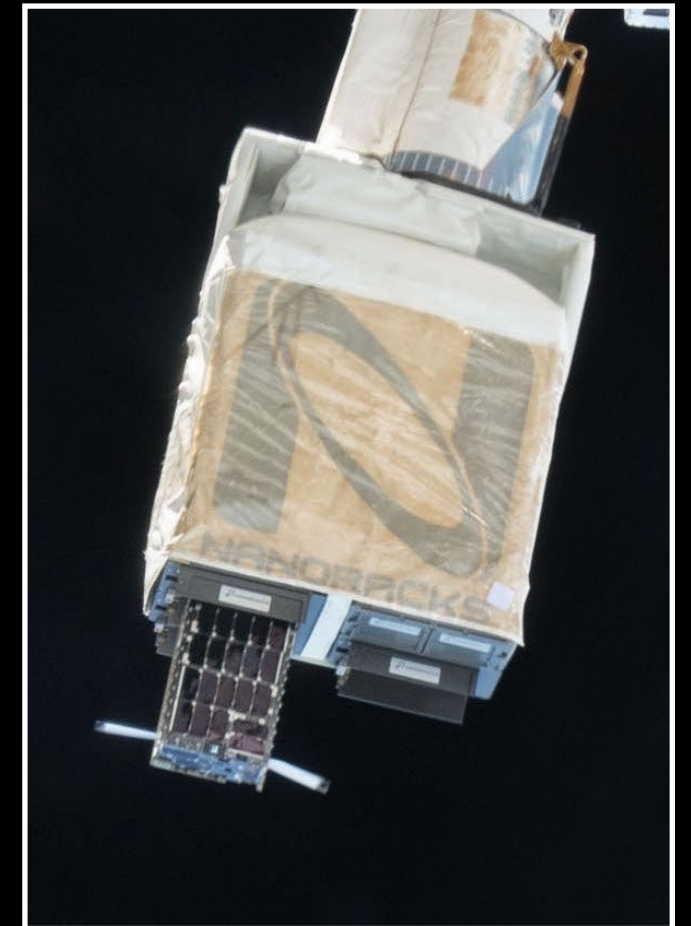
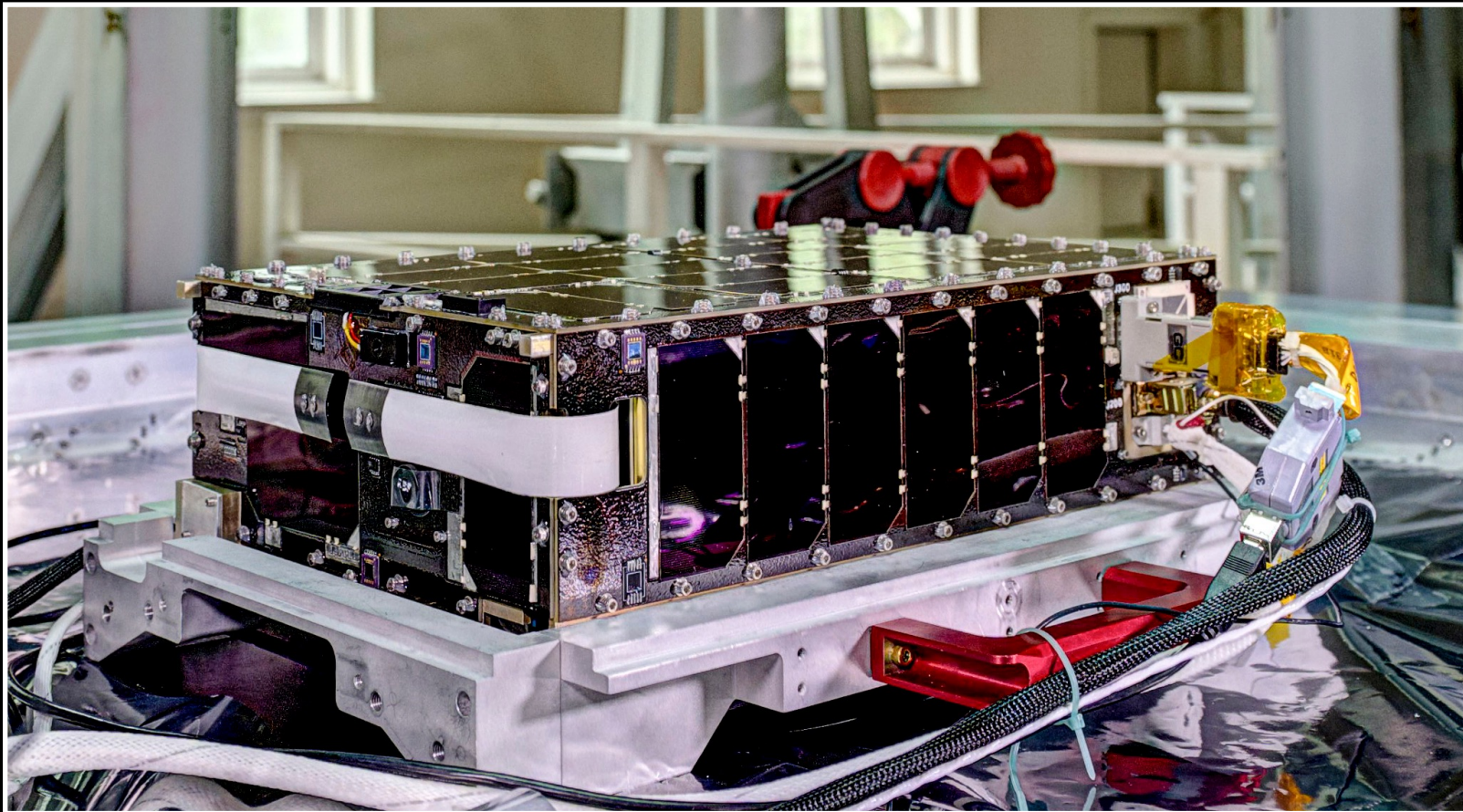


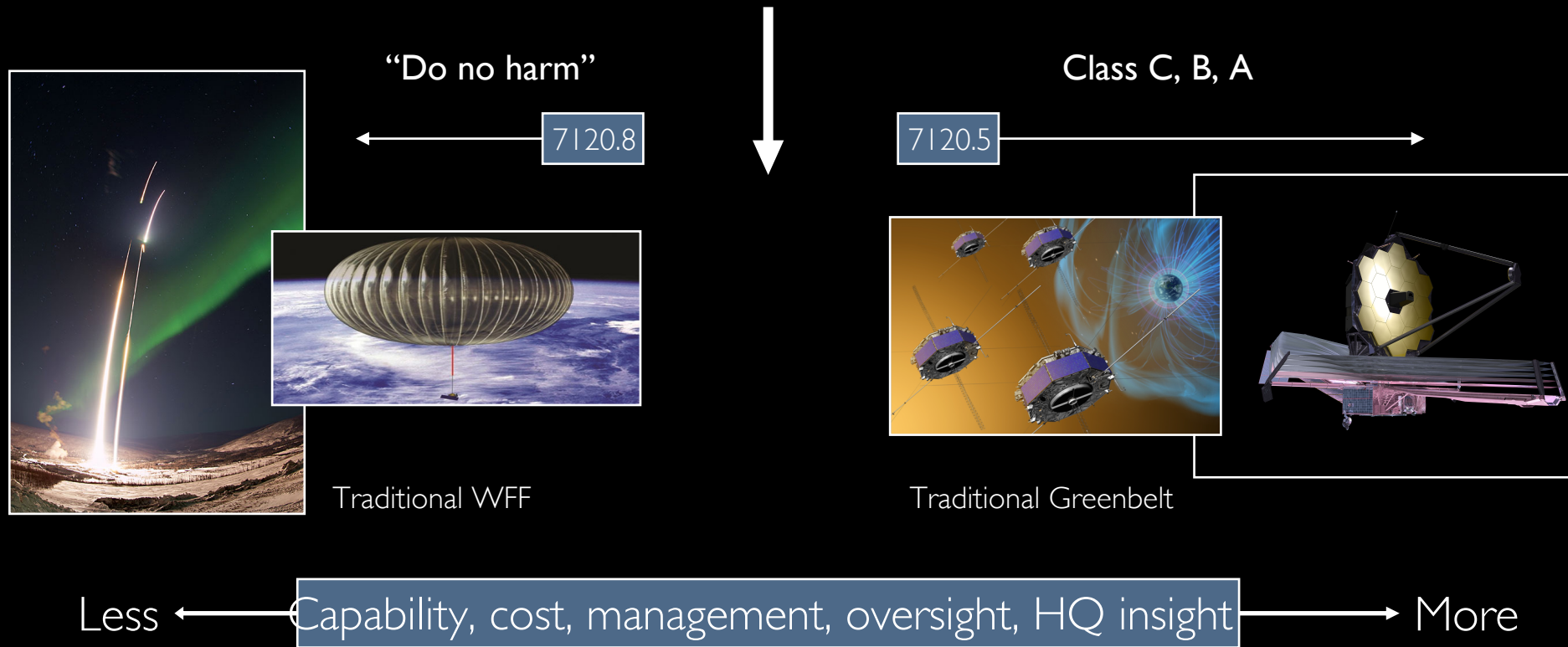
Dellingr: NASA GSFC's first 6U CubeSat

Larry Kepko, NASA GSFC Space Weather Laboratory

Chuck Clagett, Luis Santos, B. Azimi, D. Berry, T. Bonalsky, D. Chai, M. Colvin, A. Cudmore, A. Evans, S. Hesh, S. Jones, J. Marshall, N. Paschalidis, Z. Peterson, J. Rodriguez, M. Rodriguez, S. Sheikh, S. Starin, E. Zesta.
+ many, many others

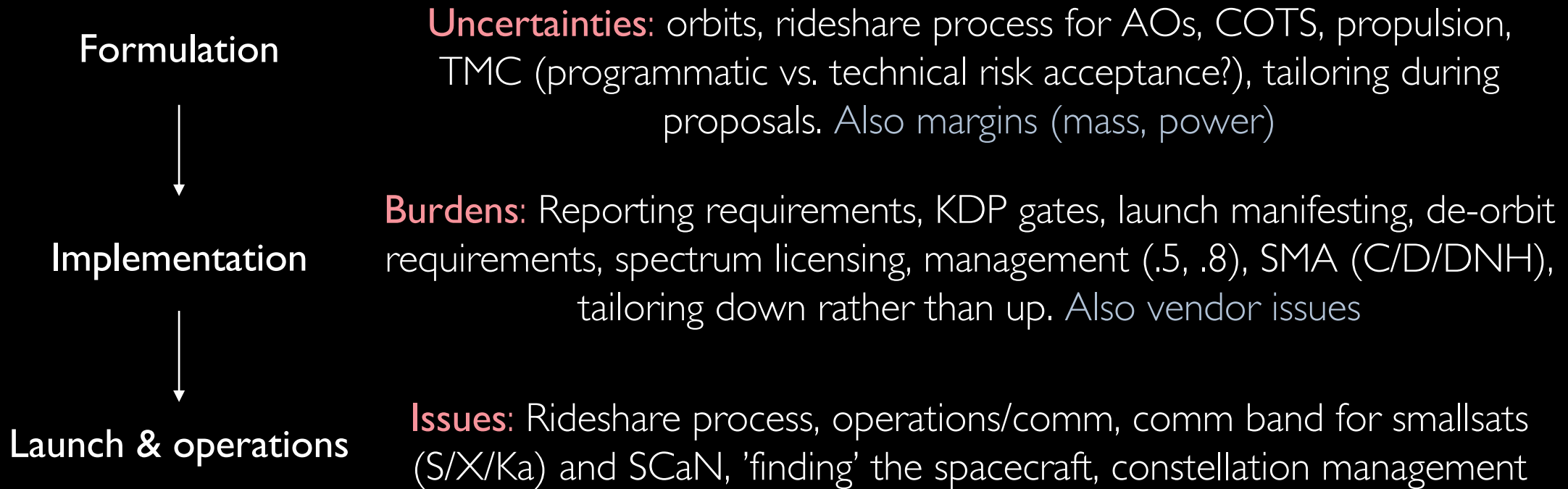


SmallSats are at the *interface* between “suborbital” and flight missions
a focal point for tension



Struggle is to balance reliability and/or resiliency against cost & schedule

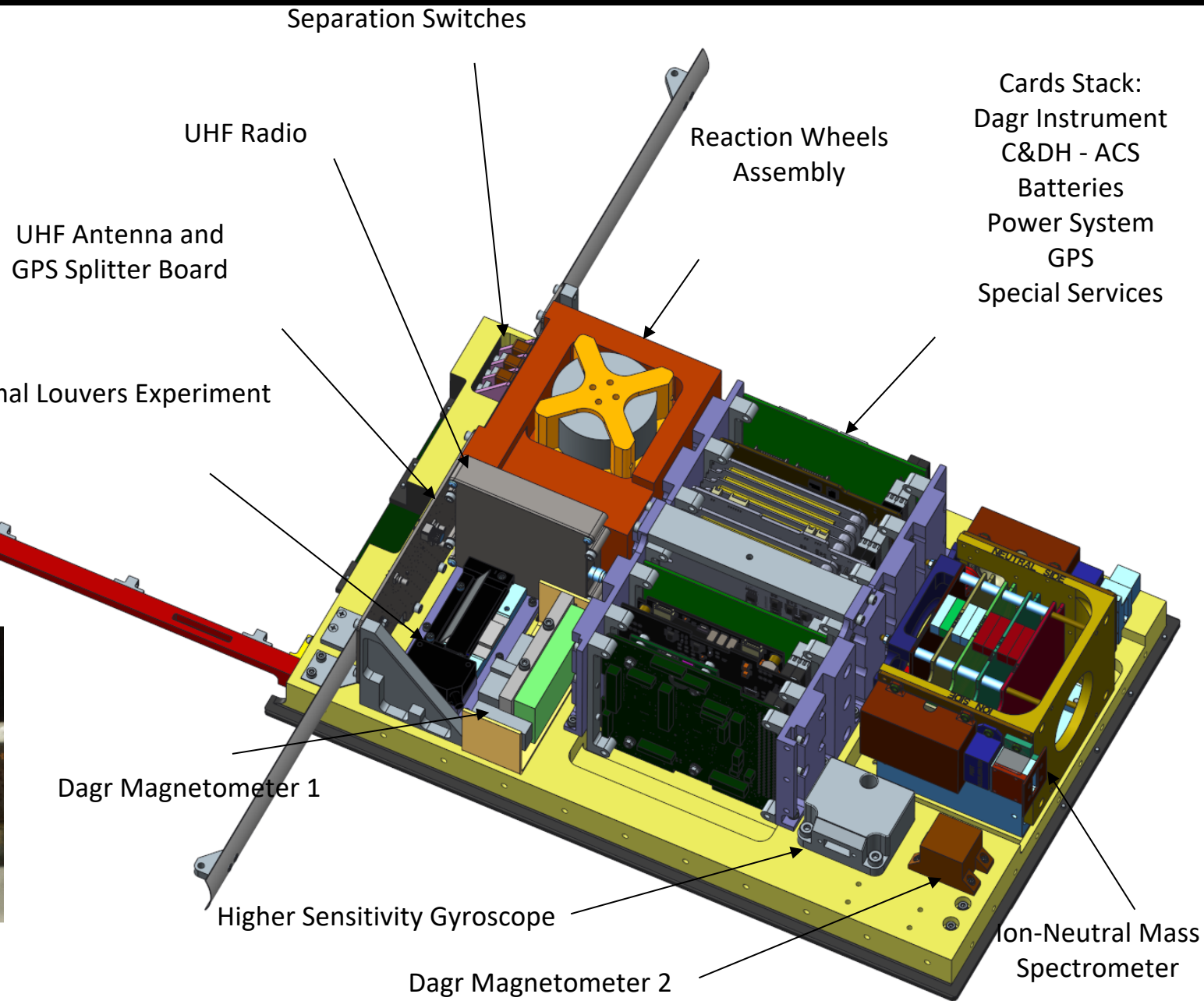
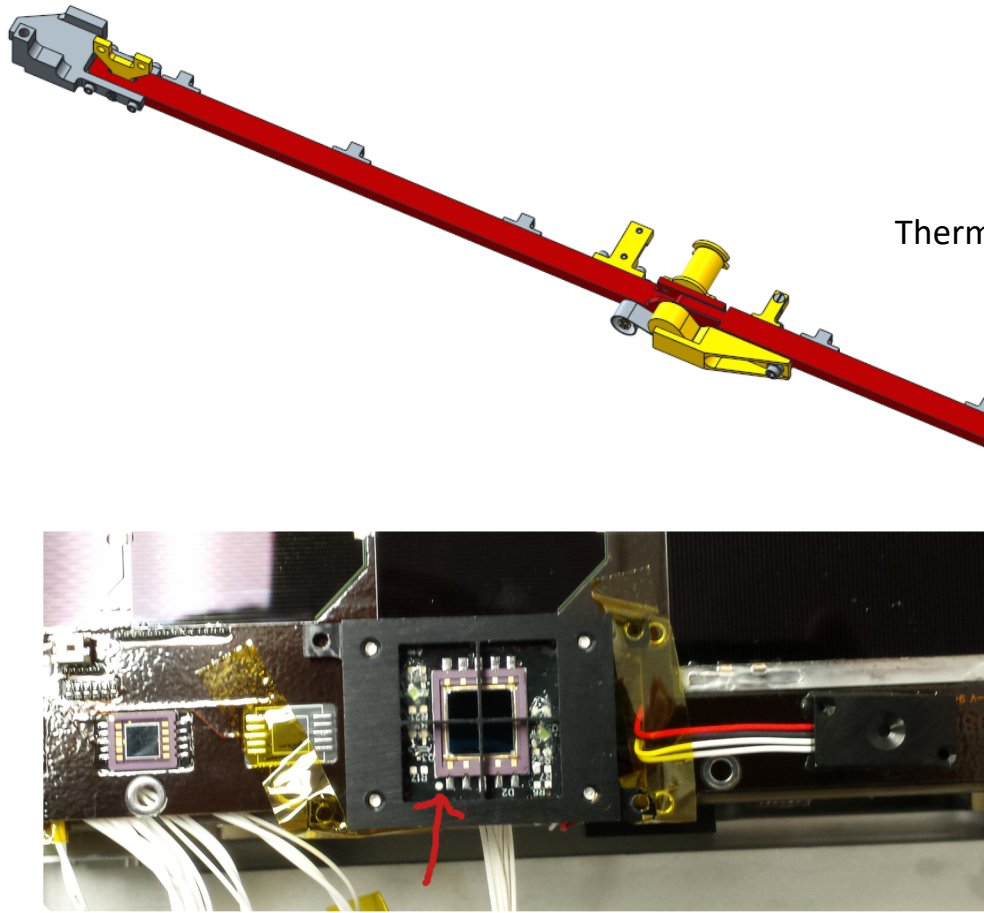
SmallSats stress every point on the implementation chain (in unique ways*)

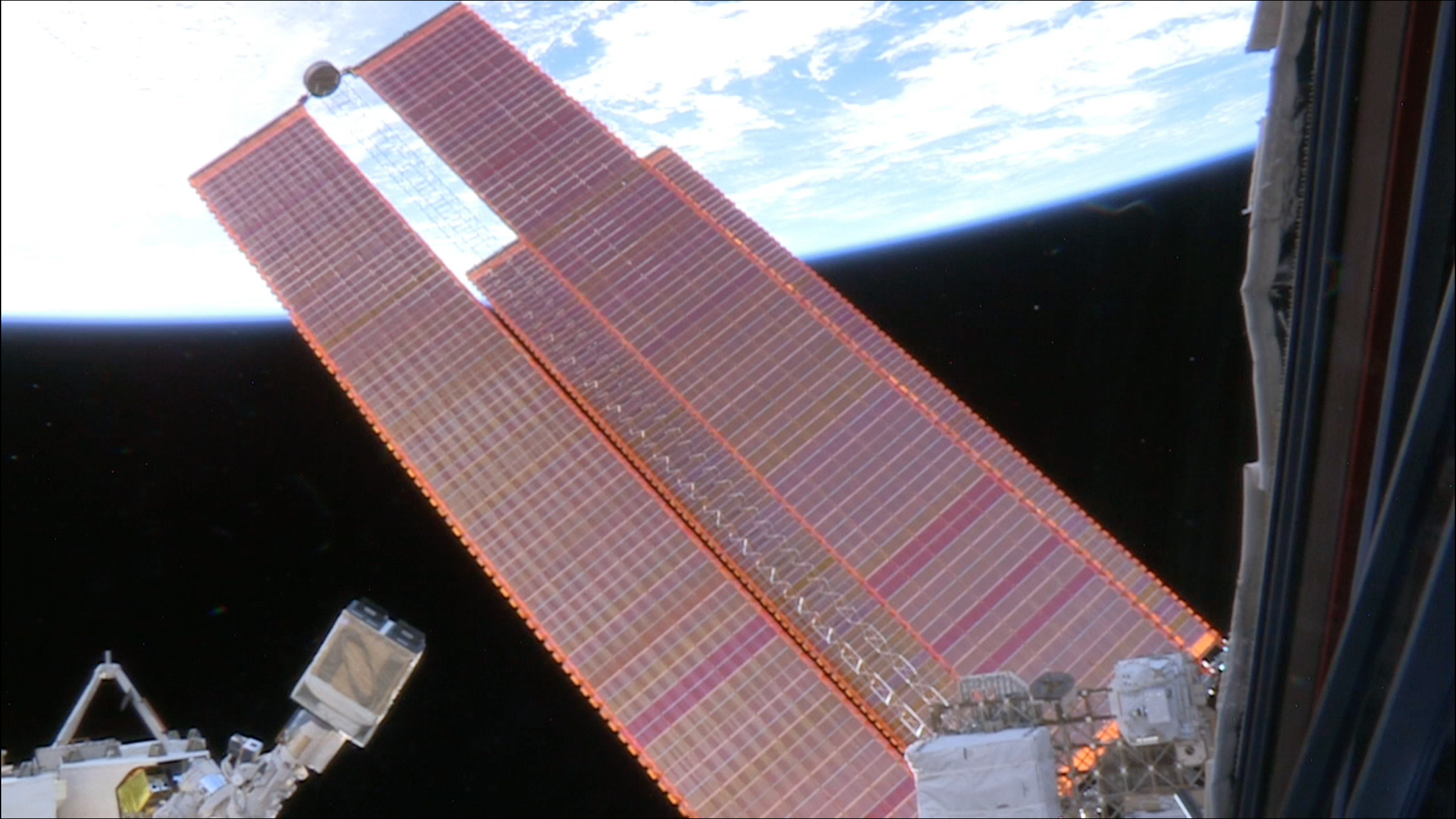


*To facilitate science investigations at **low cost**, we need to identify and then ease the stress points*

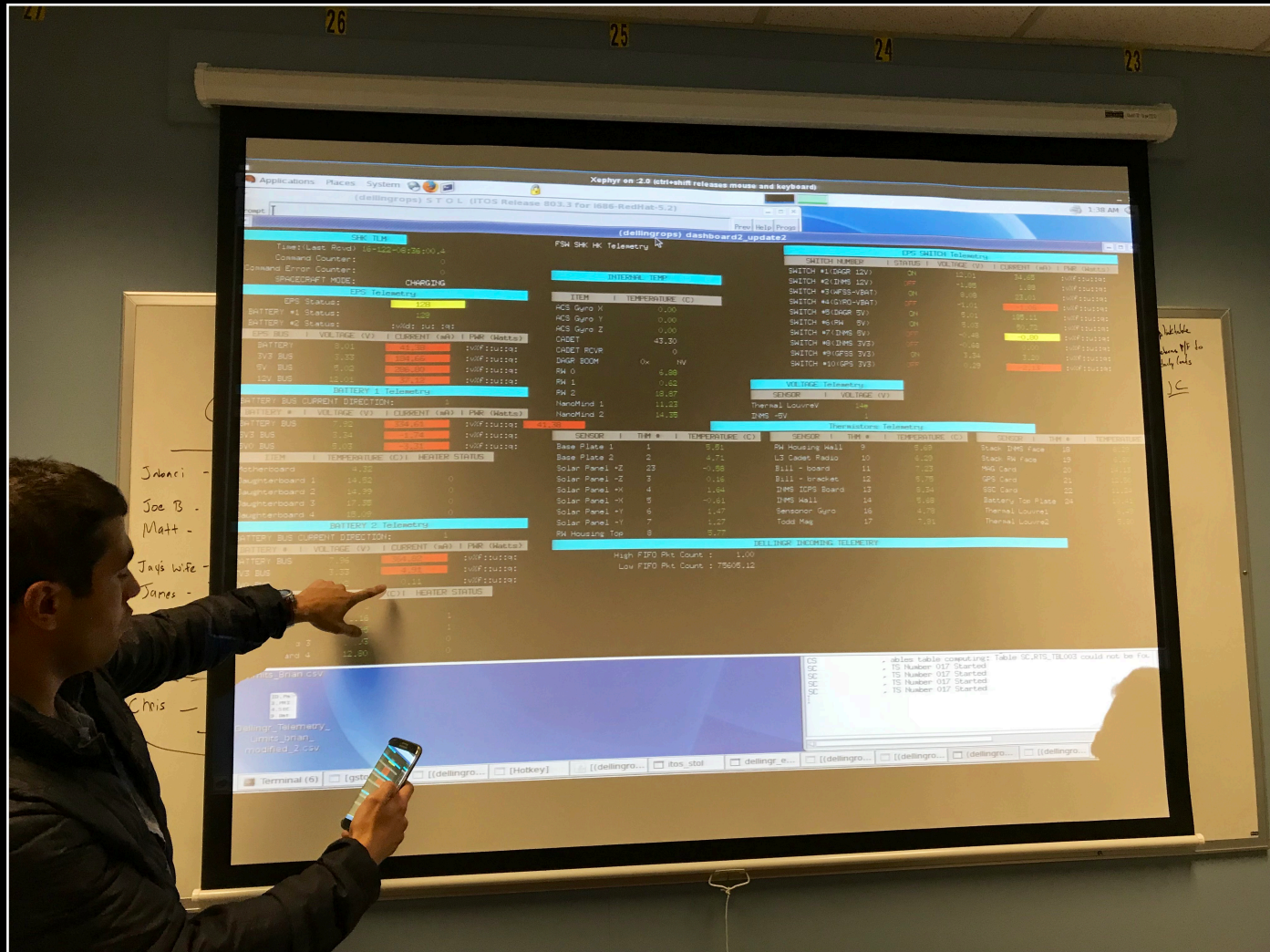
*Either with stresses unique to cubesats, or with standard stress points that, because cubesats have short development cycles and are resource constrained, burden development.

See our 2017 & 2018 SmallSat papers



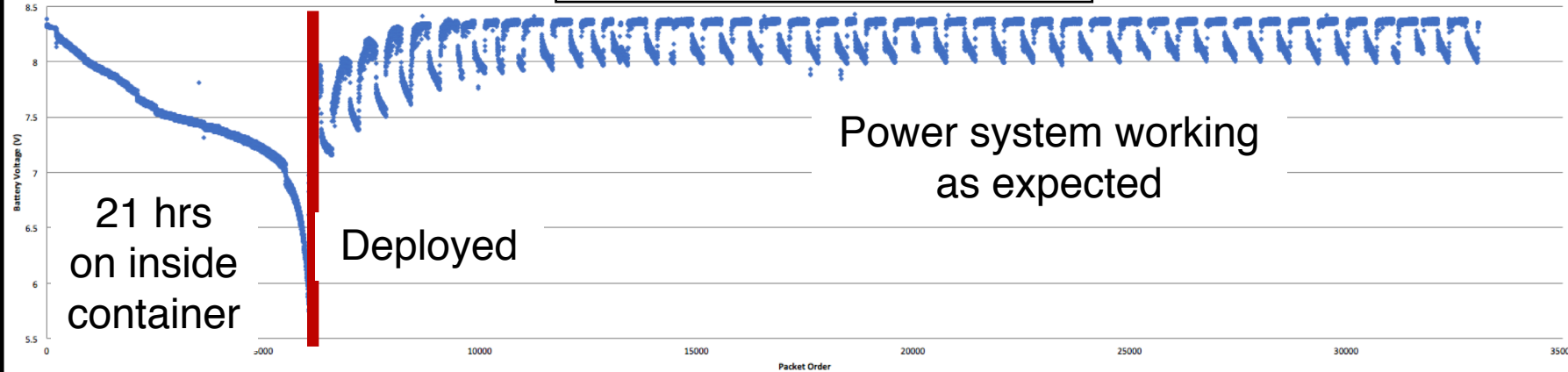


Ejected on November 20, 2017 Contact on first pass that evening

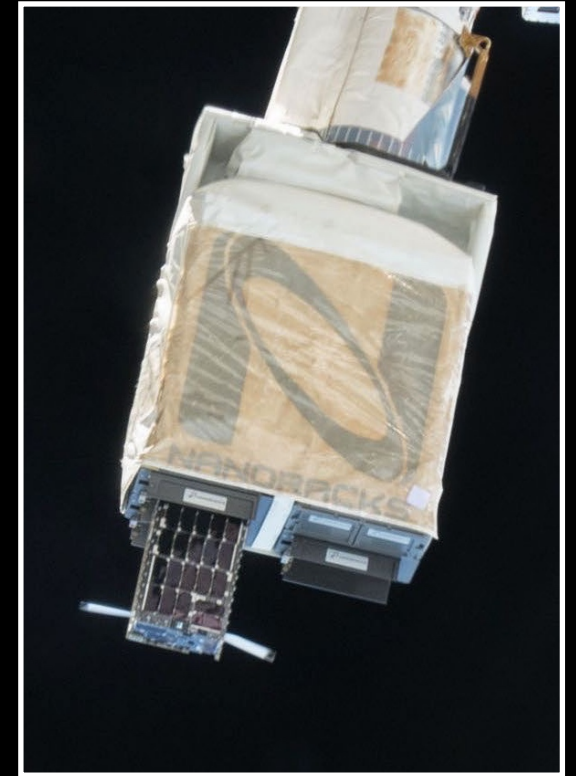


Deployment and initial checkout

Battery voltage vs. packet #

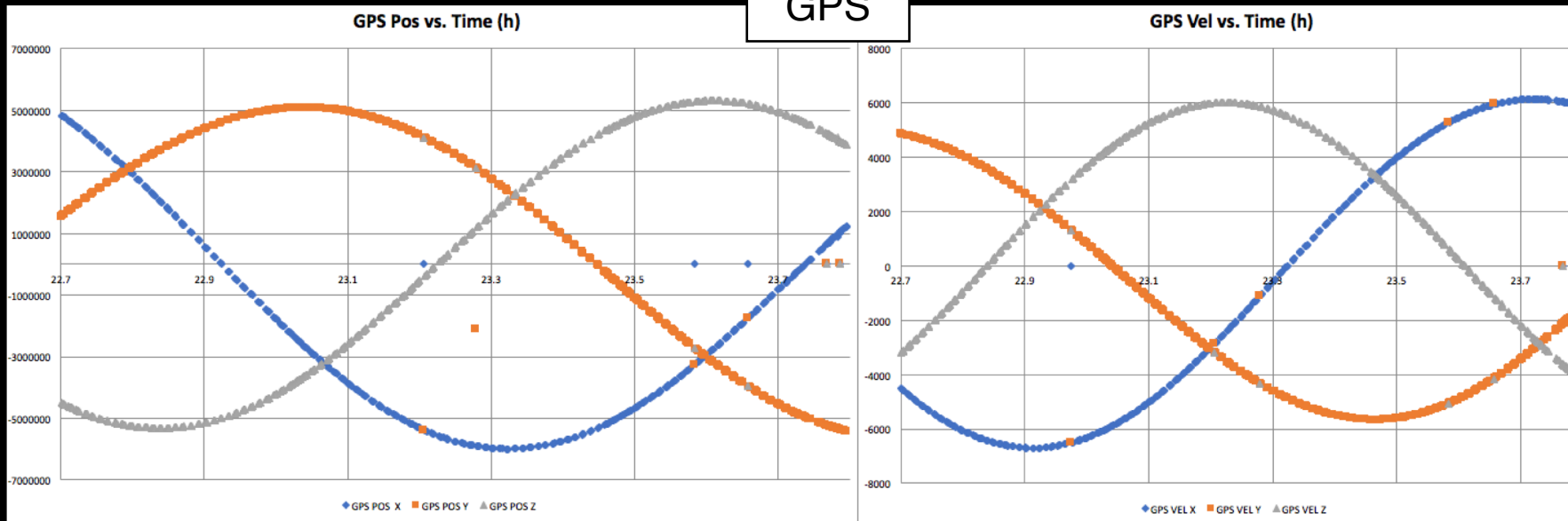


First 74 Hours (battery voltage). Satellite turned on inside deployer at unknown time for 21 hours. Dellingr restored nicely upon ejection.



We observed antenna and boom deploy in real-time

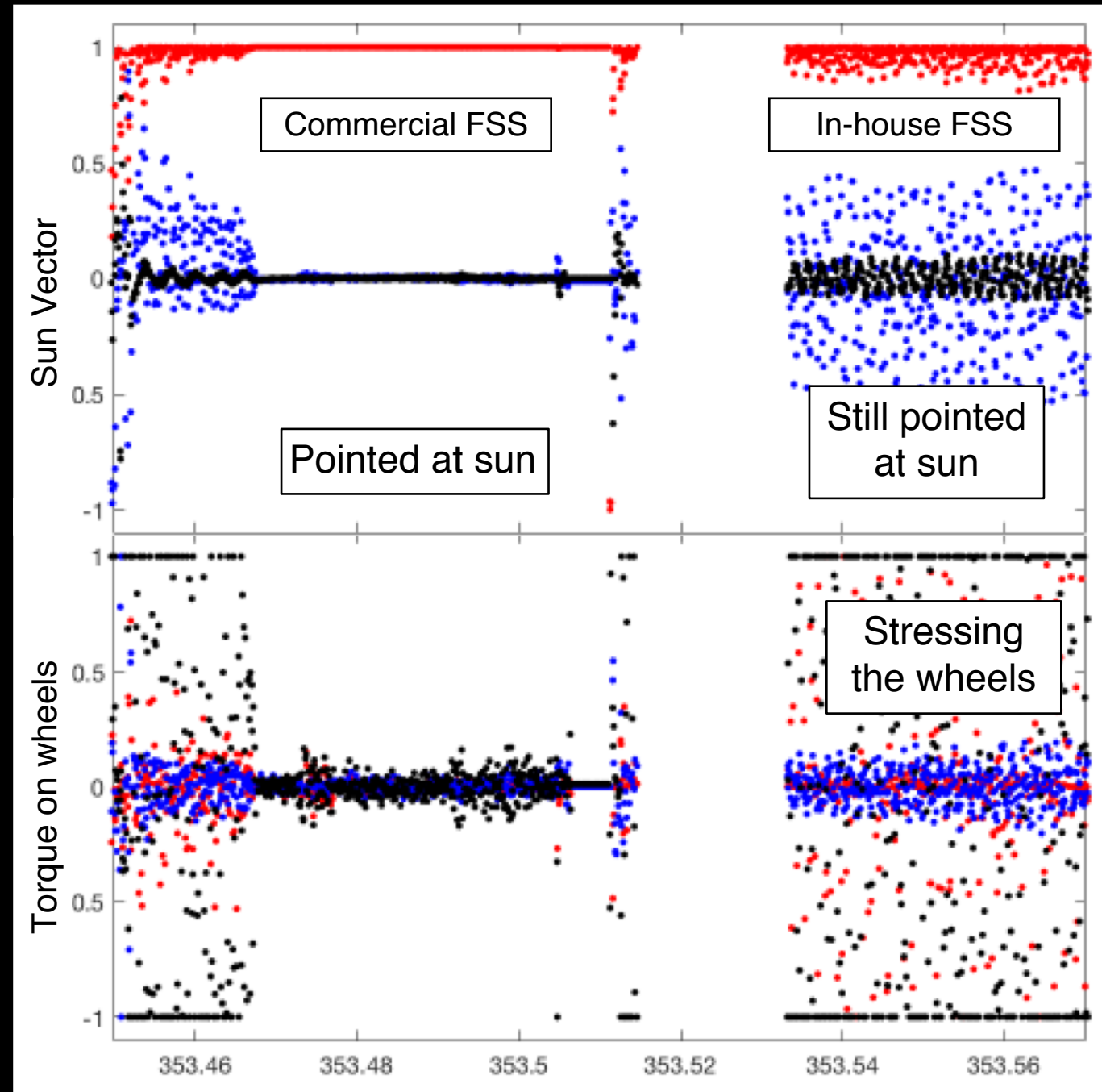
GPS



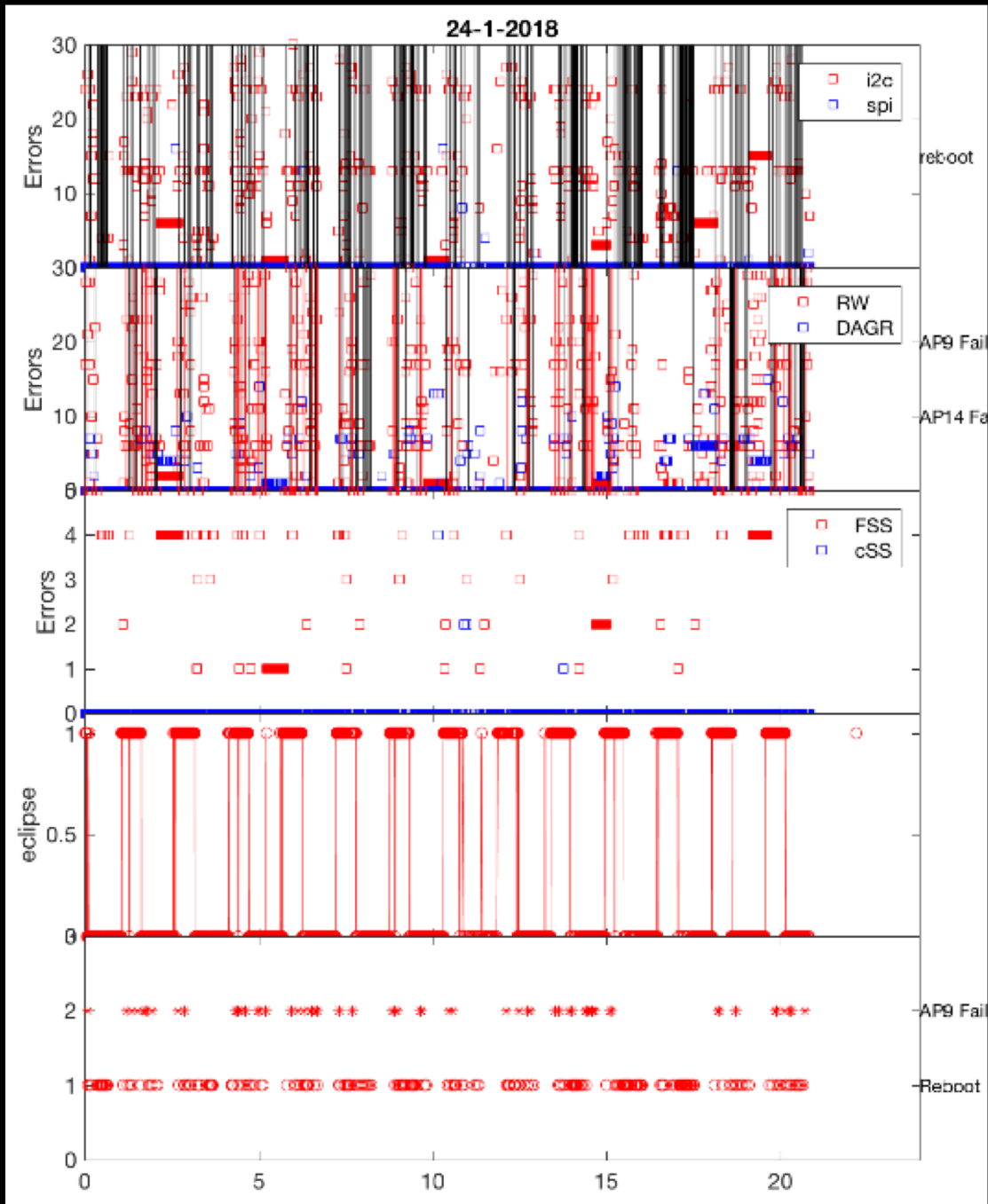
Attitude Control System starts misbehaving

Nov. 20, 2017	- Eject from ISS. All good!
Nov. 30, 2017	- Observed anomalous gyro data - Observed sun pointing inaccuracy
Dec. 19, 2017	- GPS unresponsive
Dec. 21, 2017	- In-house FSS noisy

We enter January bruised but not beaten, and had a plan to recover INMS mode



CPU having difficulty talking to subsystems



Early January, we started to see a lot of errors on the I2C bus (how the flight computer talks to various subsystems).

By late January, the reset situation had significantly worsened

January 26-February 5

```
18-031-20:23:04.000000 (2 ) (SC ) ( 73) (RTS Number 001 Started )
18-031-20:23:10.000000 (3 ) (CFE_SB ) ( 17) (Msg Limit Err,MsgId 0x18c2,pipe ACS_CMD_PIPE,sender SCH )
16-122-00:00:12.000000 (2 ) (FM ) (104) (Free Space Table verify results: good entries = 2, bad = 0, unused = 6 )
16-122-00:00:12.000000 (2 ) (FM ) ( 1) (Initialization complete: version 2.3.1.0 )
16-122-00:00:12.000000 (2 ) (FM ) (100) (Child Task initialization complete )
16-122-00:00:12.000000 (3 ) (SC ) (123) (Unbundle RTS OK: /boot/rtsb01.bin, Dest: /ram, RTS Size: 416, RTS Num: 4 )
16-122-00:00:12.000000 (3 ) (SC ) (123) (Unbundle RTS OK: /boot/rtsb02.bin, Dest: /ram, RTS Size: 416, RTS Num: 14 )
16-122-00:00:12.000000 (3 ) (SC ) (123) (Unbundle RTS OK: /boot/rtsb03.bin, Dest: /ram, RTS Size: 416, RTS Num: 16 )
16-122-00:00:12.000000 (3 ) (SC ) (123) (Unbundle RTS OK: /boot/rtsb04.bin, Dest: /ram, RTS Size: 416, RTS Num: 24 )
16-122-00:00:13.000000 (3 ) (SC ) (123) (Unbundle RTS OK: /boot/rtsb05.bin, Dest: /ram, RTS Size: 416, RTS Num: 31 )
16-122-00:00:13.000000 (3 ) (SC ) ( 21) (RTS table file load count = 32 )
16-122-00:00:13.000000 (2 ) (SC ) ( 9) (SC Initialized. Version 2.3.0.0 )
16-122-00:00:13.000000 (2 ) (LC ) ( 56) (WDT verify results: good = 15, bad = 0, unused = 49 )
16-122-00:00:14.000000 (2 ) (LC ) ( 66) (ADT verify results: good = 14, bad = 0, unused = 50 )
16-122-00:00:14.000000 (2 ) (LC ) ( 2) (LC Initialized. Version 0.0.0.0 )
16-122-00:00:16.000000 (2 ) (SEC ) ( 4) (SEC: RESET command )
16-122-00:00:16.000000 (2 ) (SEC ) ( 1) (SEC Initialized. Version 1.0.0.0 )
16-122-00:00:16.000000 (2 ) (FUL ) ( 1) (FUL App Initialized. Version 1.0.0.0 )
16-122-00:00:16.000000 (2 ) (FDL ) ( 1) (FDL App Initialized. Version 1.0.0.0 )
16-122-00:00:16.000000 (2 ) (MM ) ( 1) (MM Initialized. Version 0.0.0.0 )
16-122-00:00:16.000000 (2 ) (CS ) (144) (CS Eeprom Table verification results: good = 8, bad = 0, unused = 8 )
16-122-00:00:16.000000 (2 ) (CS ) (143) (CS Memory Table verification results: good = 0, bad = 0, unused = 16 )
16-122-00:00:16.000000 (2 ) (CS ) (107) (CS Memory Table: No valid entries in the table )
16-122-00:00:16.000000 (2 ) (CS ) (142) (CS Apps Table verification results: good = 0, bad = 0, unused = 24 )
16-122-00:00:17.000000 (2 ) (CS ) (108) (CS Apps Table: No valid entries in the table )
16-122-00:00:17.000000 (2 ) (CS ) (139) (CS Tables Table verification results: good = 46, bad = 0, unused = 26 )
16-122-00:00:17.000000 (2 ) (CS ) ( 1) (CS Initialized. Version 0.0.0.0 )
16-122-00:00:17.000000 (2 ) (MD ) ( 7) (Dwell Tables Recovered: 0, Dwell Tables Initialized: 4 )
18-031-20:24:08.000000 (2 ) (SC ) ( 73) (RTS Number 001 Started )
18-031-20:24:14.000000 (3 ) (CFE_SB ) ( 17) (Msg Limit Err,MsgId 0x18c2,pipe ACS_CMD_PIPE,sender SCH )
16-122-00:00:07.000000 (2 ) (CADET ) ( 1) (L386 CADET: App Initialized using DEFAULTS. Version 1.0.0.0 )
```

Crash!

Reboot

Crash!

January 26, Friday. Last contact with flight computer.

January 29, Monday, windy.

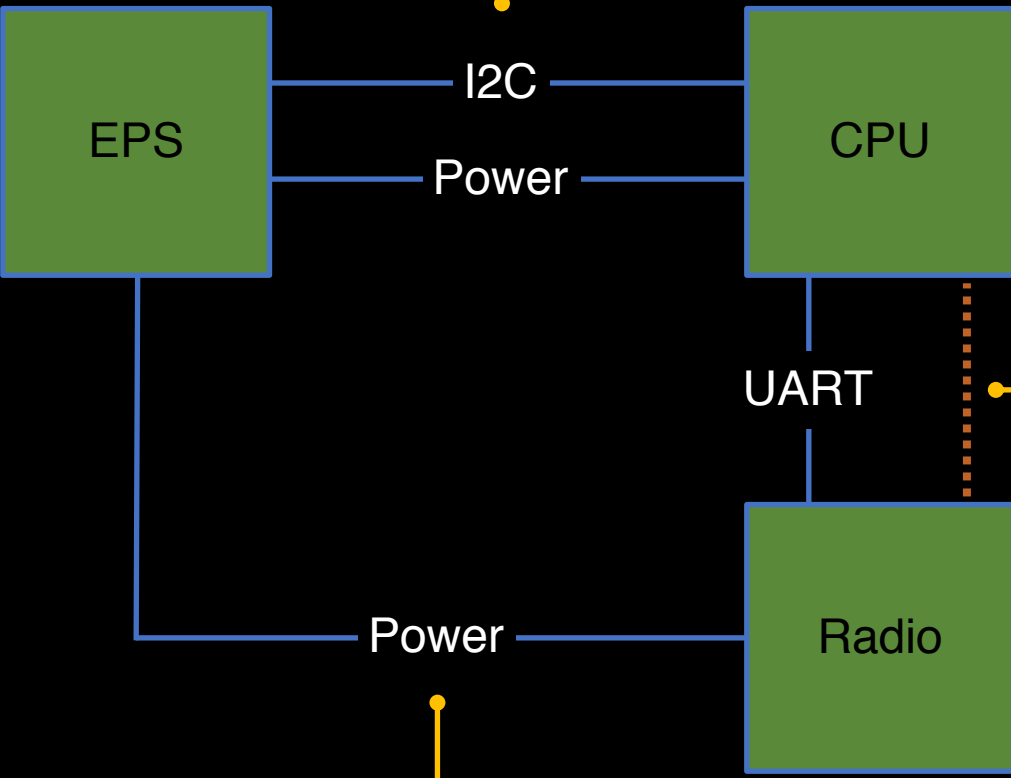
January 30, Tuesday, windy.

January 31st contact through radio, but couldn't talk to spacecraft.

From January 26 - February 5, >13,000 resets. Reboot every 64 seconds, continuously, for 10 days.

“We just confirm Dellinger is back to business”

EPS has a 4 minute "watchdog"



Radio powered independently

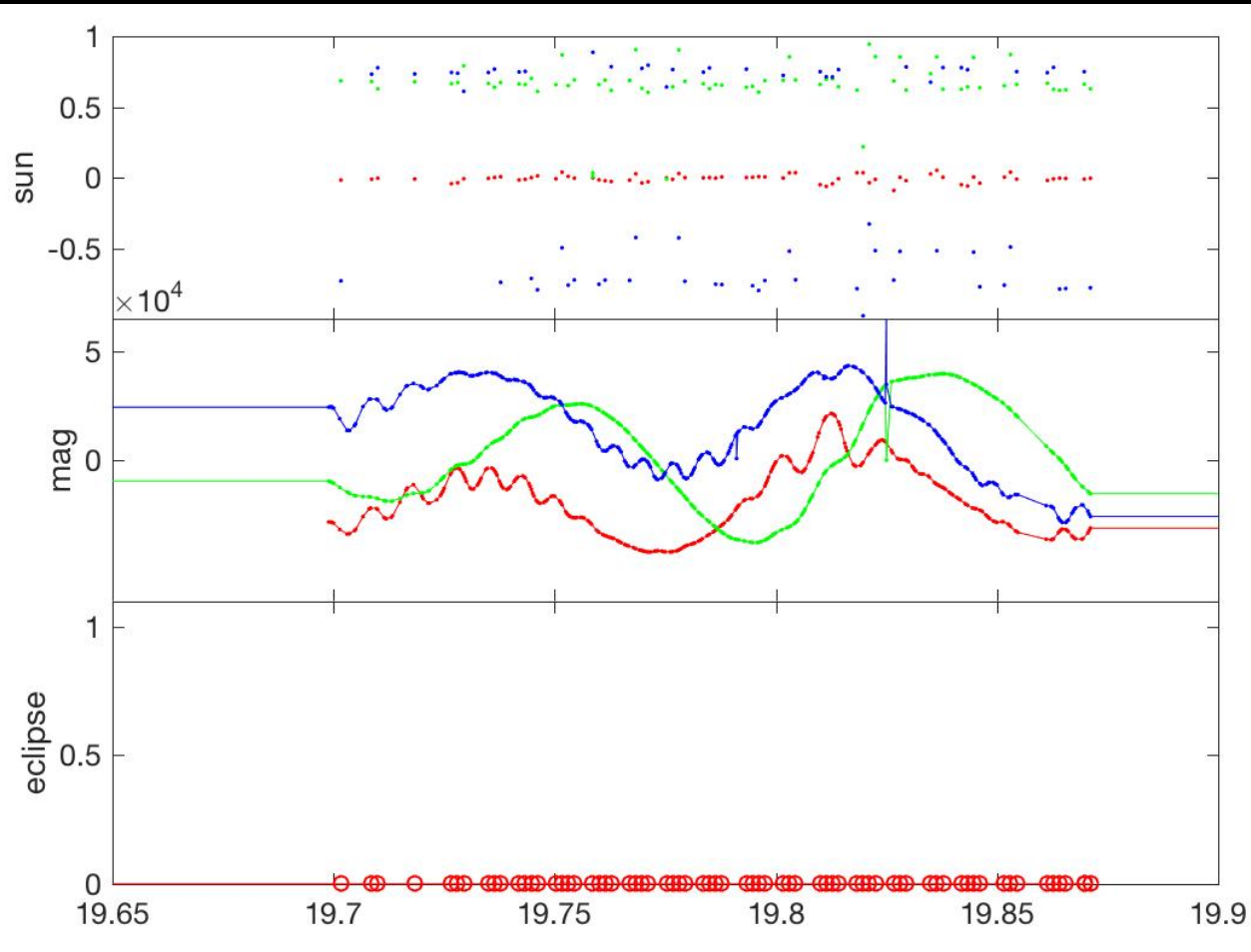
Radio has a CPU reset button



Team sent a CPU reset command for the entire duration of the pass - ~7 minutes. Lack of I2C activity triggered an EPS reset Contact next pass. Turned off the wheels. Next pass confirmed no resets.

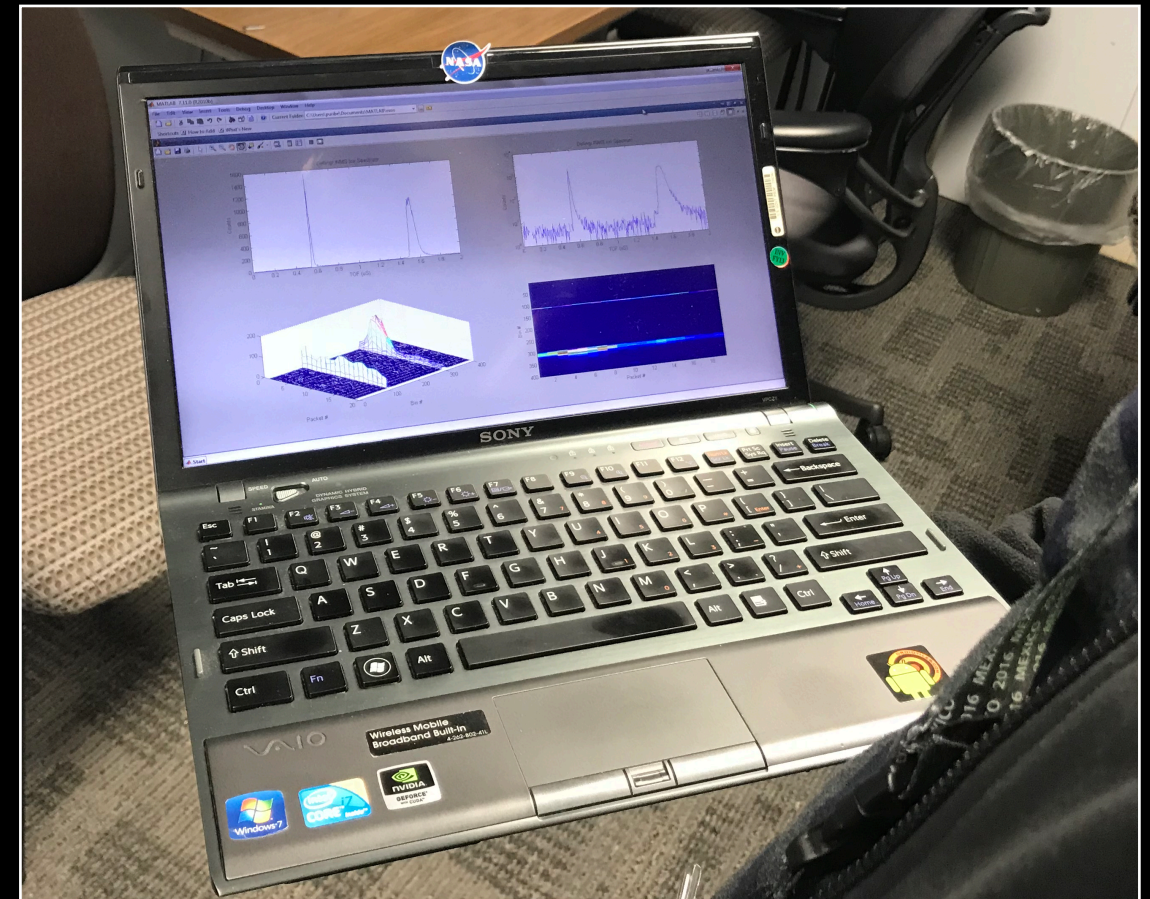
917 pm February 6:

9 minutes of data during the Feb 6 pass
after recovery

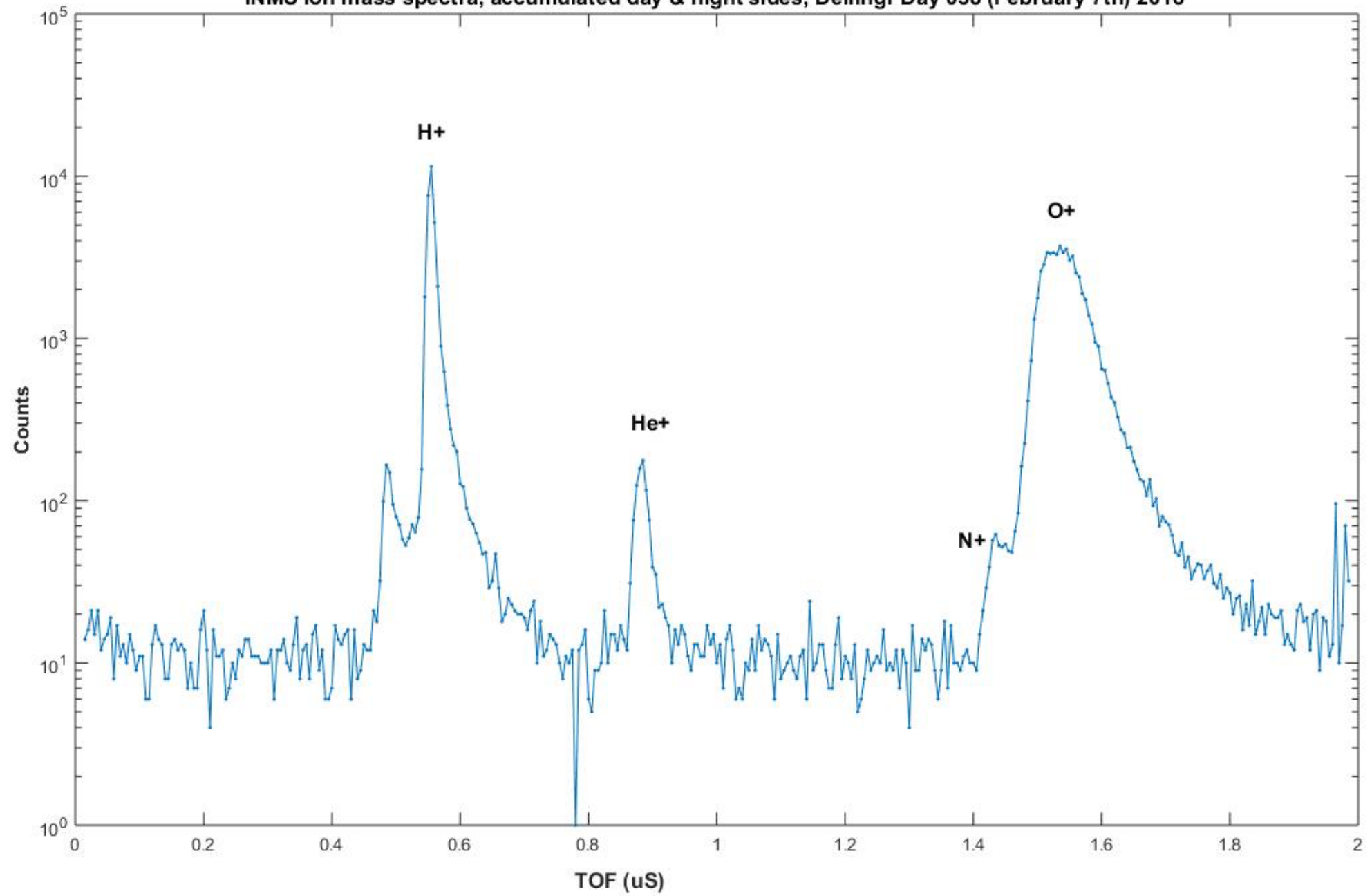


“Victory. Behnam was able to turn on INMS in the ION mode. We had no resets between the last pass and this one.”

February 9. Data!



INMS ion mass spectra, accumulated day & night sides, Dellinger Day 038 (February 7th) 2018

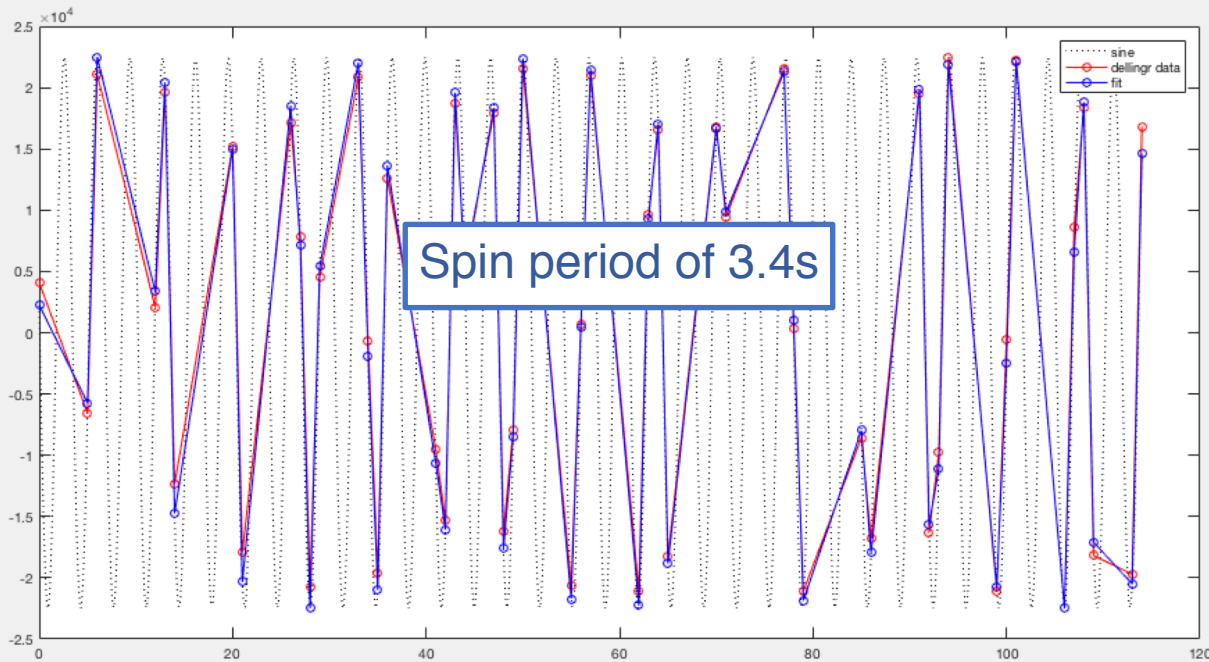


The best laid plans, and all that

We were able to upload some software patches to keep the RW off/on. We turned on INMS neutral mode (could not download). Had plans for larger updates.

But ...

ACS system designed for 40°/s. Dellingr is spinning at 120°/s



2 minutes of data from March 16th

As of 7:18 am March 16th:

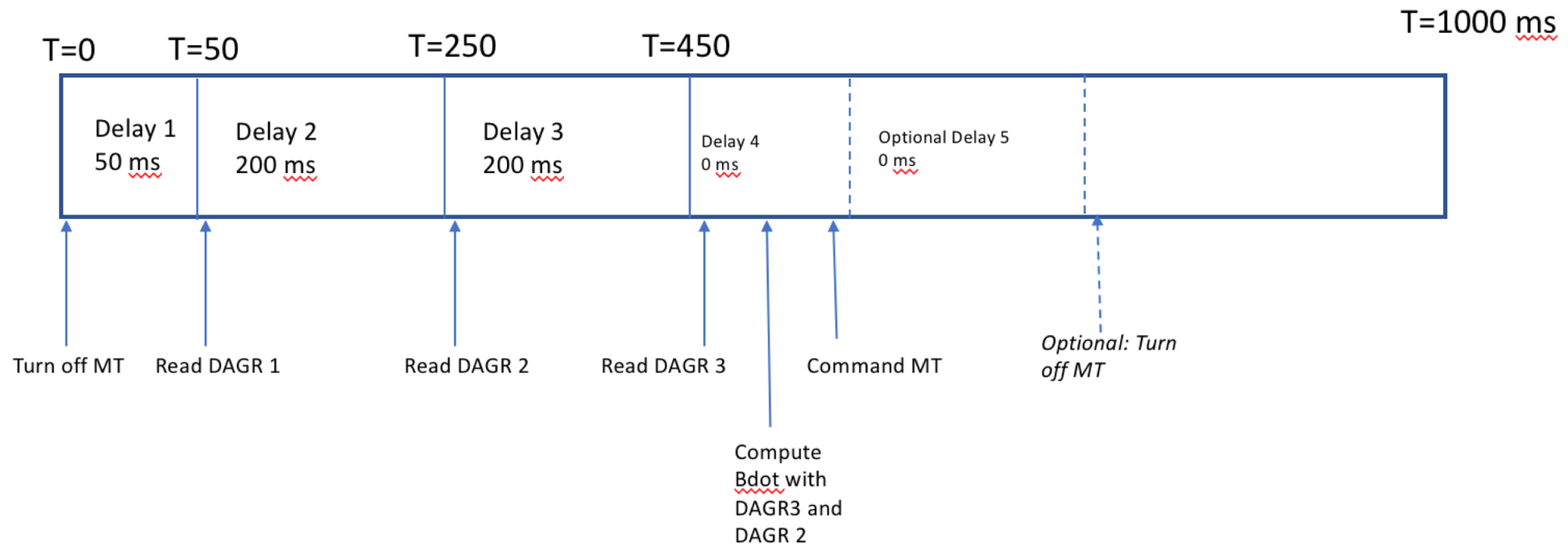
Dellingr is spinning too fast... is not power positive... communication is weak... we have 1 pass/day... and the resets are starting again... for a different reason...

Despin via bdot

V1 uploaded from 3/29-4/5, didn't work

V2 uploaded from 4/12-4/17, partial success

V3 uploaded from 5/1-ongoing.



Issues:

WFF developed FSS is very noisy, despite ground testing
GSP failed after 4 weeks, despite ground testing
Cannot run onboard ephemeris due to underpowered CPU
ACS not designed for $>\sim 20^\circ/\text{second}$ spin rate
IMU not providing clean data since launch (likely software bug)
Extensive I2c errors for much of January related to reaction wheels
Faced vendor and technical issues with EPS, batteries, and radio

Things that increased reliability and/or resiliency:

Multiple FSS
In-house ACS
Core Flight Software
Flatsat during operations — didn't have it during development
Experienced engineers
25 hour reset
Ability to talk directly to radio

Things that would be nice:

Power reset capability (a backdoor)
Better uplink & full duplex radio
Ability to turn off and isolate subsystems (we mostly have this)
A full time team & trending

Other things that happened:

Cadet radio data deleted. Twice
Cadet radio froze. 25 hour reset cleared it.

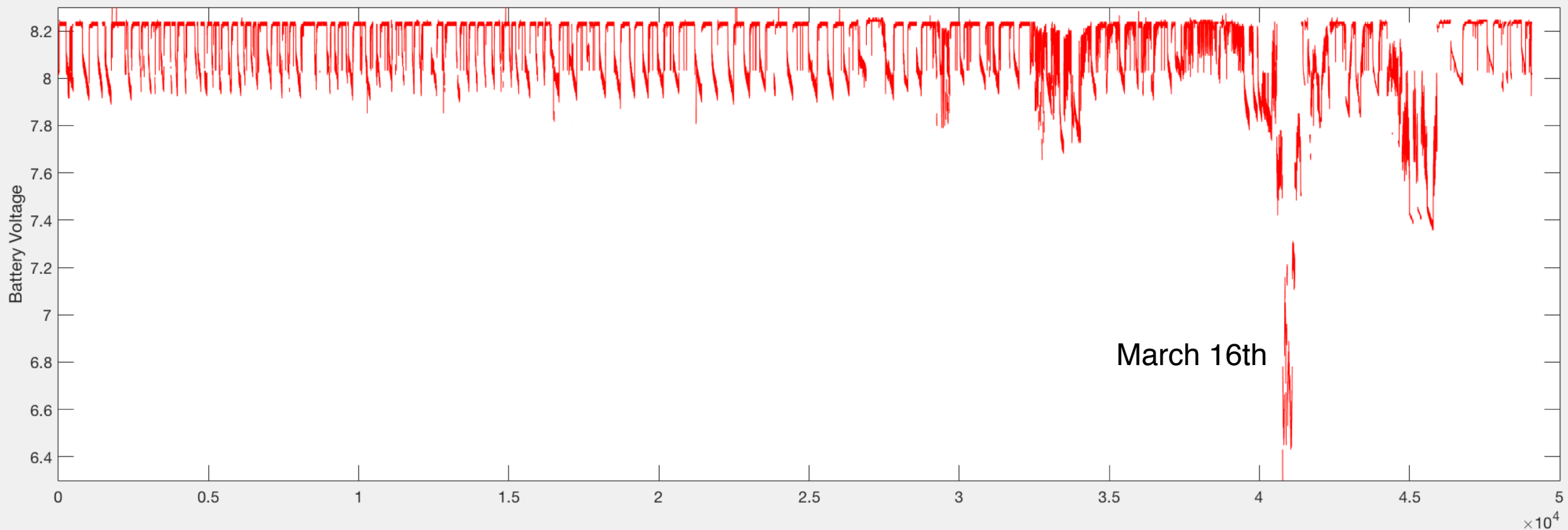
Conclusions

Dellingr relied on “Build, test, fix”. That provided level of confidence s/c would work on orbit.

GSP failure and I2C issues were not observed during testing.

Given price point and risk posture, Dellingr landed in the right place. A small change of luck and we'd have a fully successful *science* mission (we still might!).

Battery voltage from January 1, 2018 to today



Since then, things have improved:
Power is healthy.
Resets were EPS shutting off at 6.2 V
Spin period is another story....

Take-aways

Lessons Learned

- FSW reuse and core-flight are key to keeping costs down, and need a flatsat for software development work
- We tested, but still suffered a critical failure (GPS)
- Harness Mockup – A 3D printed or similar physical model is needed for wire harness development
- Dellinger invested in detailed I&T procedures and documentation as part of the pathfinder (“build, test, fix”) approach
- Component level performance tests should be completed before integration, as cubesat hardware is less mature
- Dellinger wasn’t “reliable”, but is “resilient”

The future for GSFC

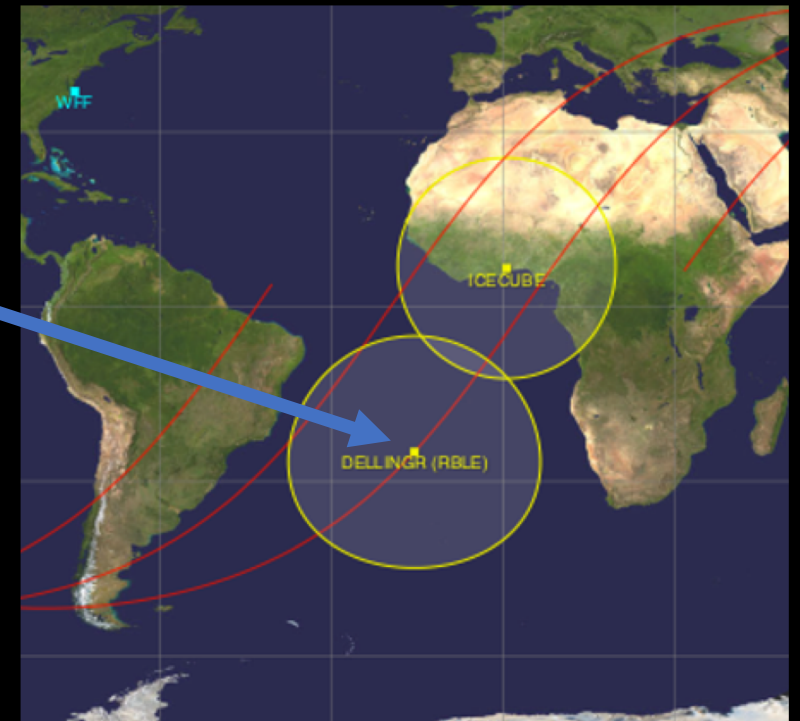
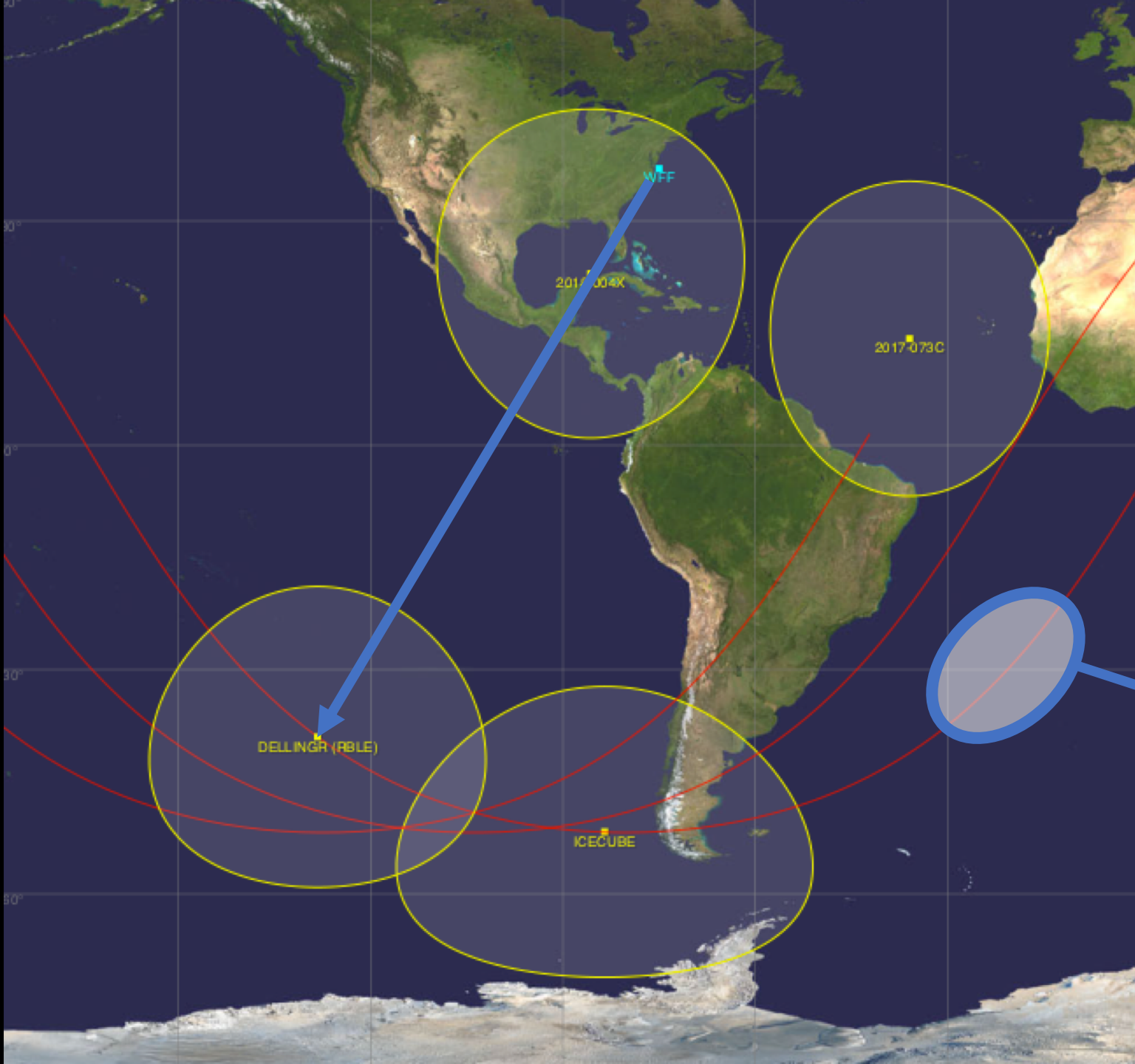
- Future focus is on rad-hard, high performance SmallSats for Decadal Survey science (GTOSat is pathfinder).
- Dellinger experience and capabilities leveraged for GSFC SmallSat science missions - changing the culture.



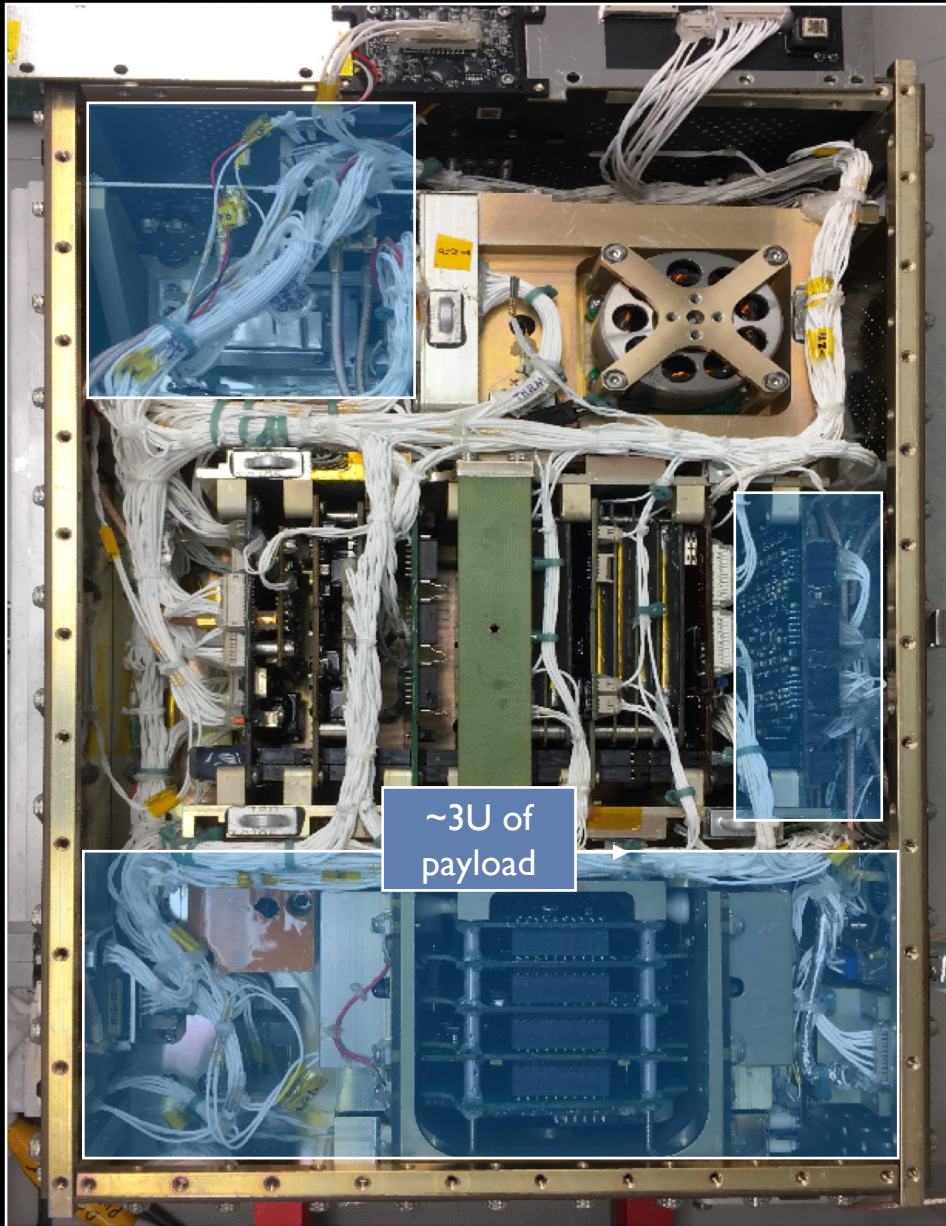
Proudly flying the Dellinger flag

January 25

“Due to some unknown reason
all LO-FIFO data deleted around
8 hours ago.”



Dellingr overview



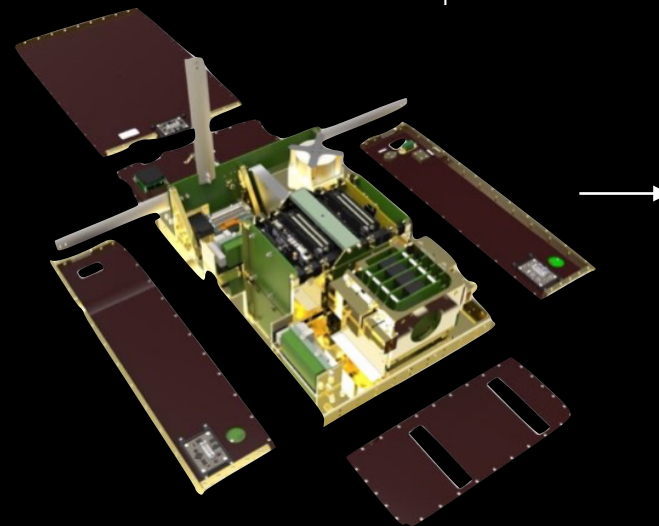
- **COTS:**

- Flight computer, EPS, batteries, UHF radio, reaction wheels, GPS, IMU, FSS, camera, CSS

- **In-house**

- Special Services Card, solar panels, UHF antenna, FSS, release mechanisms, magnetometer boom, GPS splitter & antenna, flight software, instruments

baseplate facilitated integration

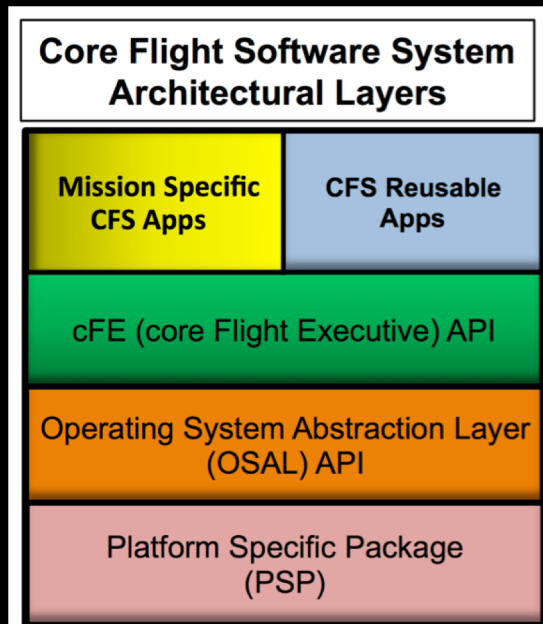


Flight Software, C&DH, electrical bus



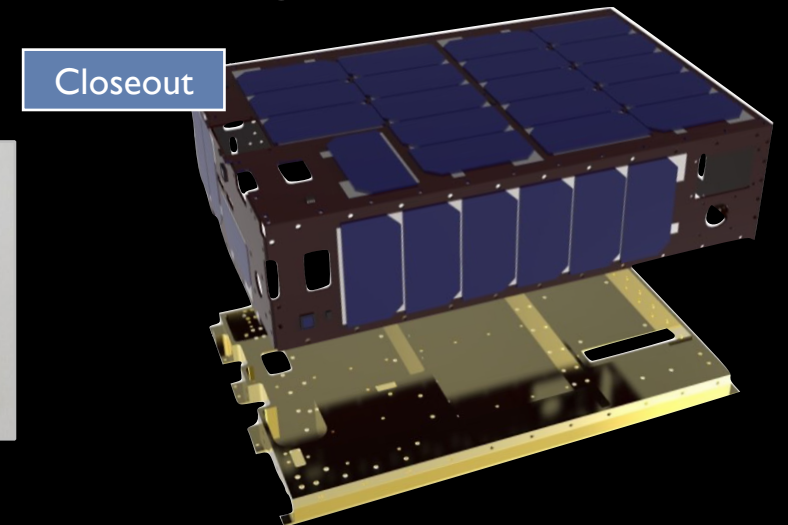
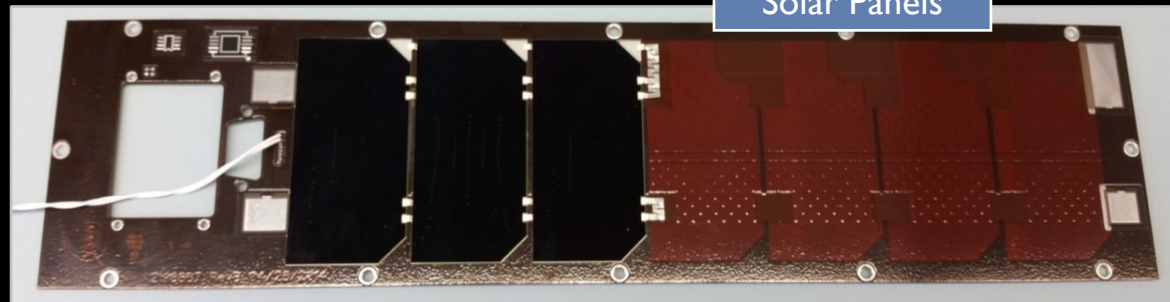
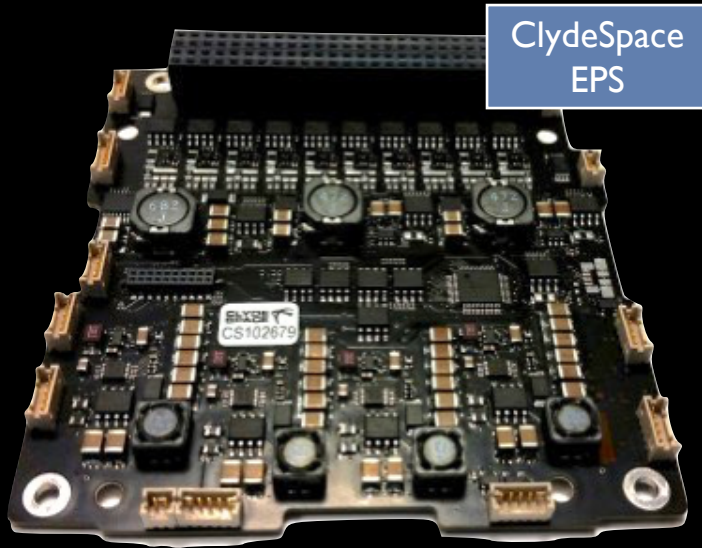
Gomspace
C&DH

- **Gomspace Nanomind for flight computer**
 - 40 MHz Amtel ARM, 2 MB SRAM, 8 MB flash
 - FreeRTOS
- **Core Flight Software**
 - Open source framework, available via SourceForge
 - Used on LRO, GPM, MMS, etc.
 - Abstracts software architecture from hardware
 - Publish/subscribe messaging framework, event reporting, FDC, scheduling
- **Mission specific applications**
 - ACS, spacecraft housekeeping, instrument interface, and radio control
- **NanoMind included I2C, SPI and 3 UARTS**
 - Supplemented on SSC with A2D, general purpose I/O pins, and additional UARTS

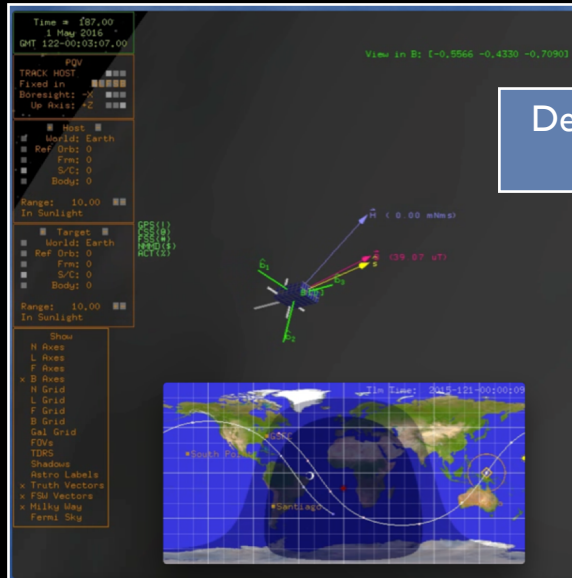


Power

- ClydeSpace 3rd generation EPS
- Two ClydeSpace 40 Wh ISS approved batteries
 - Originally three 30 Wh; did not meet ISS requirements
- In-house solar panels
 - SolAero ZTJ Triple Junction CIC cells (GPM spares)
 - Mounted to PCB substrate with double-sided kapton tape (thanks Aerospace!)
 - Embedded torquers for momentum dumping
 - Formed closeout panels
- SSC added fuses, switches and current regulation for release mechanisms

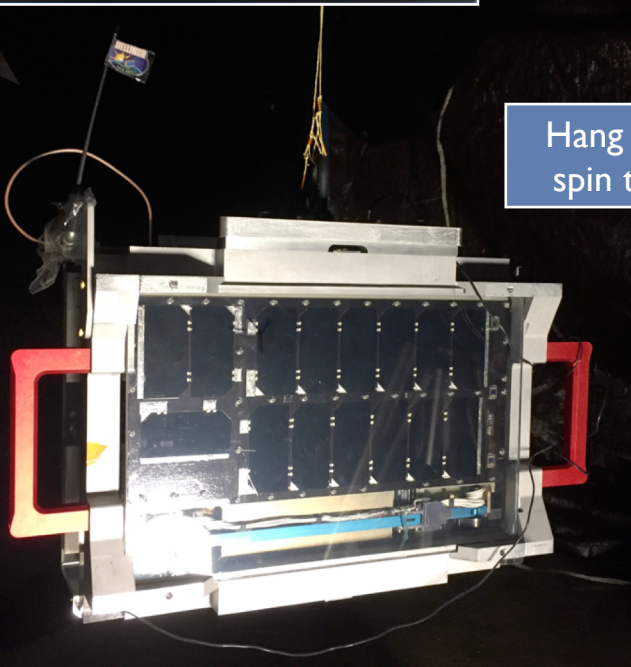


Attitude Determination and Control System

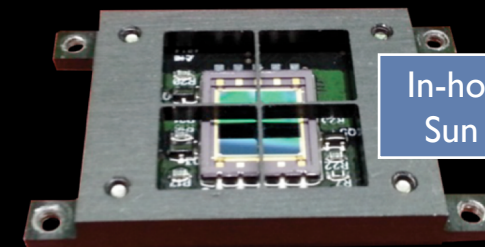


Dellgr in
"42"

- Sensors - Combination of magnetometer, sun sensors (fine and coarse), and IMU
- Actuators - Reaction wheels and torquers for momentum control
- ACS software developed in-house, based off Solar Dynamics Observatory (SDO)
 - Software written as cFS apps
- Verified in 42 and with hang and spin test
 - 42 simulates all 6 DoF, all sensors and actuators, including the reaction wheels and the torquers

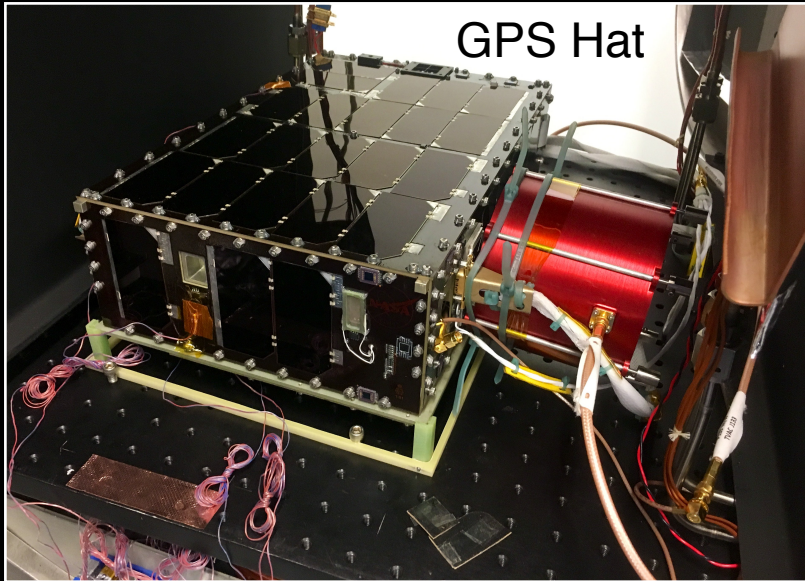


Hang and
spin test



In-house Fine
Sun Sensor

Testing



- **Initial environmental**
 - TVAC bakeout, 8 TVAC cycles, thermal balance, day in life, random vibrate (9.47 GRMS) & sine-burst (14.5g)
- **Magnetics**
 - Calibrated magnetometers and characterized spacecraft interference; validated phasing
- **End-to-end comm at WFF**
 - L3 Cadet, half-duplex up to 3 Mbps downlink
 - SDL TITAN ground software
- **ITOS (I&T and MOC)**
 - Enables "Test as you fly"
 - Developed for original SMEX program
 - Commands initiated at MOC (Greenbelt), sent to WFF
- **Final NR vibrate, 2 cycle TVac, regression testing, final mag cal. delivery May 31**

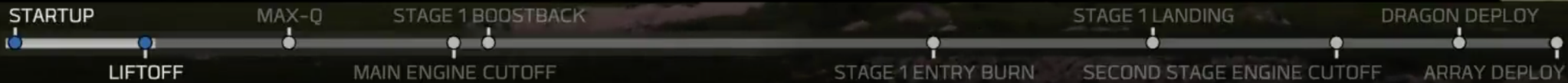


August 14, 2017



STAGE 1		TELEMETRY	
SPEED		ALTITUDE	
00097 km/h		00.1 km	
UPCOMING		MAX-Q	
THE HOLDDOWN CLAMPS HAVE RELEASED FALCON 9 AND WE HAVE BEGUN OUR FLIGHT TO THE INTERNATIONAL SPACE STATION			

LAUNCH: CRS-12

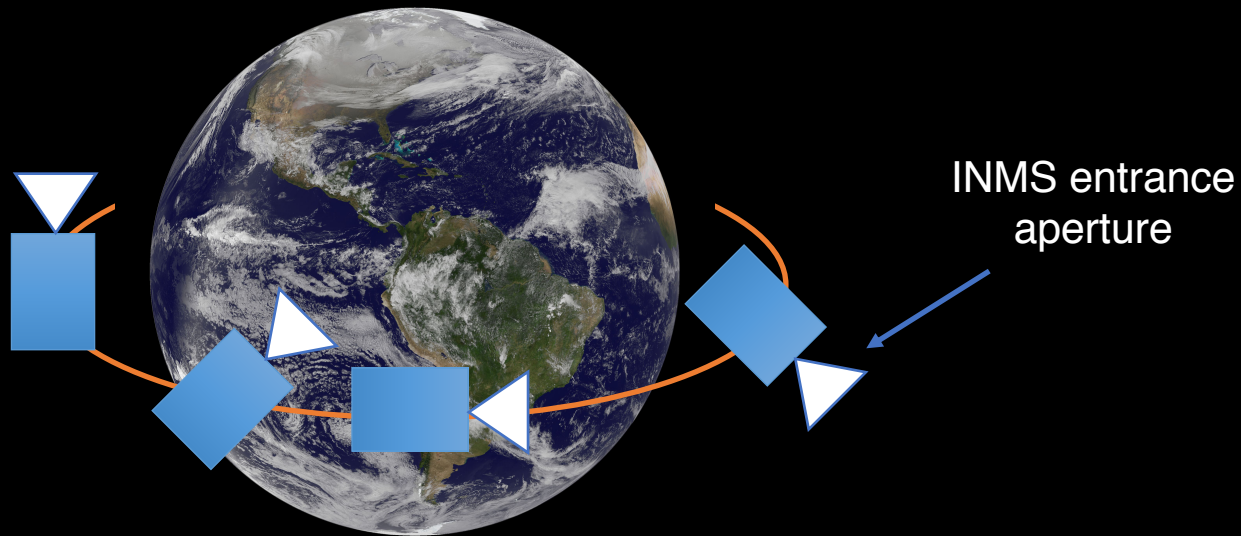


SPACEX

Ion Neutral Mass Spectrometer

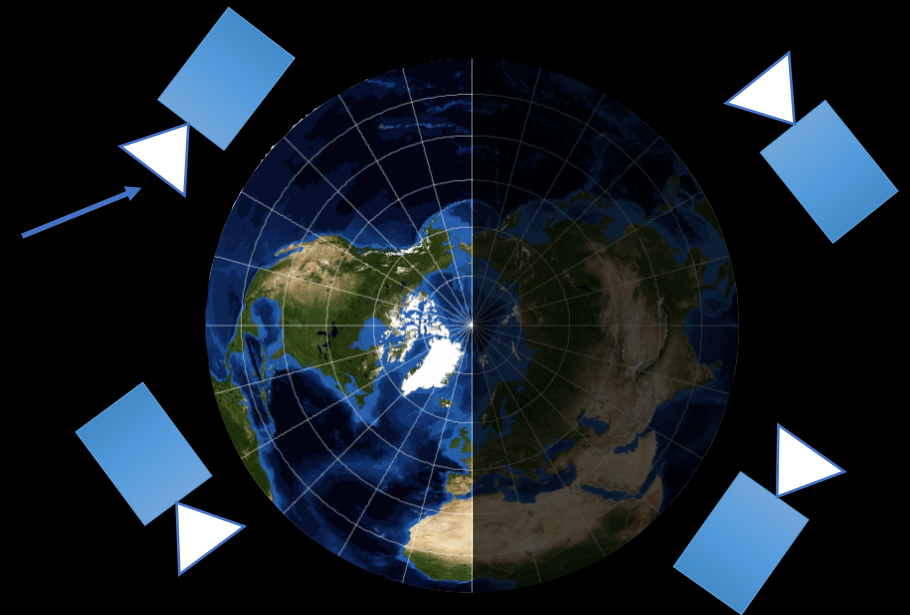
- A key instrument for GDC, and *highest priority for Dellingr operations*
- Required several weeks of outgassing before turning on high voltage (could not turn on in early mission)
- Jan 10, 2018 turned on and verified nominal voltages and currents
- **Loss of GPS** requires software patch to recover INMS science mode

Short term solution




Use INMS in sun-point mode and spin through ram on dayside (requires several uploads)

Long term solution



Use INMS as ram-sensor or run ephemeris propagator on orbit



48x5=240 bytes/pass

Whan that aprill with his shoures soote The drog
hte of march hath perced to the roote, And bathe
d every veyne in swich licour Of which vertu eng
endred is the flour;Whan zepirus eek with his s
weete breeth Inspired hath in every holt and hee

Whan that aprill with his shoures soote
The droghte of march hath perced to the roote,
And bathed every veyne in swich licour
Of which vertu engendred is the flour;
Whan zephirus eek with his sweete
breeth Inspired hath in every holt and hee

— 48x5=240 bytes/pass

th Tendre croppes, and the yonge sonne
Hath in the ram his halve cours yronne,
And smale foweles maken melodye,
That slepen al the nyght with open ye
(so priketh hem nature in hir corages);
Thanne longen folk to goon on pilgrimages,
And palm

— 48x5=240 bytes/pass

eres for to seken straunge strondes,
To ferne halwes, kowthe in sondry londes;
And specially from every shires ende
Of engelond to caunterbury they wende,
The hooly blisful martir for to seke,
That hem hath holpen whan that they were seeke.

— 48x5=240 bytes/pass

ifil that in that seson on a day,
In southwerk at the tabard as I lay Redy
to wenden on my pilgrimage. To caunterbury
with ful devout corage, At nyght was come
into that hostelrye Wel nyne and twenty
in a compaignye, Of sondry folk, by advent

— 48x5=240 bytes/pass

ure yfalle In felaweshipe, and pilgrimes were
they alle, That toward caunterbury wolden ryde.
The chambres and the stables weren wyde,
And wel were esed atte beste. And shortly,
whan the sonne was to reste, So hadde I
spoken with hem ev

— 48x5=240 bytes/pass

We need *at least* 5 perfect passes to get 1000 bytes uploaded

Need additional commands to put the fragments together