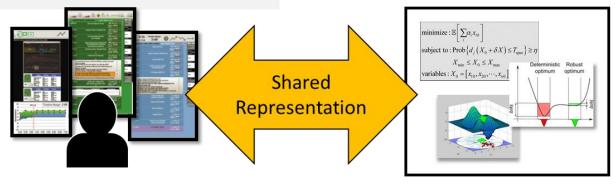
Technologies for Mixed-Initiative Plan Management for Human Space Flight

Karen M. Feigh (PI)
Amy R. Pritchett (Co-PI)
Martin Savelsbergh (Co-PI)

Georgia Institute of Technology

Research Objectives:

- 1. Represent the work of planning to enable computation and visualization
- 2. Identify how the human should interact with the machine
- 3. Develop computational algorithms to monitor and adapt plans



Multiple forms of interaction

Approach

- Tightly integrate the needs of the human planner with the machine's computational algorithms
- Create a common representation of the plan for machine and human planner
- Build on methods in cognitive engineering and operations research

Multi-objective Optimization

Potential Impact

A successful planning management tool will:

- Allow the crew to operate (semi-) autonomously.
- Support the crew in achieving complicated mission goals while maintaining their safety
- Support the crew in reacting quickly and safely in off-nominal situations