## Title and Research Team

- Robust Entry and Landing Guidance Under Dynamic Uncertainty
- PI: Professor Jay McMahon, CCAR, Smead Aerospace Engineering Sciences department, University of Colorado Boulder
- TBD Post-doctoral researcher
- TBD Graduate Student Research Assistant
- Collaborators
  - Dean/Professor Bobby Braun, College of Engineering and Applied Sciences, Smead Aerospace Engineering Sciences department, University of Colorado Boulder
  - Professor Hanspeter Schaub, CCAR, Smead Aerospace Engineering Sciences department, University of Colorado Boulder

## **Research Objectives**

- What do you hope to accomplish?
  - Design and feasibility testing of a new robust guidance algorithm applied to EDL problems
- What is the innovation?

**GMM Capturing Uncertainty in:** 

 $\delta x_2$ 

Propulsive Control Phase

Supersonic Control Phase Dynamics (winds, atmospheric density, ...)

Controls (maneuver errors, thrust, ...)

- Create and implement a general aerospace guidance algorithm that will robustly deliver a vehicle to a desired target state in the presence of uncertainty
- How does your research compare to the SOA?
  - PredGuid our algorithm is more general not for only bank angle guidance and more appropriately accounts for

uncertain nature of problem

- G-FOLD directly addresses uncertainty for robustness
- What are the start and end TRLs (with justification)?
  - TRL 1 start (since unpublished)
  - TRL 4 target (test algorithms)

## **Potential Impact**

Benefits of the proposed space technology research to future space science and exploration needs if the technology is eventually successful

- Improve performance and capabilities for Mars landing
- More mass to the ground more robustly
- New missions to Mars moons enabled by improving aerocapture guidance and propulsive landing
- Other benefits and outcomes from the proposed research
  - Builds a core research competency that will be used in the future to improve guidance for many other aerospace systems, most immediately for lunar and asteroid exploration

## Approach

• Overview description: use experience in spacecraft GNC to apply new advances in control theory to the problem of EDL in

order to create a system that could be implemented in the near future (ie doesn't require a servers worth of computers on- board)

- The new guidance algorithm will be based on advances in stochastic model predictive control, and will consist of three main components
  - Machine learning for prediction of perturbing accelerations

Hypersonic Aerodynamic

**Control Phase** 

- Unscented Gaussian Mixture Model for prediction of the effect of uncertainties in the dynamic model
- Non-linear minimization of stochastic error metrics with controls
- Implementation of high-fidelity simulation in BASILISK