National Aeronautics and Space Administration



NASA's Game Changing Technology Industry Day June 29-30, 2016

### **Satellite Servicing**

Presented by Charles Bacon NASA Satellite Servicing Capabilities Office

**TECHNOLOGY DRIVES EXPLORATION** 



# Satellite Servicing



Satellite Servicing encompasses a group of technologies that work together to enable in-space life extension, upgrades, assembly, replenishment, replacement, or repair of spacecraft

SSCO is executing projects to advance the state of satellite servicing technologies that will enable:

- Routine servicing of legacy spacecraft in government and industry
- Exploration of the solar system
- U.S. to be a global leader of inspace servicing













# Satellite Servicing Capabilities Office



Current satellites cannot be repaired onorbit and are disposed of even if a majority of the spacecraft is still functional

Future exploration missions will not be possible without servicing technologies:

- Relative Navigation for autonomous rendezvous
- Robotics with sophisticated tools to support assembly, upgrades, or repairs
- Propellant Transfer in-space refueling

The technologies required to repair legacy satellites or enable future exploration missions are immature and must be enabled through technology demonstration missions. This is the goal of SSCO, a world leader in the field of satellite servicing.





### **Restore-L Servicing Mission**





Restore-L is a technology demonstration mission to repair a legacy satellite that encompasses all satellite servicing technology areas and represents a culmination of decades of satellite servicing technology development



## **Relative Navigation**





- Heritage development on RNS (SM4), Argon, and Raven
- Covers vision-processing algorithms, visual and ranging sensors, and high-speed computing
- Provides client pose data for control of the servicing spacecraft during autonomous rendezvous
- Goal is to provide an off the shelf government technology set













- NASA Servicing Arm has been in development of several years and has heritage with previous robotic arms developed under NASA and DARPA projects
- System includes the Robotic Arm, Control Electronics, and Software
- Capable of autonomous and telerobotic control modes
- Goal is to provide a qualified robotic system that can be used on a wide range of future missions







### **Robotic Tools**

#### **Current TRL: 4-7**



- Robotic servicing tools are used for interfacing with client satellites to perform a wide range of tasks:
  - Cut wires, remove caps, manipulate MLI
  - Refueling
  - **Close-up inspection**
  - Repair
- Robotic Refueling Mission (RRM) has given some of these • tools successful operation in space



Goal is to provide a suite of universal tools for future missions • to utilize









### **Propellant Transfer**

#### Current TRL: 3-4



- System to transfer fluid in zero-g from one spacecraft to another
- Includes flow meter and flexible hose components
- Development focusing on compatibility with hydrazine, oxidizer, and xenon
- Major development to date came from the Remote Robotic Oxidizer Transfer Test (RROxiTT)
- Goal is to provide a configurable set of technologies that can be used on missions with different propellant needs









# Servicing Technology Benefits







### What's Next?



SSCO near-term objectives to advance servicing TRLs:

- Complete Raven operations onboard ISS (2016-2017)
- Build, fly, and operate Robotic Refueling Mission 3 onboard ISS (2017-2018)
- Complete Restore-L Mission (2020)

In the meantime SSCO will:

- Release a synopsis of a technology transfer plan for industry feedback (2016-2017)
- Host Industry Days to provide data from major Restore-L reviews
- Begin efforts to transfer technology via non-exclusive licenses
- Educate the space community about how to utilize servicing technology in the development of their projects
- Provide updates on the latest developments in the advancement of servicing technology via media communications and technical papers
- Study how future missions can be enhanced through the application of servicing technology



## **Contact Information**



For more information about this technology or to discuss potential collaboration efforts:



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