## A Novel Electrostatic/ Microstructured Adhesive with Dust Mitigation Capabilities

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## Approach

- FEA models optimize electrode geometry for adhesion
- Prototypes are fabricated and adhesion pressure is experimentally validated
- Prototypes experimentally tested for dust mitigation under both controlled and "real-world" conditions
- Gripper fabricated according to payload restrictions of free flying Astrobee/SPHERES class robots
- Gripper and adhesives experimentally validated using autonomous perching micro air vehicle testbed



## **Research Objectives**

- Develop a novel electrostatic/microstructured (gecko-like) adhesive with an order-of-magnitude improvement of electrostatic adhesion coupled with the unique ability to shed dust particles
- Elevate electrostatic adhesion levels to be on par with microstructure adhesion levels
  - Initiate first known research to date on dust mitigation of microstructured adhesives
  - Start TRL 2. Concept and application have been formulated
  - End TRL 3. We will deliver experimental proof-of-concept of increased adhesion and dust mitigation

## **Potential Impact**

- Increase system-level performance to allow the Astrobee/SPHERES class of freeflying robots to exert high inertial loads during docking or perching
- Enable adhesion to rough surfaces and fabrics
- Dust mitigation significantly improves reliability and allows repeated use without the need for a human to frequently and repeatedly clean the adhesives by hand
- Applications in orbital debris removal, satellite servicing, as well as in-space assembly, manipulation, and docking