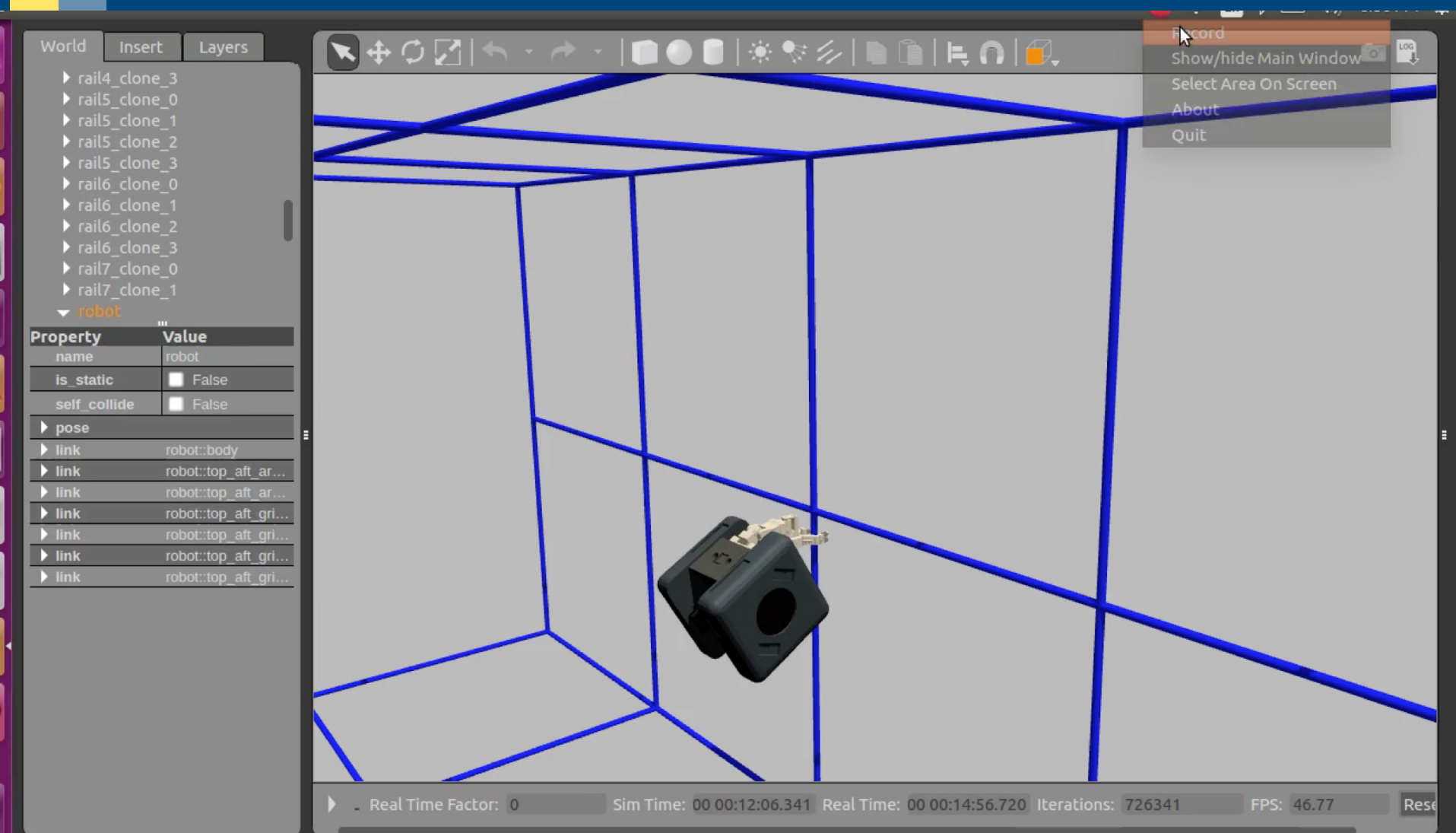
- Proof of concept.

- Based on v0.2 of the GitHub public release.
- Simplified environment to facilitate maneuver development.
- Plugin for idealized handrail grasping.



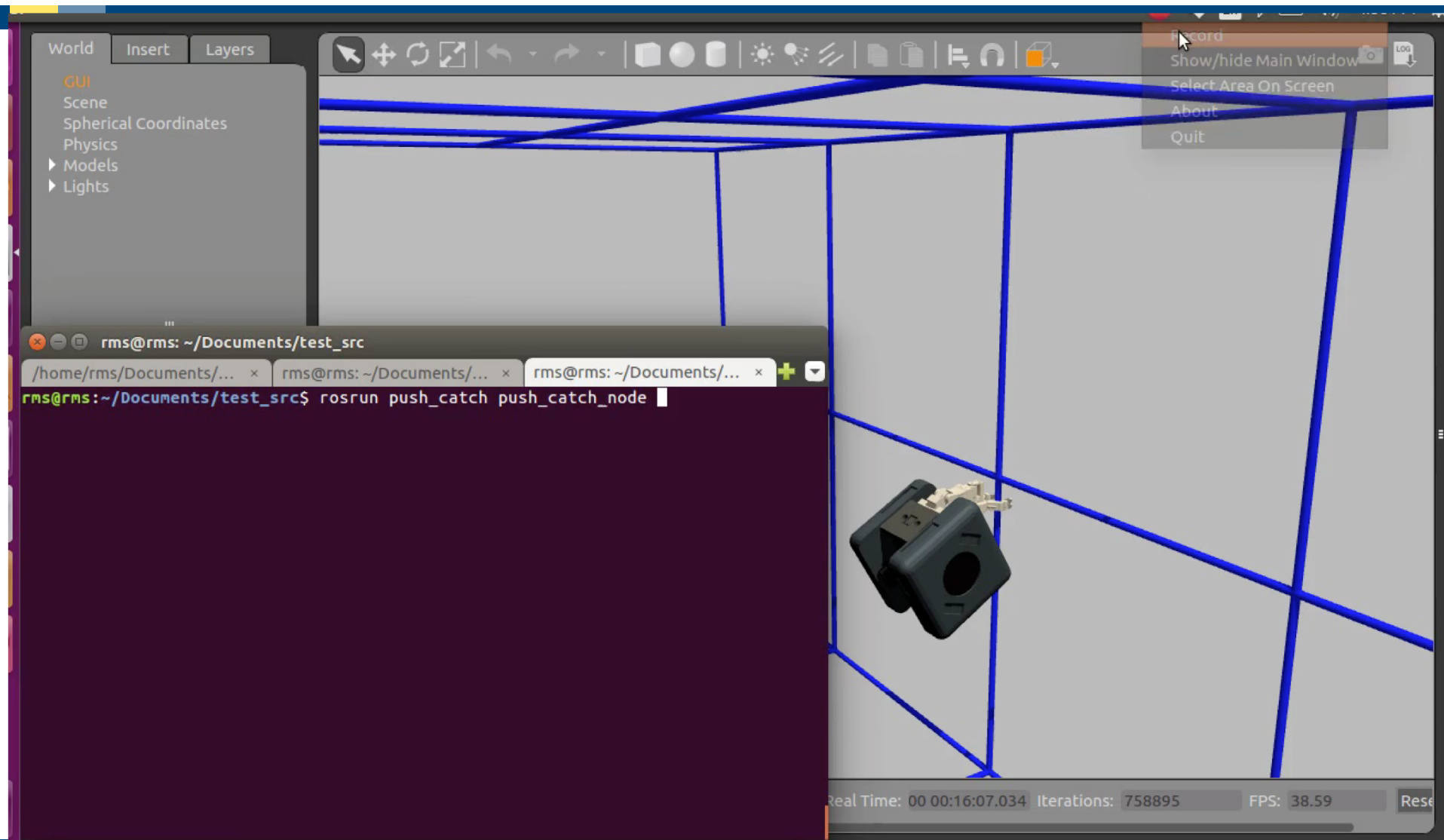


Astrobotic Maneuver 1: Push and Stabilize



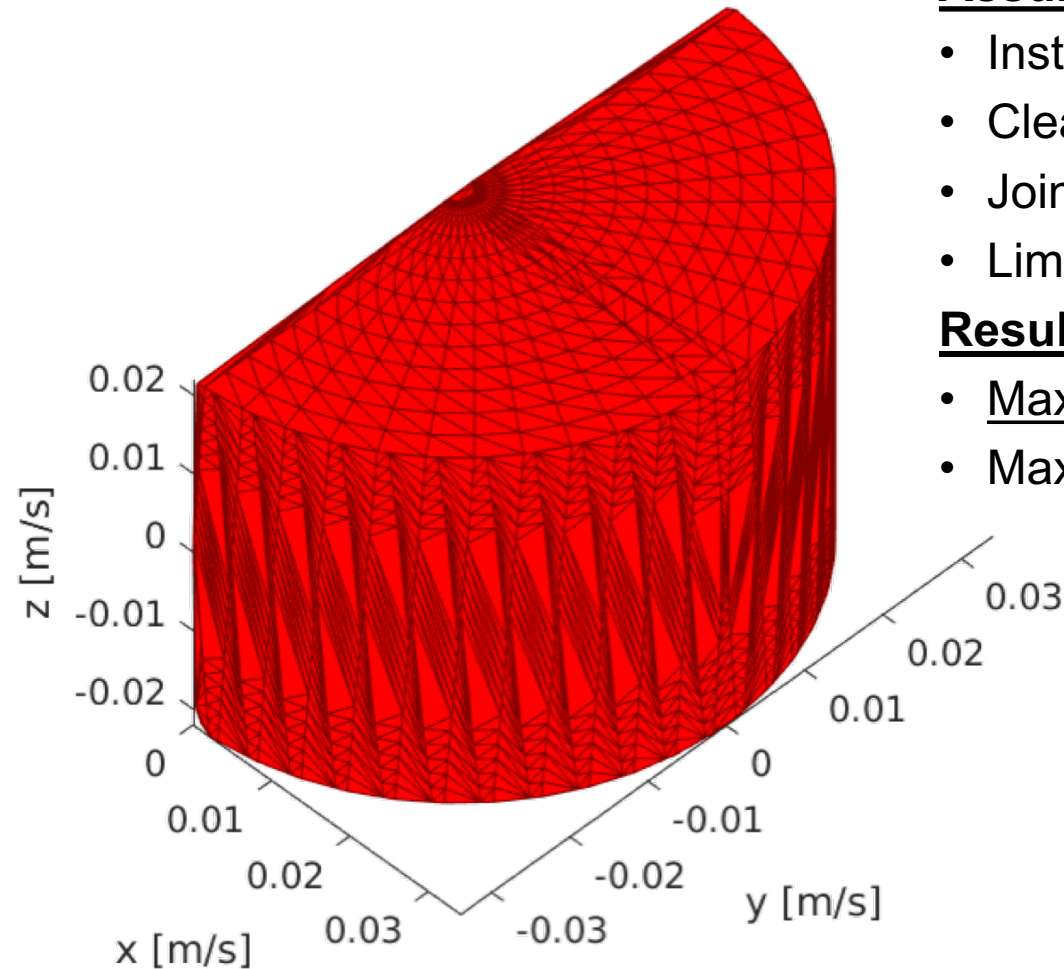


Astrobatic Maneuver 2: Hopping



Astrobee's Body Linear Velocity Envelope

Linear Velocity Envelope

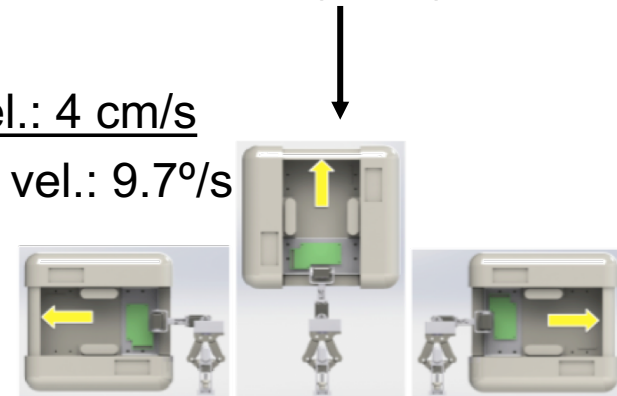


Assumptions:

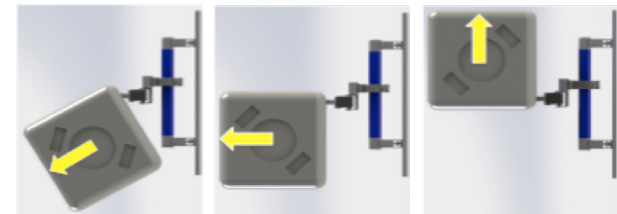
- Instantaneous acceleration.
- Clean rail separation is always possible.
- Joint velocity control is available.
- Limits as defined in In Won (2017)

Results

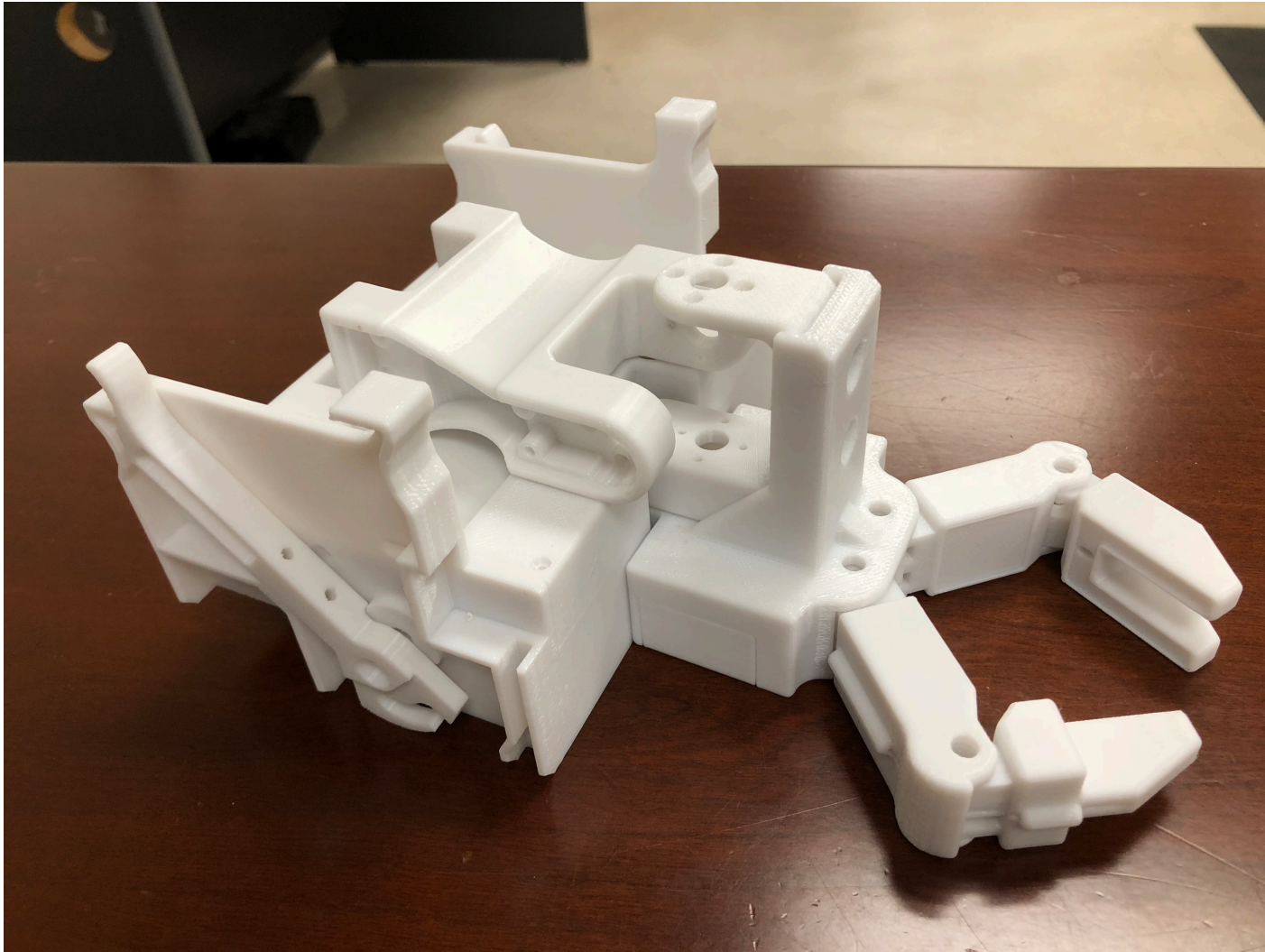
- Max linear vel.: 4 cm/s
- Max. angular vel.: 9.7°/s



(a) Pan range of -90.0° to 90.0°

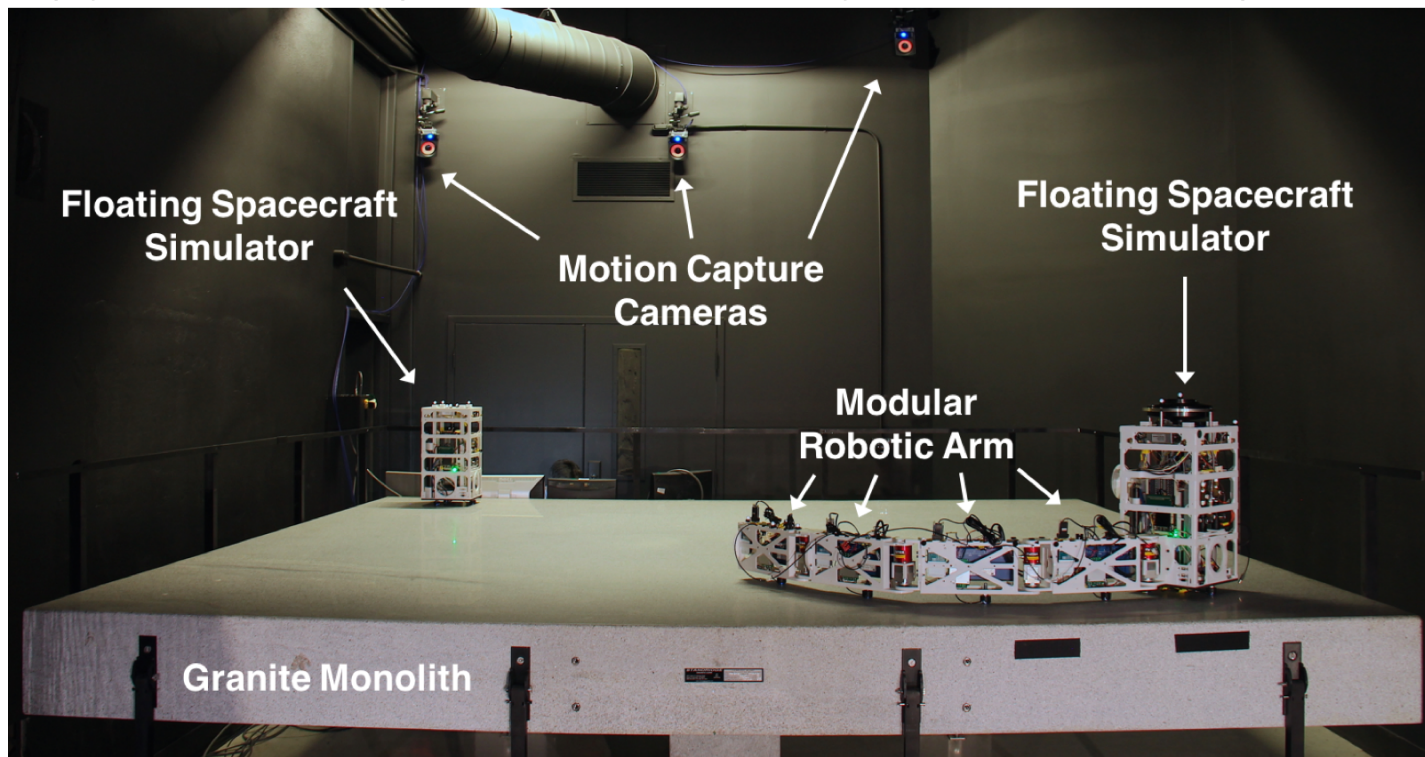


(b) Tilt range of -30.0° to 90.0°



The NPS POSEIDYN Test Bed (2004-2017)

Elements: 1) granite table, 2) autonomous floating S/C simulators, 3) metrology system.



Goals: testing of dynamic models GN&C algorithms for research and graduate students education

[Ref: Zappulla, Virgili-Llop, Zagaris, Park, Romano, POSEIDYN Air-Bearing Test Bed for Experimental Evaluation of Autonomous Spacecraft Proximity Maneuvers. Journal of Spacecraft and Rockets, 2017]



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Questions?

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