

Low-Mass Planar Photonic Imaging Sensor

S. J. Ben Yoo, Ryan P. Scott

*Dept. of Electrical and Computer Engineering, University of
California, Davis, CA, 95616 USA*

Alan Duncan

*Lockheed Martin Advanced Technology Center, Palo Alto, CA,
94304 USA*

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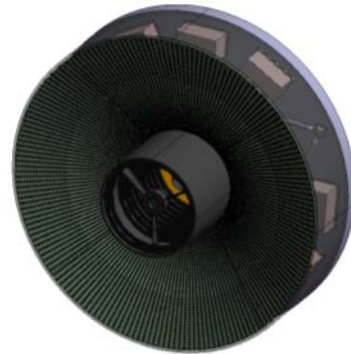
Key to Affordability – Low SWaP



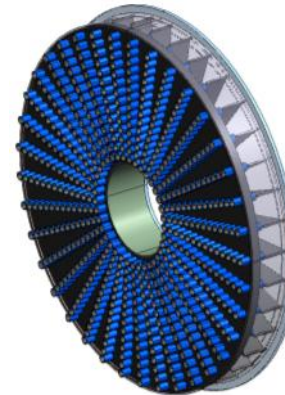
Orders of Magnitude SWaP Reduction Achievable



Conventional
Telescope and
focal plane



SPIDER:
Radial Blade
Design Option
B: outer ring

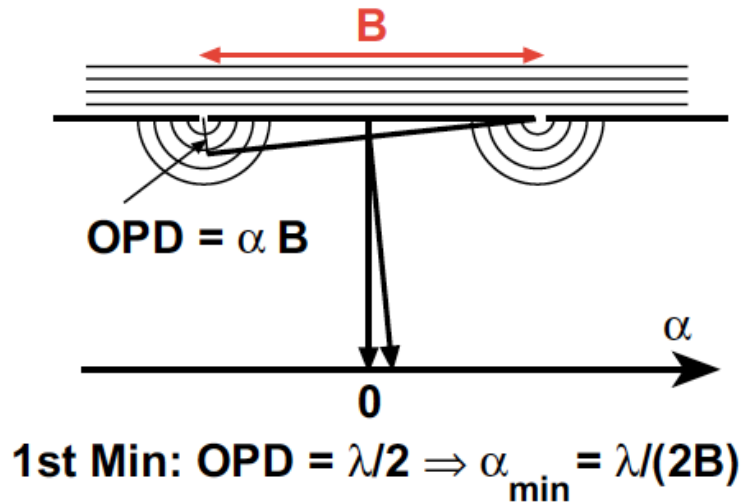


SPIDER:
Radial Blade
Design Option
A: full sensor

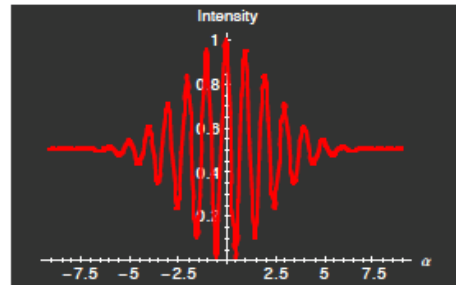
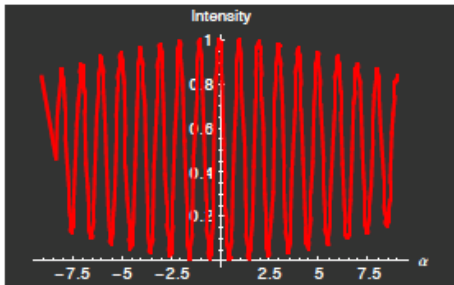


SPIDER:
Single Chip
Design

Basic Idea--Young's Two-Slit Experiment



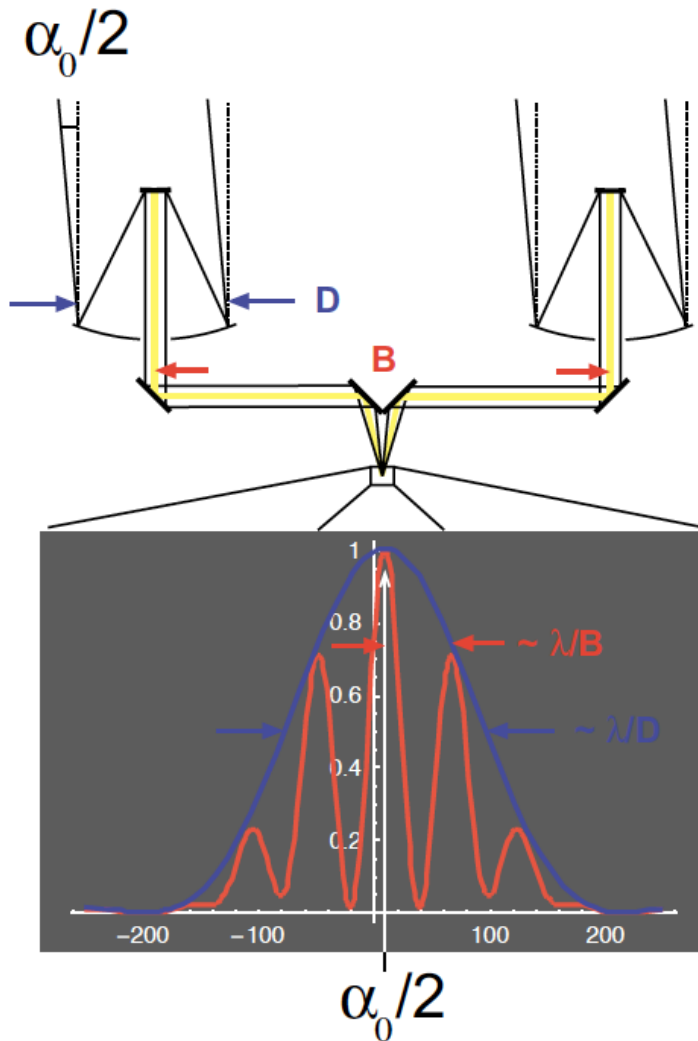
- Light source at infinity at $\alpha = 0$
- Intensity pattern $\sim 1 + \cos$ as a function of α , period length: λ/B
- OPD > coherence length \Rightarrow fringes disappear
- Light source at angle α_0 \Rightarrow fringe pattern shifts accordingly



(First and last picture of a movie)

Figure Courtesy of Andreas Glindemann

Basic Idea--Michelson Stellar Interferometer



- Stellar source with angular size α_0
- Add fringe patterns (i.e. intensities) between $\pm\alpha_0/2$

Figure Courtesy of Andreas Glindemann

Advantages of Interferometric Imaging

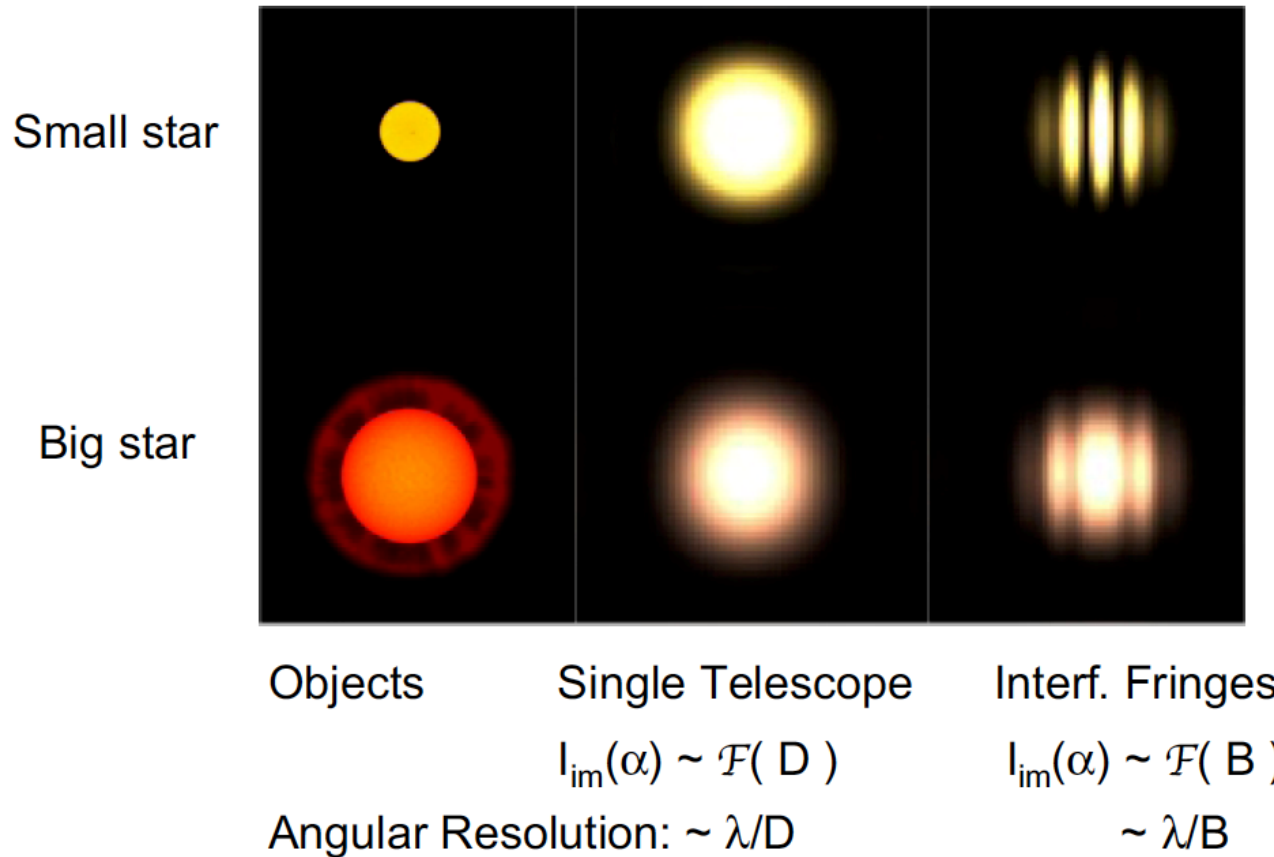


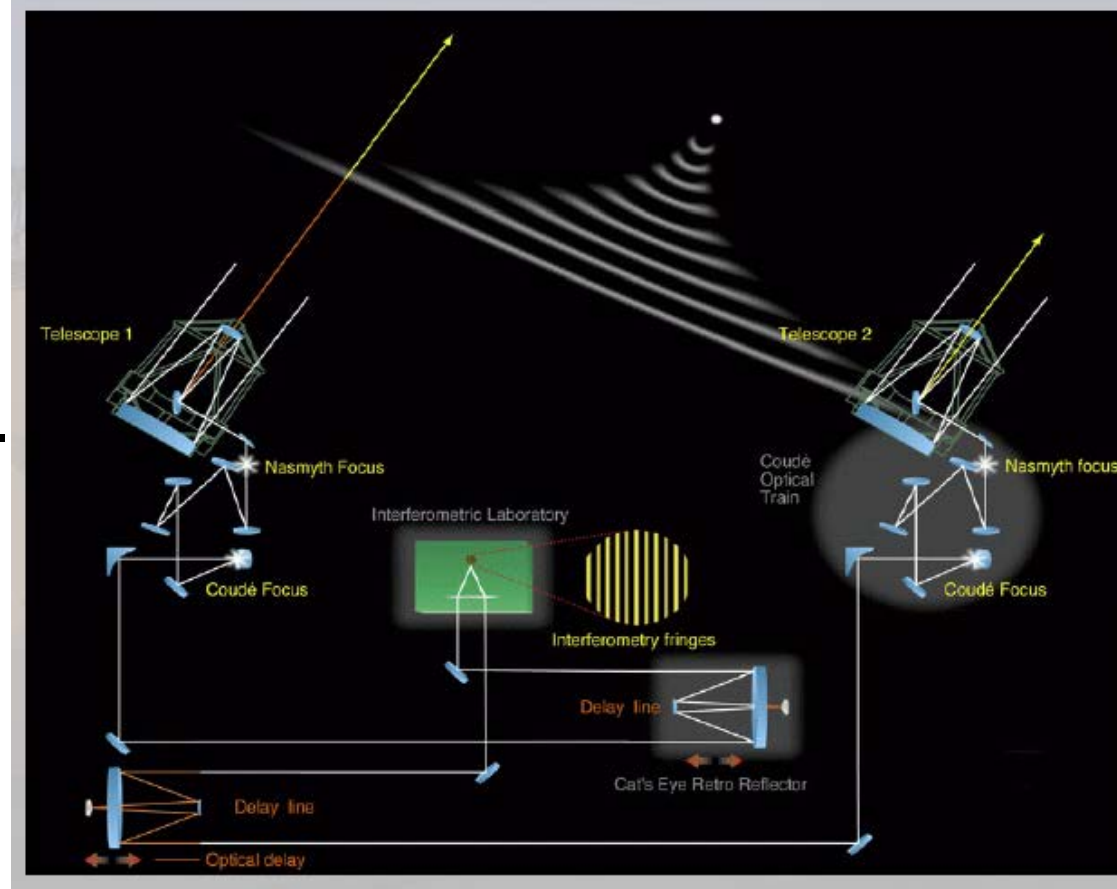
Figure Courtesy of Andreas Glindemann

Radio VLA



Basic Algorithm

- Sample the fields at r_1 and r_2 .
- Optical train delivers the radiation to a lab.
- Delay lines assure that we measure when $t_1=t_2$.
- The instruments mix the beams and detect the fringes.
- Measure the fringes
- Interpret the Fourier spectrum of the target



Courtesy of C. Haniff



The Output of a Two-element Interferometer

- A combination of E fields from the two collectors can be described as:

$$\Psi_1 = A \exp\left[ik\left(\hat{s}\cdot B + d_1\right)\right] \exp(i\omega t) \text{ and } \Psi_2 = A \exp\left[ik\left(d_2\right)\right] \exp(i\omega t)$$

- Summing these at the detector yields:

$$\Psi = \Psi_1 + \Psi_2 = A \left[\exp\left(ik\left[\hat{s}\cdot B + d_1\right]\right) + \exp\left[ik\left(d_2\right)\right] \right] \exp(i\omega t)$$

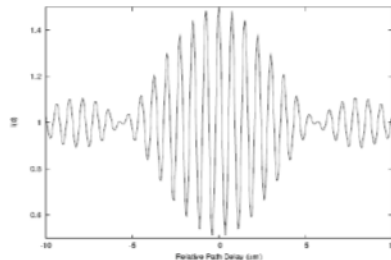
- Thus, the time averaged intensity, $\langle \Psi\Psi^* \rangle$, is given by:

$$\begin{aligned} \langle \Psi\Psi^* \rangle &\propto \left\langle \left[\exp\left(ik\left[\hat{s}\cdot B + d_1\right]\right) + \exp\left(ik\left[d_2\right]\right) \right] \times \left[\exp\left(-ik\left[\hat{s}\cdot B + d_1\right]\right) + \exp\left(-ik\left[d_2\right]\right) \right] \right\rangle \\ &\propto 2 + 2 \cos\left(k\left[\hat{s}\cdot B + d_1 - d_1\right]\right) \\ &\propto 2 + 2 \cos(kD) \end{aligned}$$

- Here, D is a function of the path lengths, d_1 and d_2 , the pointing direction (i.e., where the source is), and the baseline.

- Measure the fringe visibility at $D = 0$ and the fringe phase (with respect to a ref):

$$V = \frac{I_{\max} - I_{\min}}{I_{\max} + I_{\min}}$$



The fringe amplitude and phase measure the amplitude and phase of the Fourier transform of the source at one spatial frequency.

Adapted from C. Haniff – The theory of interferometry

SPIDER Provides Low Cost Option to Enhance Resolution of a Conventional Telescope



- **Objectives**

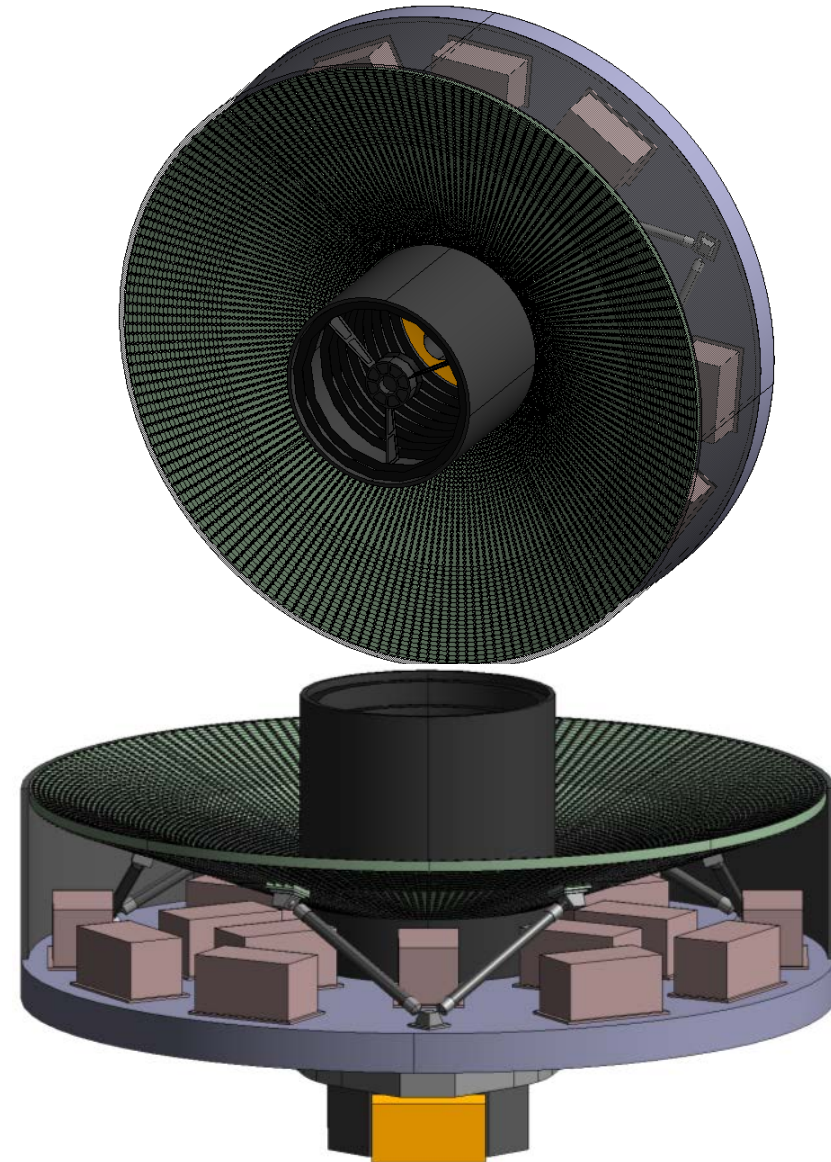
- Enhanced quality imagery using sparse high resolution image sampling and hyperspectral data
- Increase effective aperture diameter by 2X - 3X (9X mass reduction)

- **Concept Description**

- Moderate aperture diameter conventional imaging telescope with staring focal plane
- White light waveguide coupled interferometers with integrated combiner / phase shifters / detectors

- **Performance Characteristics**

- Moderate resolution full field of view panchromatic image
- Selectable subfield regions enhanced with high resolution and hyper-spectral content



SPIDER* Concept Enables Next Generation Imaging Capabilities



Linear arrays of lenslets arranged in spoke-like pattern to fill u,v (Fourier) imaging plane

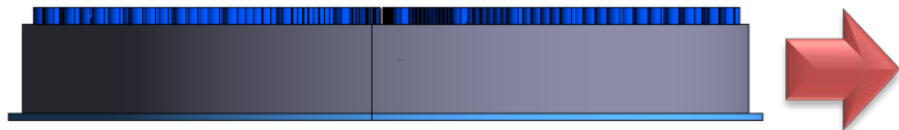
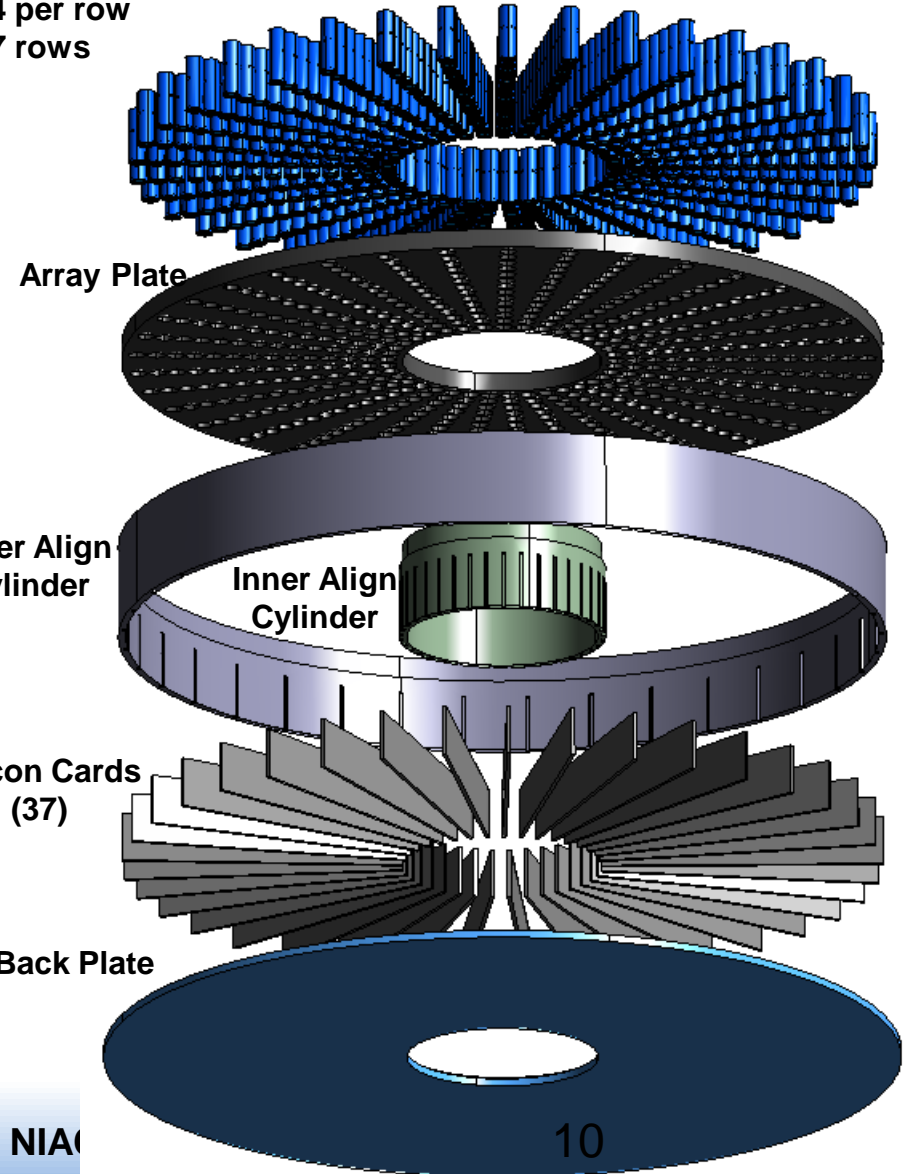
Objectives

- Planar “flat panel” telescope with NO large optics
- Large field of view with NO precision gimbals for line of sight steering

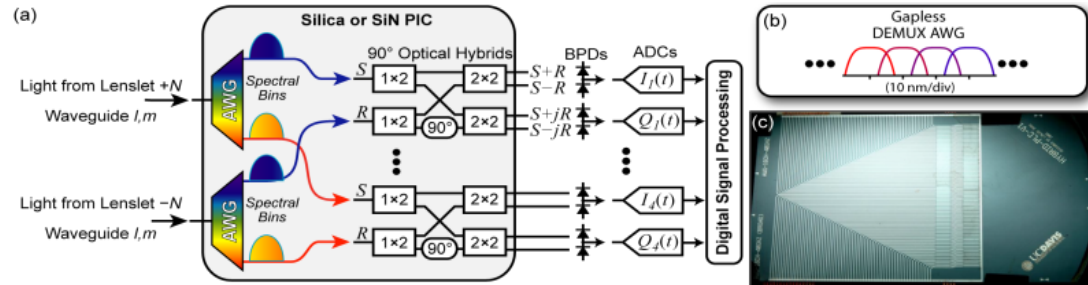
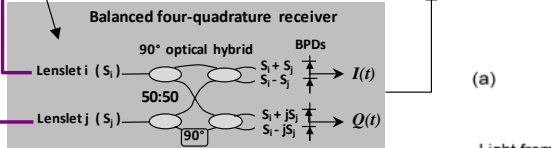
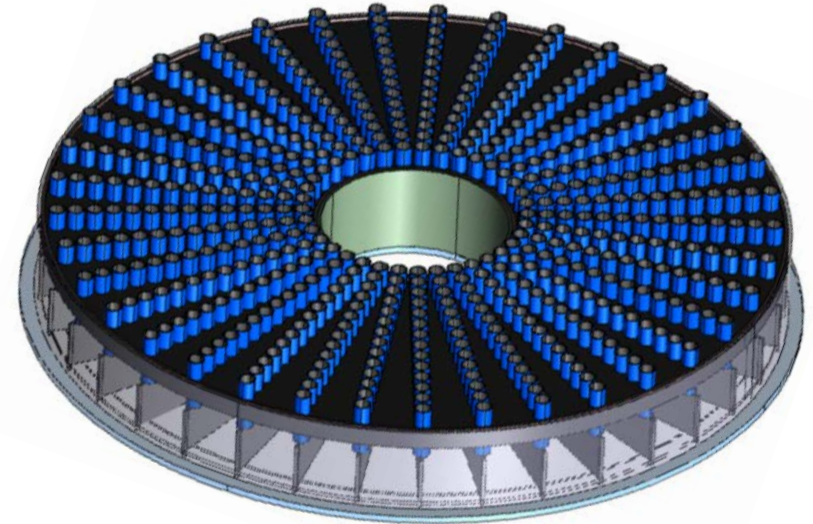
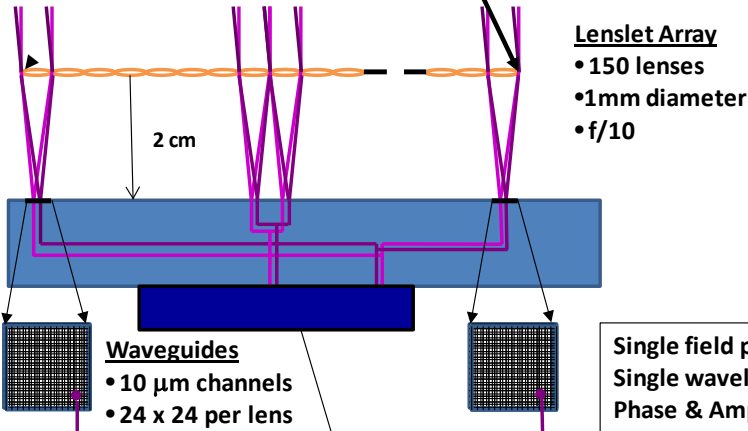
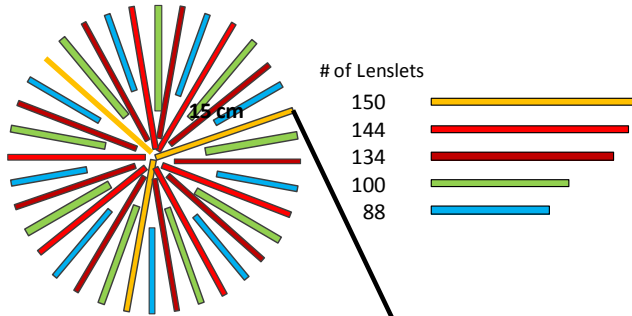
Concept Description

- Light input by large area lenslet array “wired” into interferometer channels using nanophotonics (leverages commercial high density optical interconnect 3D computer chip technology)
- Scalable to larger apertures using fiber coupling of multiple interferometer chips

Interferometer Tube Assy Array
14 per row
37 rows

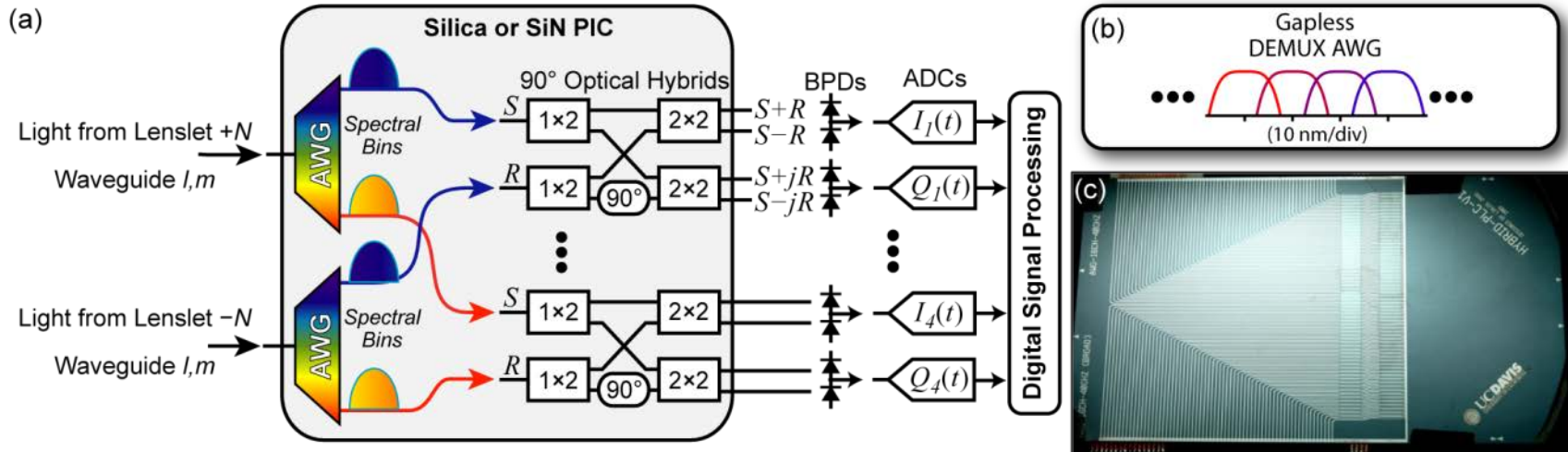


UC Davis – Lockheed Martin's NIAC Approach



Spectrally Resolved High Resolution Interferometric Telescope

Photonic Integrated Circuit (PIC) Design

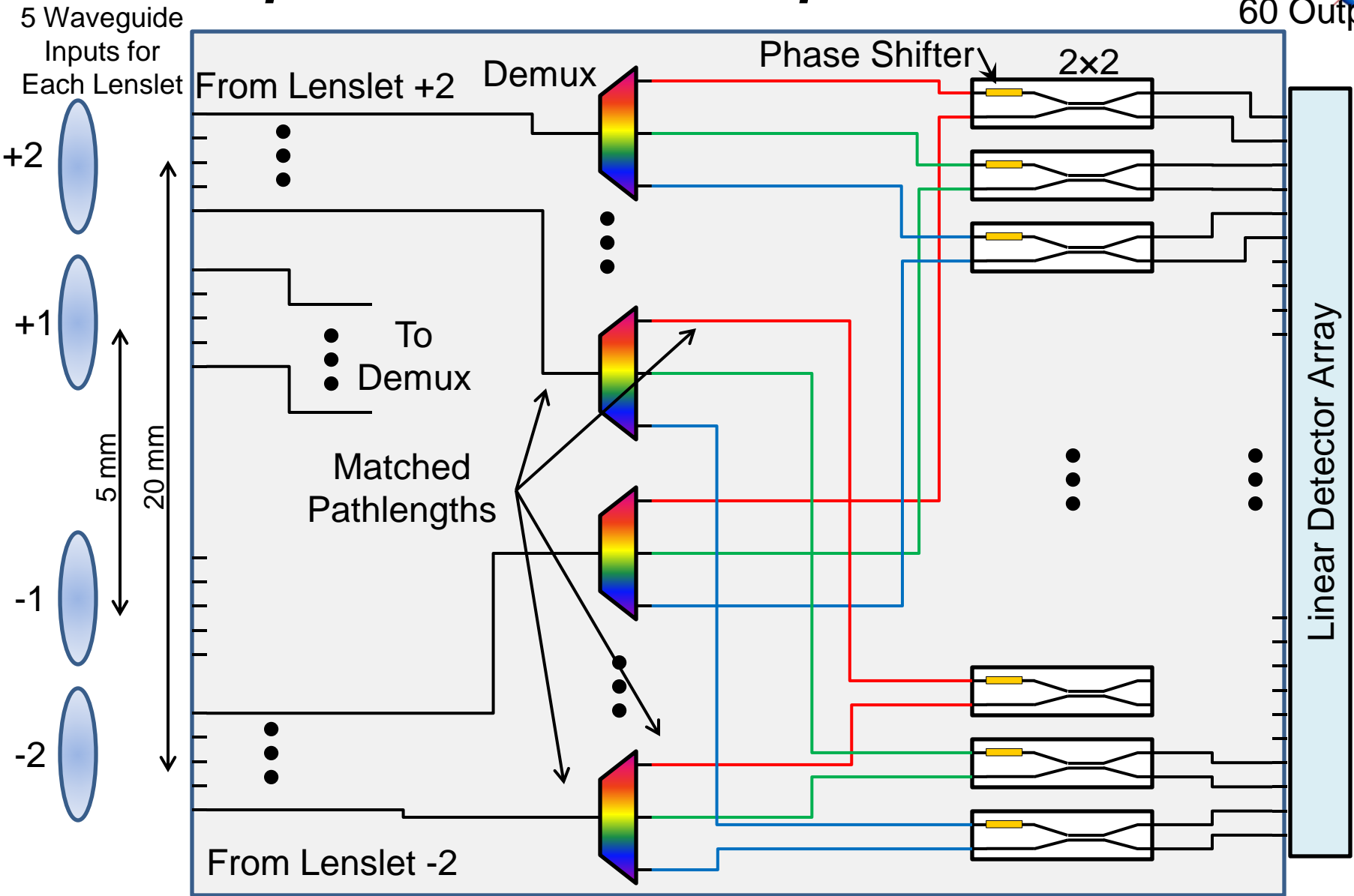


- Specify spectral bin widths, bin spacing, interferometer phase shift requirements, desired optical mode size, etc.
- Simulations of individual photonic components (spectral demultiplexer, splitters, etc.)
- Packaging design
- Layout of waveguide and metal mask layers including test structures
- Design review

10-Spatial-Channel \times 3 Spectral Band PIC



60 Outputs

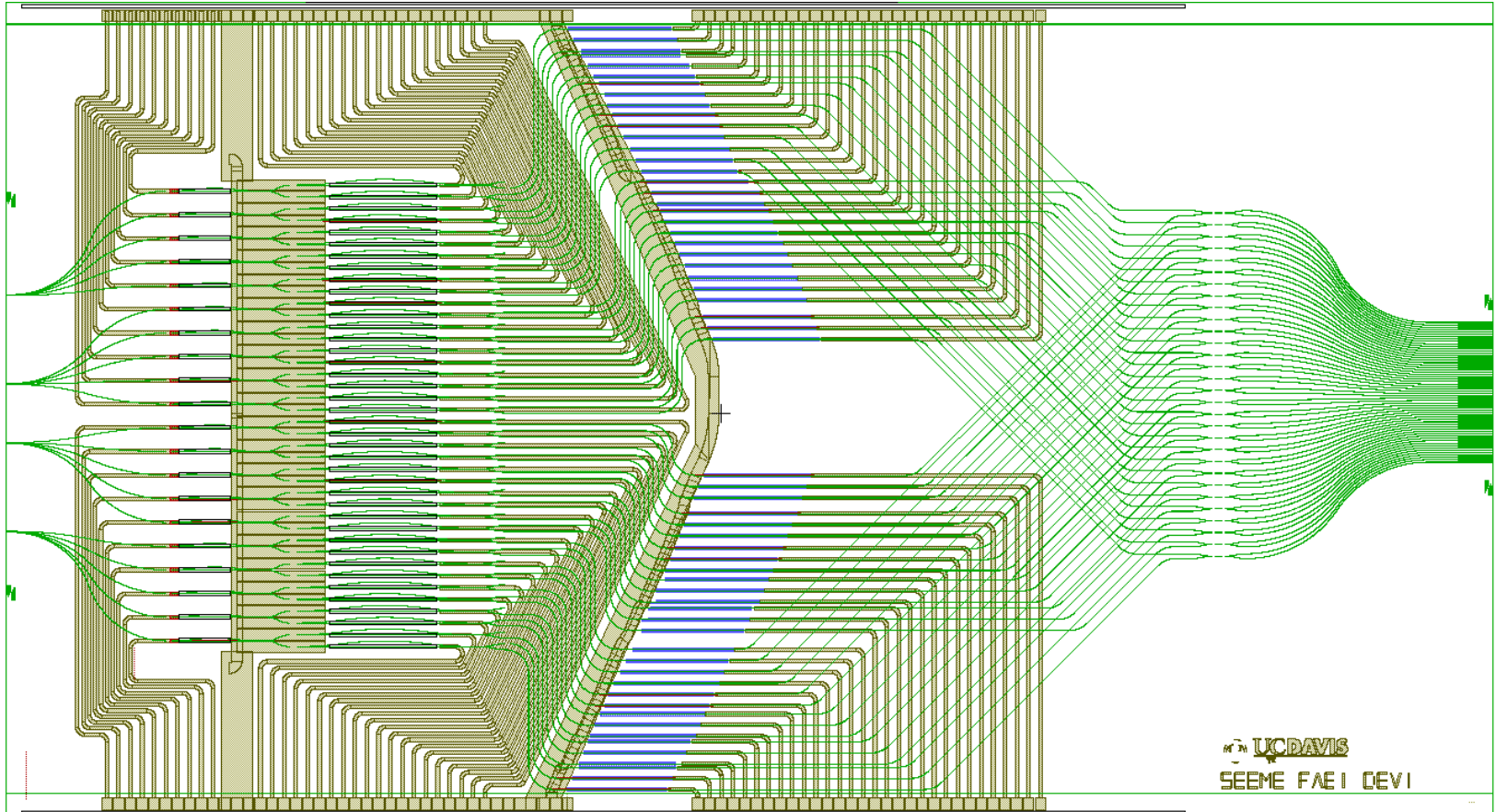


10-Spatial-Ch x3 Spectral Band



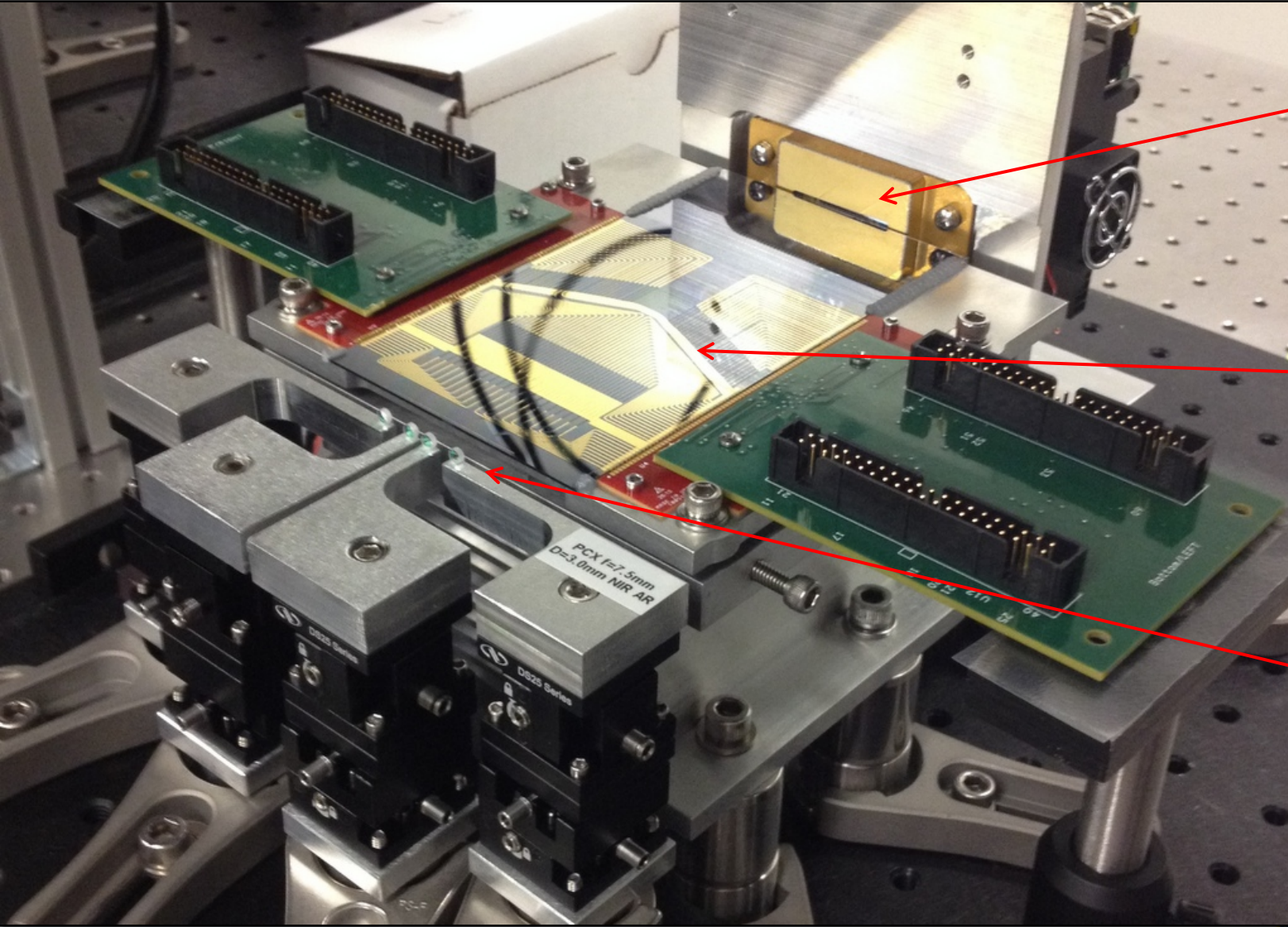
Main Device Layout

- Layer#1: waveguide
- Layer#2: heater
- Layer#3: electrode
- Layer#4: trench
- Layer#11: waveguide keep out



DARPA funded work

Packaged PIC



Linear
Detector
Array

PIC

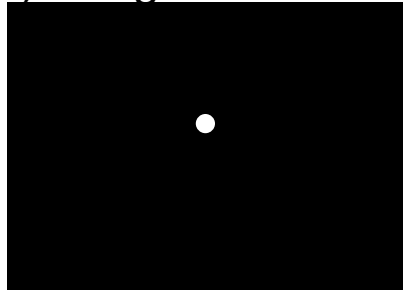
Lenslets

DARPA
funded
work

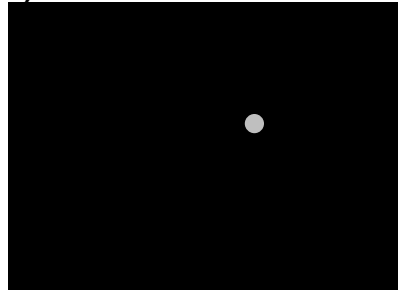
Measuring Fringes from One and Two Sources



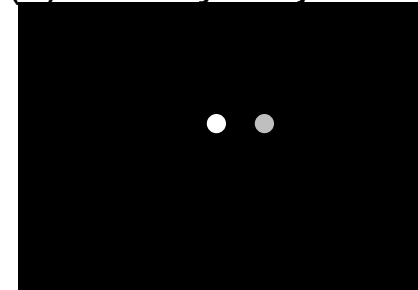
(a) Bright Source



(b) Faint Source

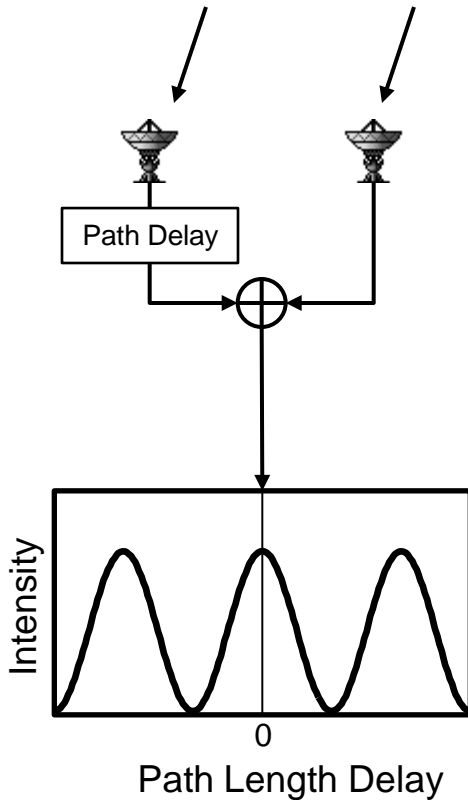


(c) Binary Object

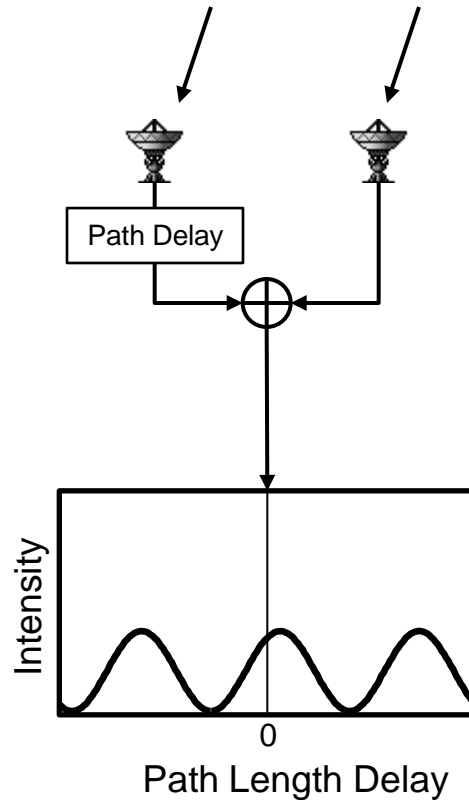


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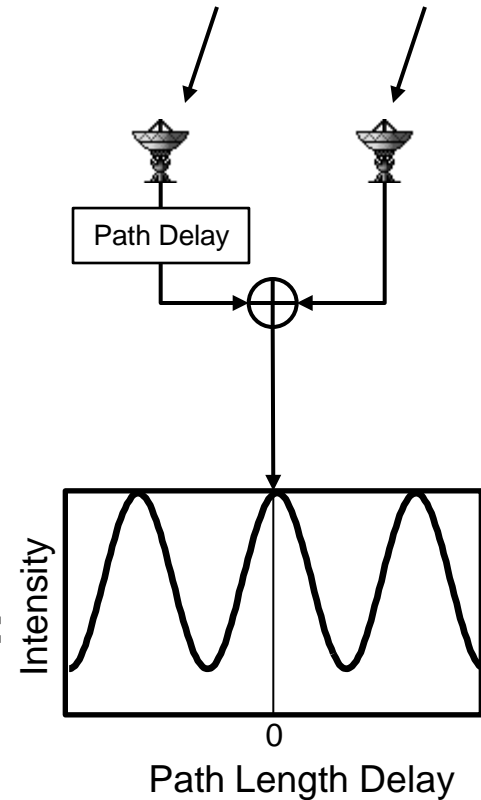
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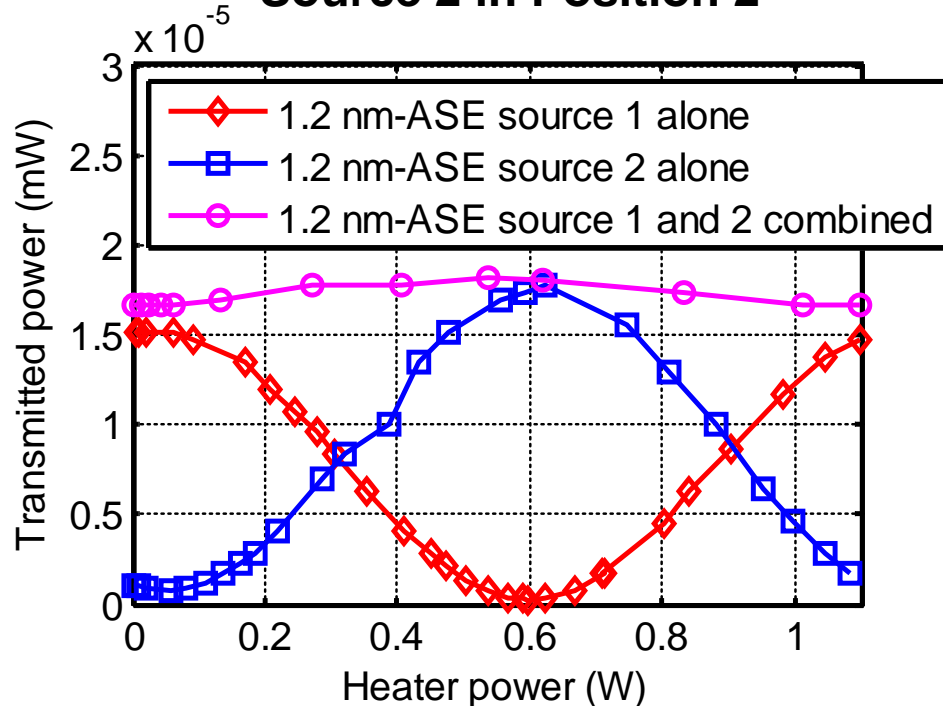
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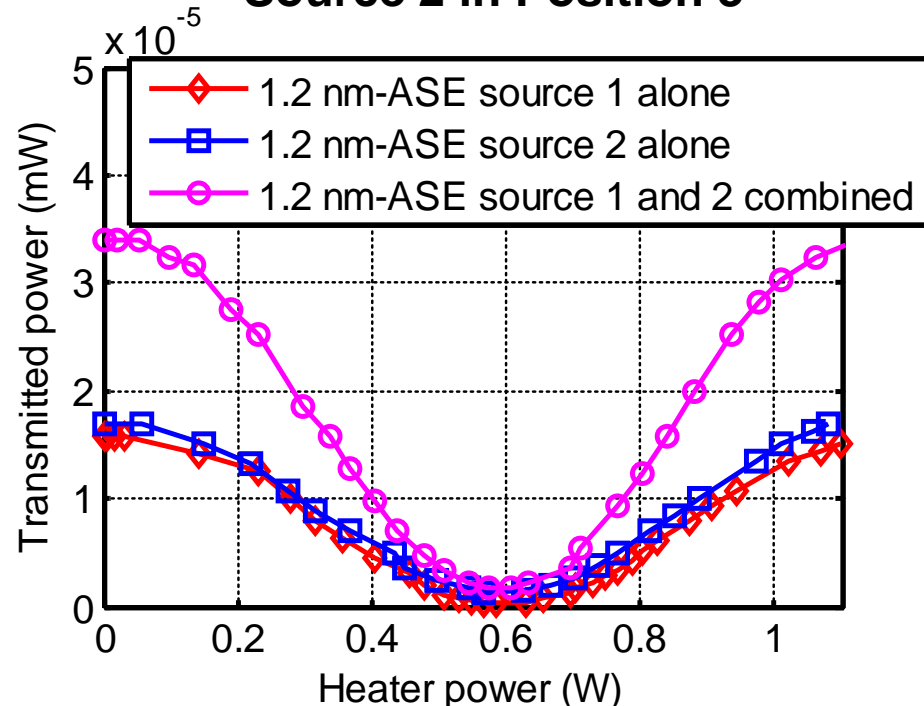
Fringe Measurements of Point Sources

- Fringe extinction >10 dB
- The ASE sources are incoherent with respect to each other

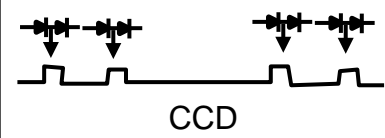
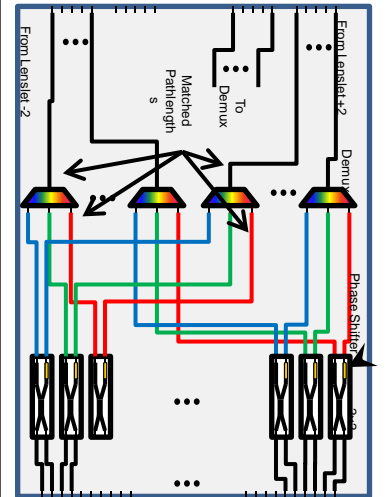
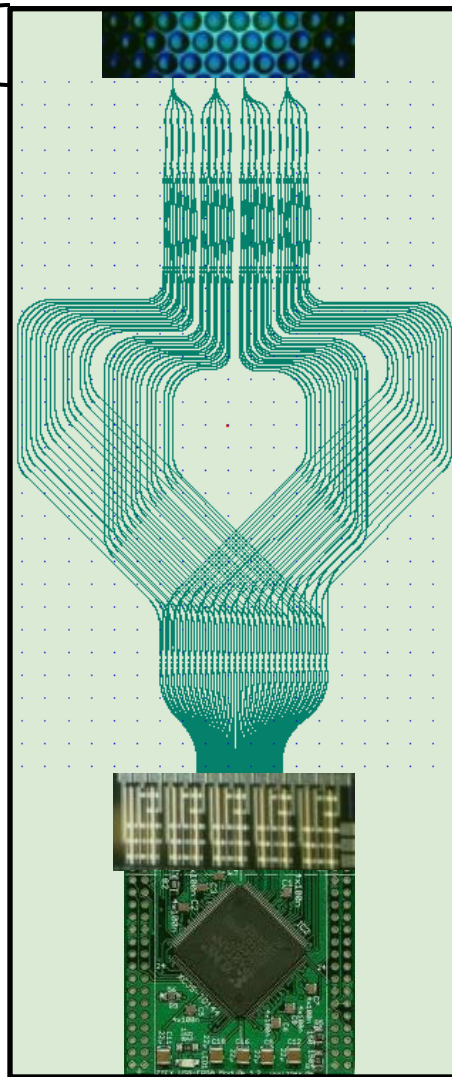
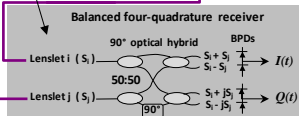
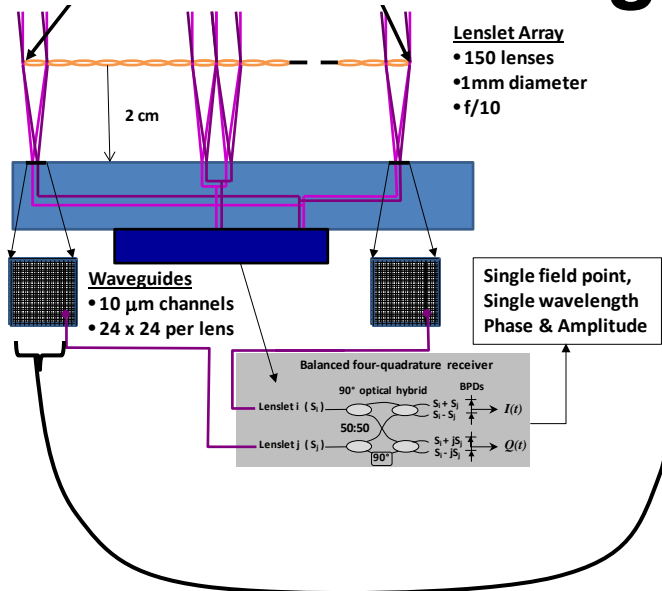
Source 2 in Position 2



Source 2 in Position 3



Integrated SPIDER Blade



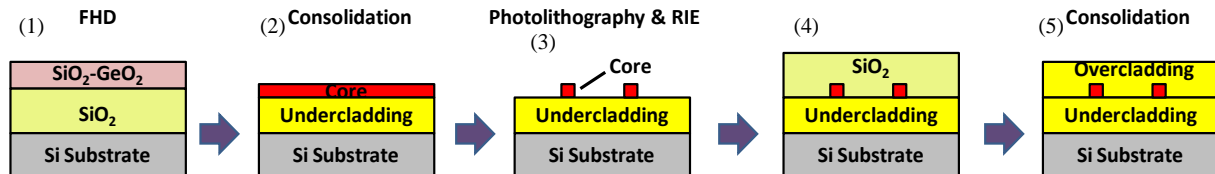
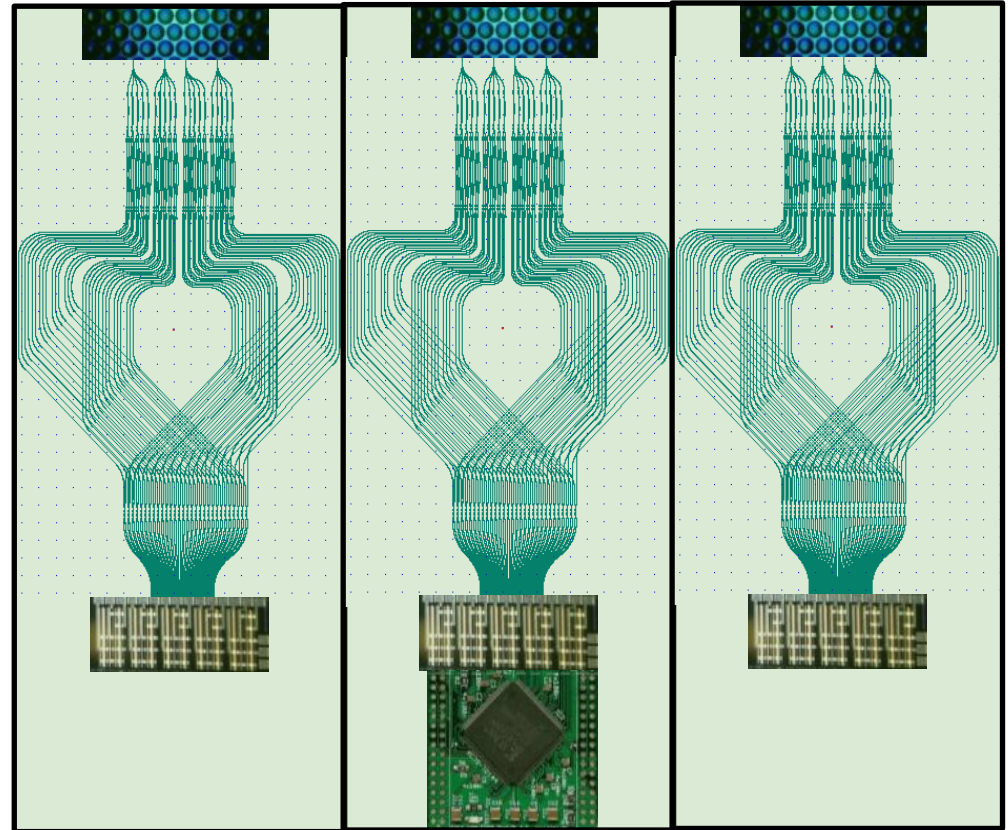
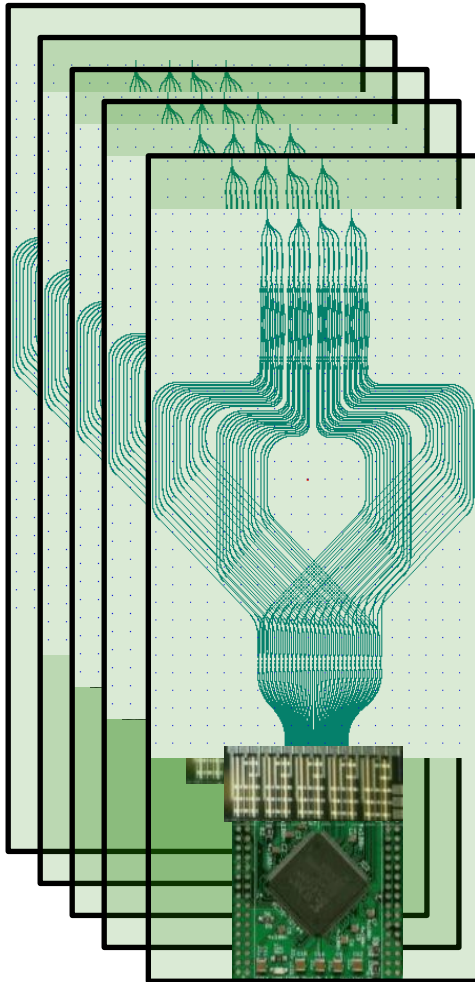
PIC

Self-aligned to

Silicon Photonics

Electronics Board

Integrated SPIDER Blade PIC: two approaches



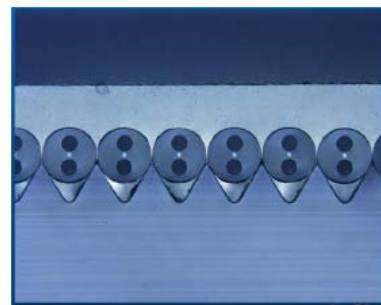
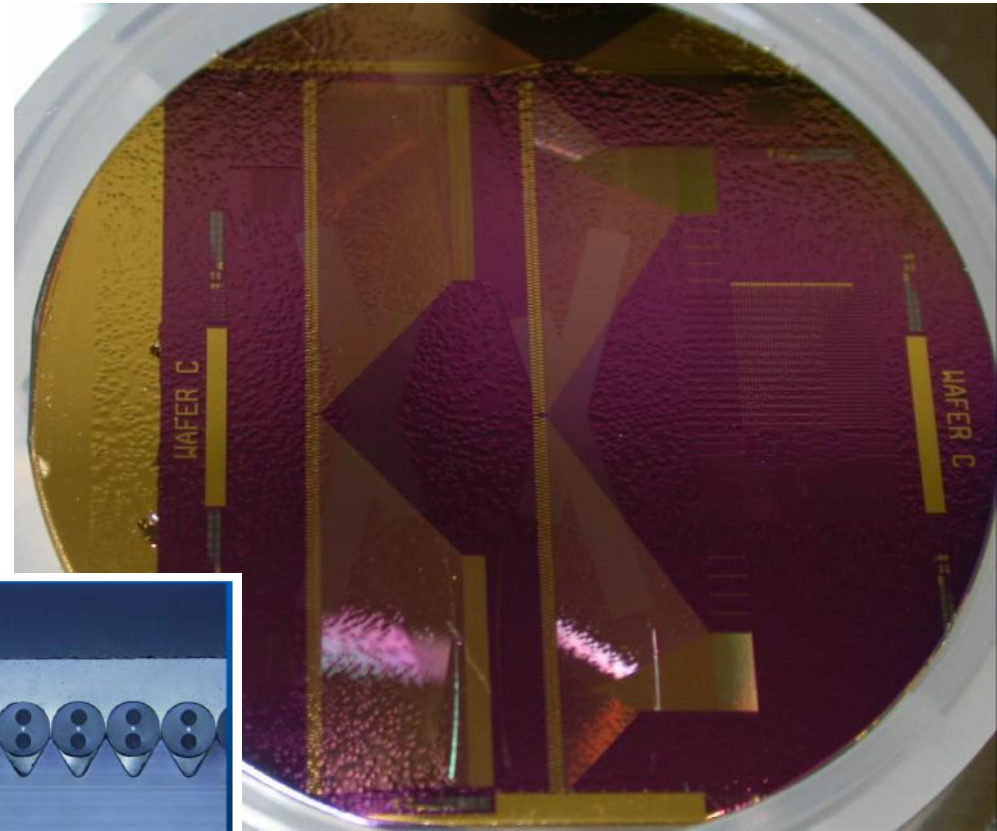
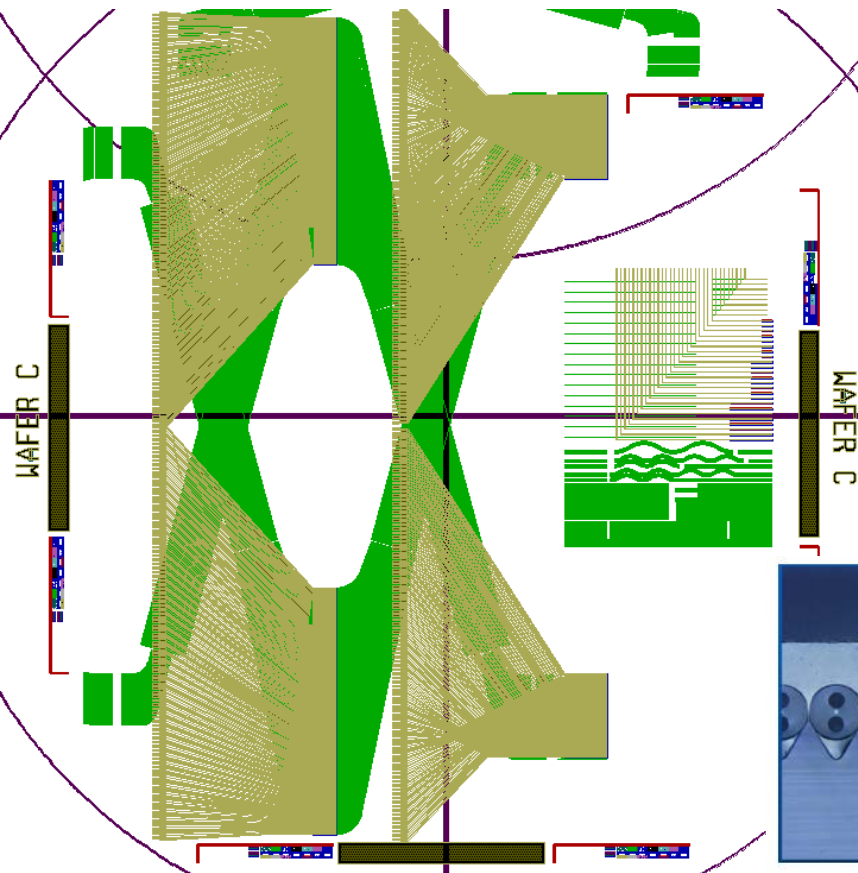


Our Previous Experience:

~8000 waveguides with 1200 independently addressable devices on a chip developed at UC Davis
1 THz (100ch x 10 GHz) OAWG Transmitter (DARPA DSO)

Mask Layout

Fabricated Chip



Modeling / Simulation Flow Chart



Array Configuration

Input Parameters

- Baseline lengths, orientations
- Spectral: width, # of bins
- Integration times
- Etc.

Interferometer Model

Scene Characteristics

Collection Throughput

Line of Sight and Pathlength Errors

Transmission and Signal Mixing

Spectral Dispersion and Binning

Fringe Detection

Simulated Raw Fringes

Visibility Amplitude / Phase Algorithm

Fringe Tracker

Image Reconstruction Algorithms

Image Quality Assessment

Interferometer Model (detail)

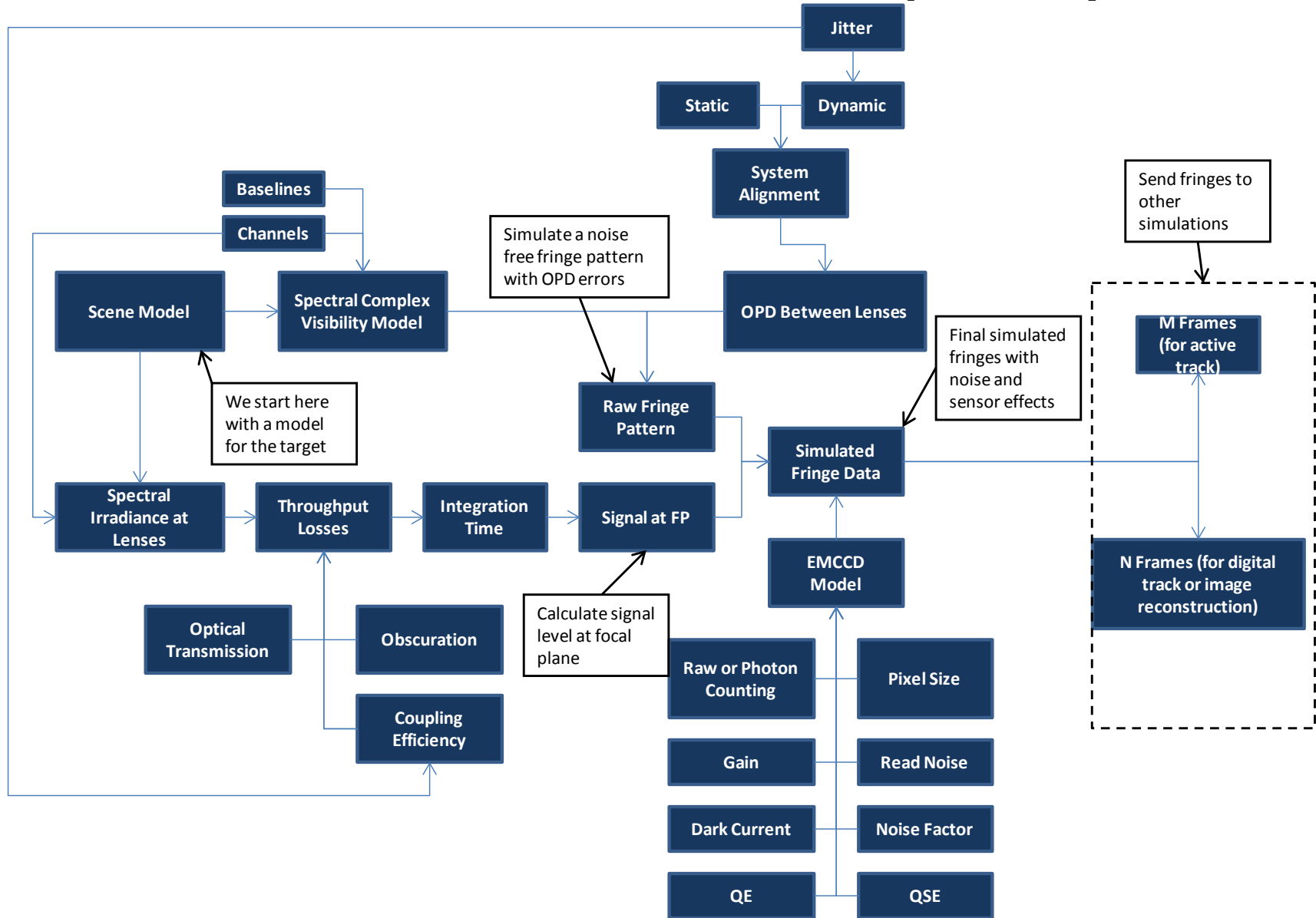


Image Reconstruction Flow Chart



- Developed by University of Rochester (Dr. Jim Fienup) under Lockheed Martin's IRAD funding
- Image reconstruction details will be tailored to imager conceptual design

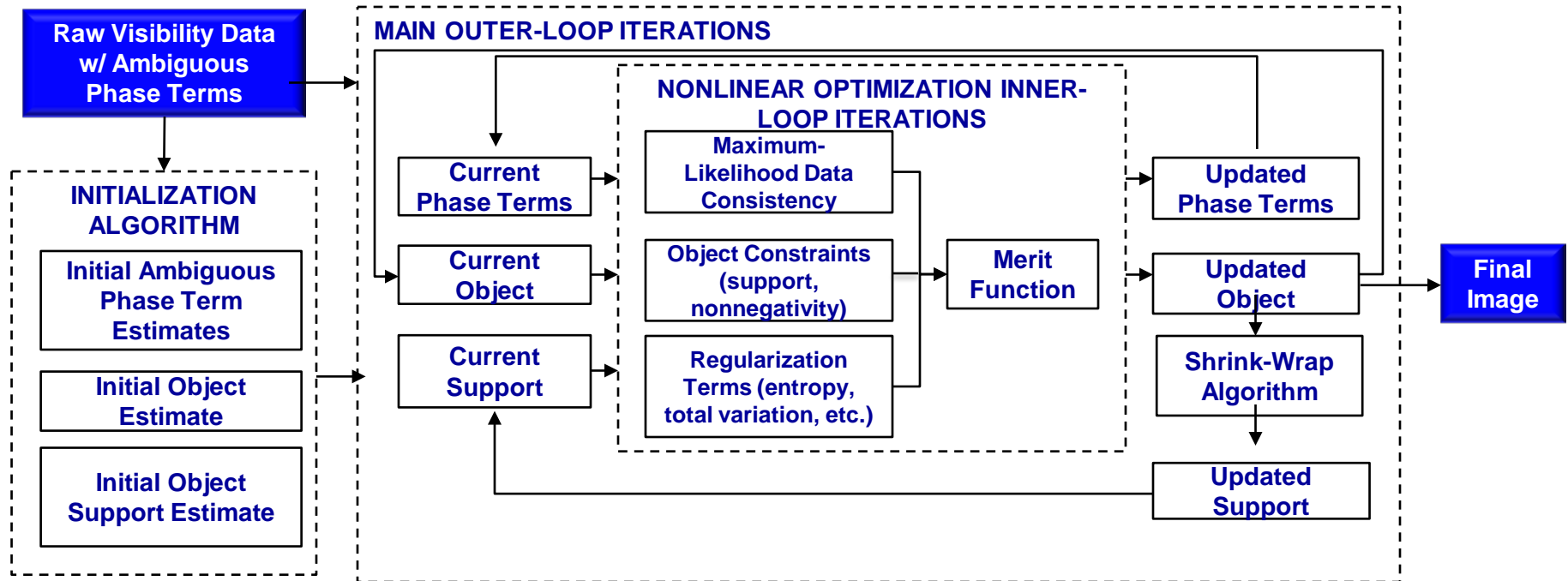
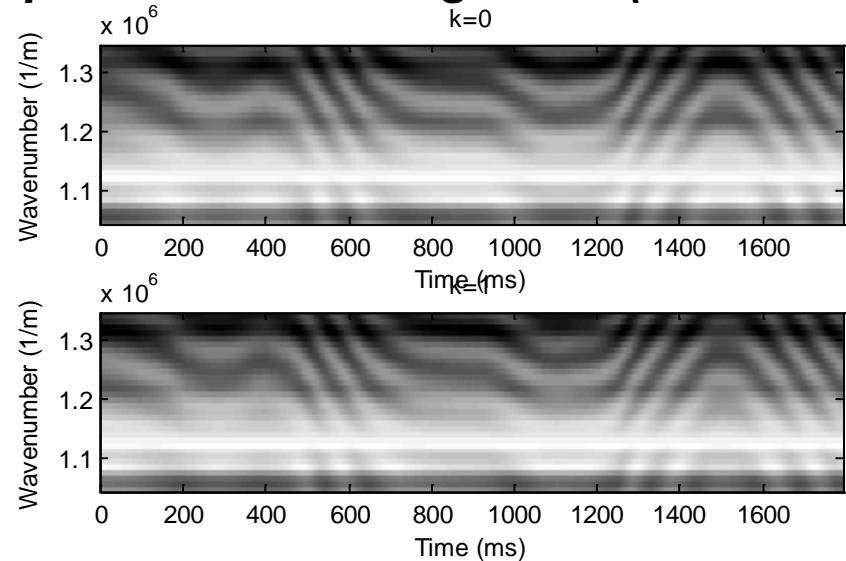
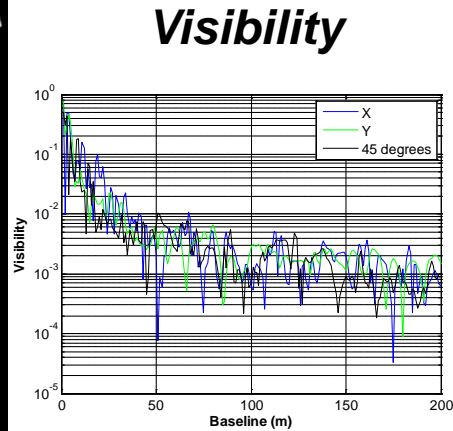
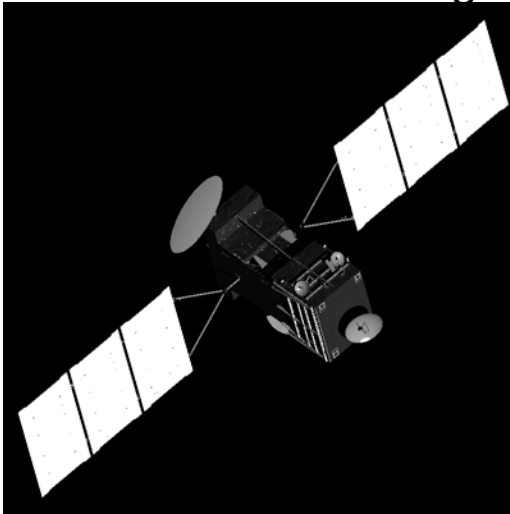


Image Simulations

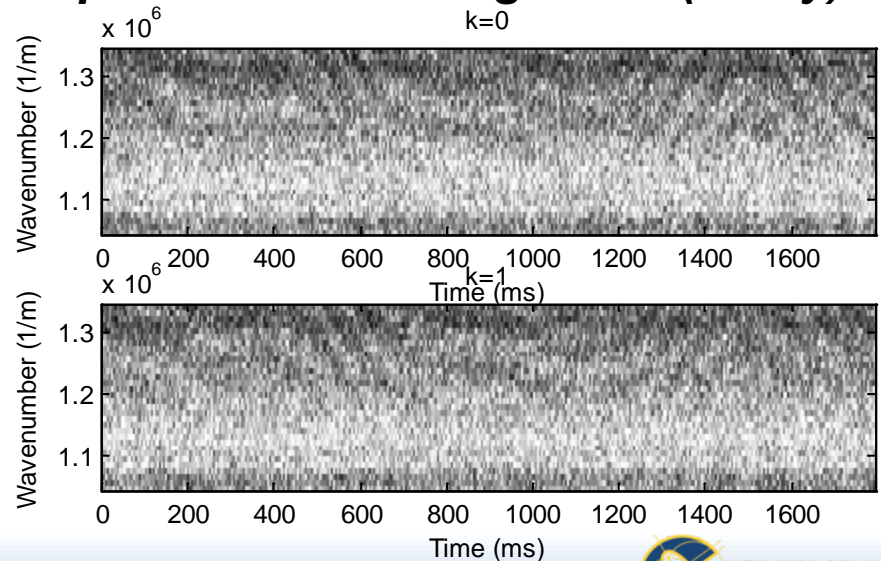
Example Simulated Fringe Data (Noise Free)

DIRSIG model of target



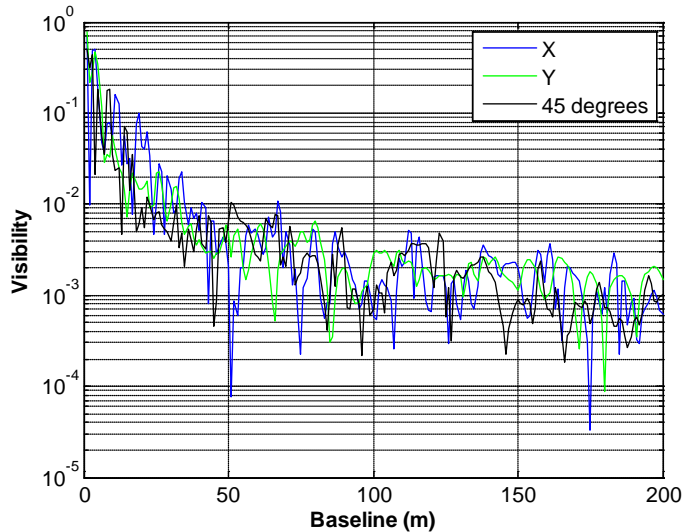
Example Simulated Fringe Data (Noisy)

- 131 spectral bands uniformly spaced in wavelength between 0.5-1.8 μm
- Each band uses the units of $\text{W}/\text{cm}^2\text{-str-}\mu\text{m}$ at the top of the atmosphere
- Resolution of image is 1.65 cm
- More details elsewhere



Lockheed Martin IRAD work

Visibility and Signal Calculation

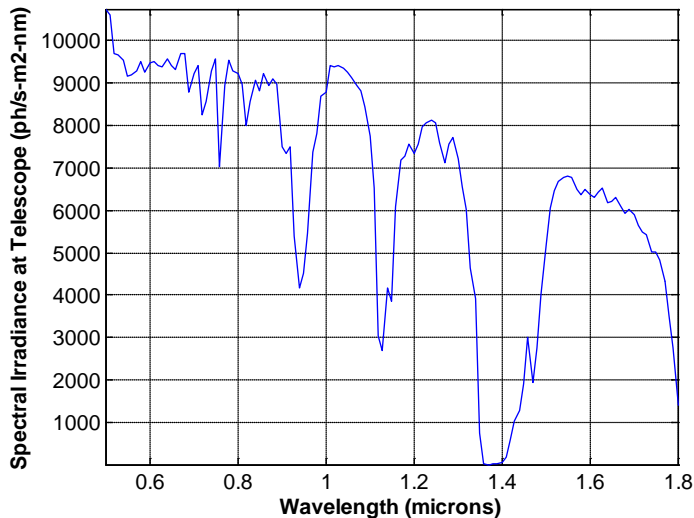


- Complex visibility at a distinct wavelength is the scaled and normalized Fourier Transform of the target

$$V(B_x, B_y; \lambda) = \frac{\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} R(x, y; \lambda) \exp\left(-i \frac{2\pi}{\lambda z} (xB_x + yB_y)\right) dx dy}{\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} R(x, y; \lambda) dx dy}$$

V = Complex Visibility, B_x, B_y = Baseline, λ = Wavelength

$R(x, y)$ = Target Radiance, z = slant range to target



- Spectral irradiance calculation (ph/s-m²-nm)
- Visual magnitude of DIRSIG target is ~9.78
 - Spectral irradiance can be scaled by a factor of 0.324 to give $m_v=11$

$$I(\lambda) = \frac{\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} R(x, y; \lambda) \times \frac{c\lambda}{h} dx dy}{z^2} \times \frac{10000}{1000} \times \tau_{atm}(\lambda)$$

c = Speed of light, h = Planck's constant

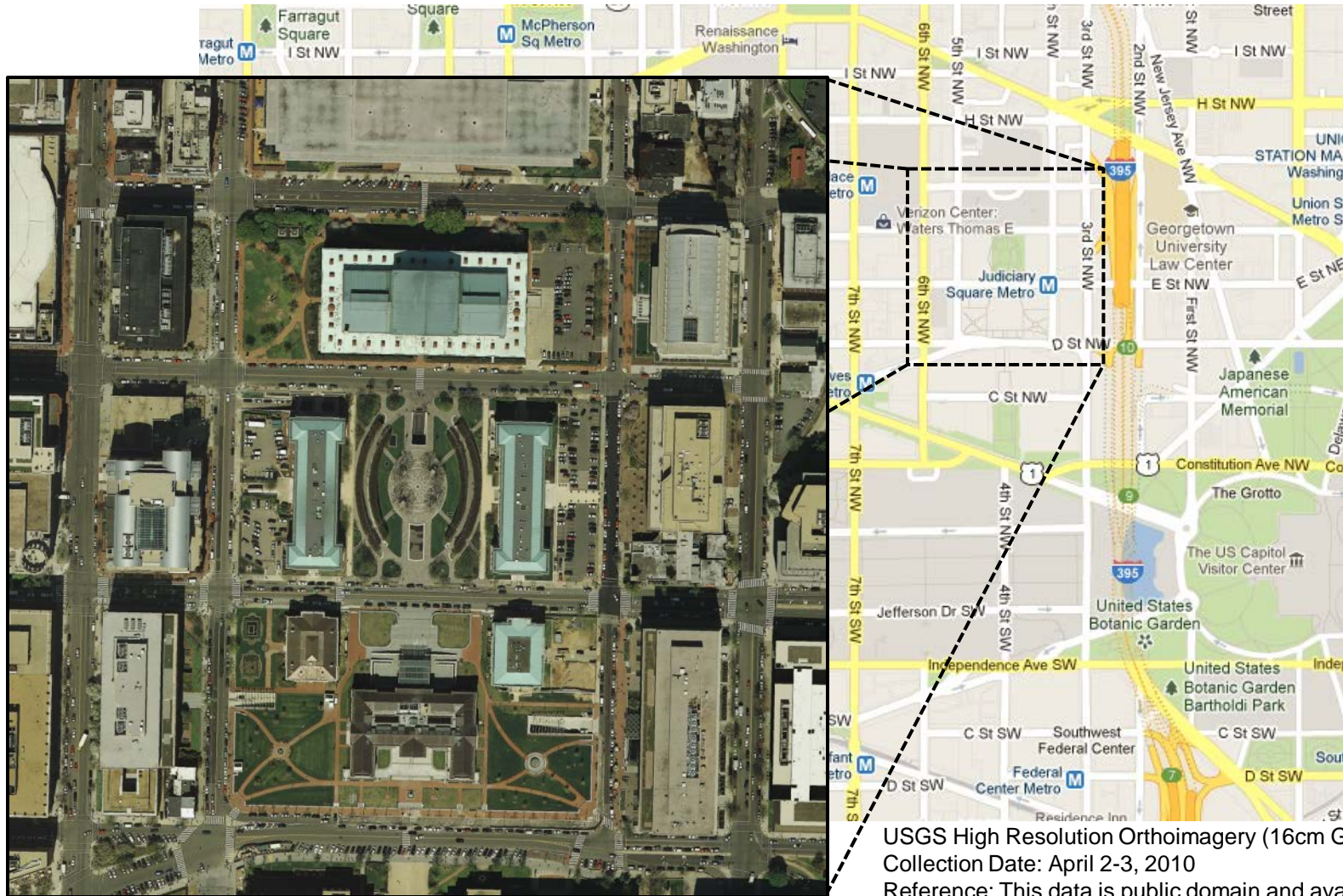
$\tau_{atm}(\lambda)$ = Atmospheric Transmission

Lockheed Martin IRAD work

Scene Data used for Imager Simulations



Judiciary Square, Washington, D.C.



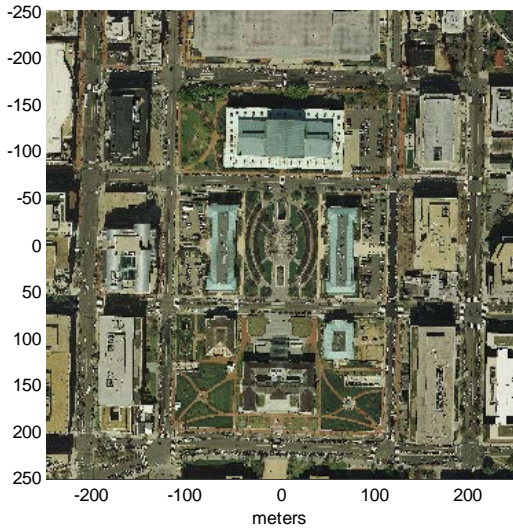
USGS High Resolution Orthoimagery (16cm GSD)
Collection Date: April 2-3, 2010
Reference: This data is public domain and available from the
United States Geological Survey through
<http://nationalmap.gov>.

Lockheed Martin IRAD work

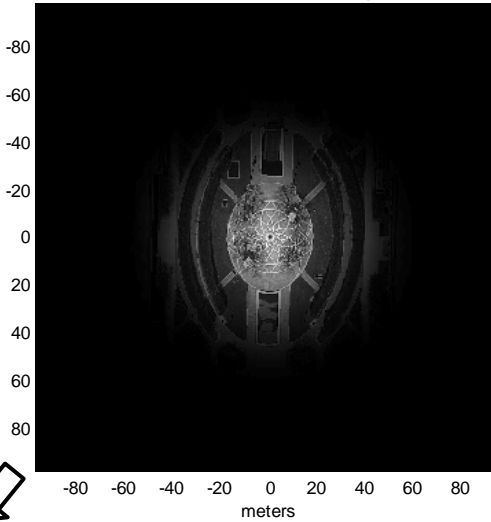
Simulation for a Single Sub-Image



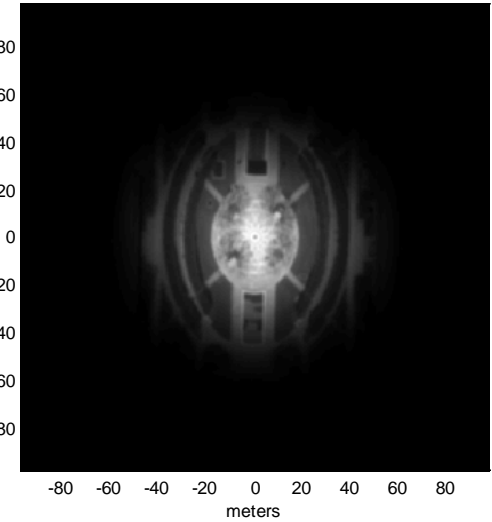
1. User selects FOV for sub-image



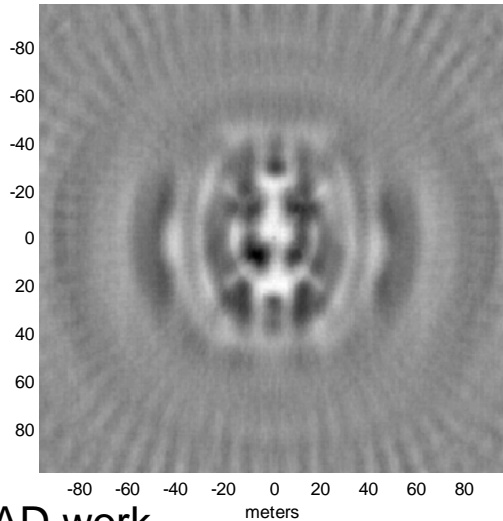
2. Crop scene and apodize (fiber coupling)



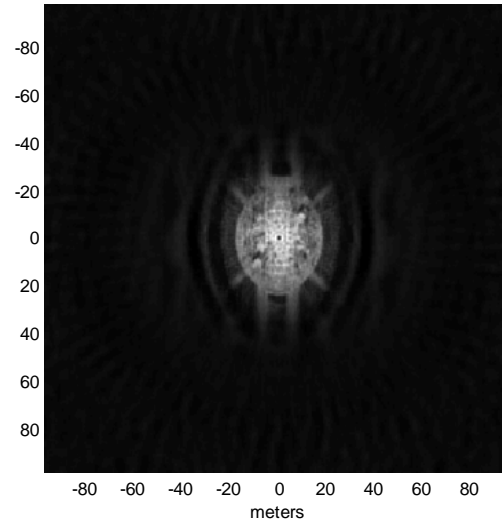
3. Make a conventional comparison sub-image



4. Compute $u-v$ data & make "dirty" image



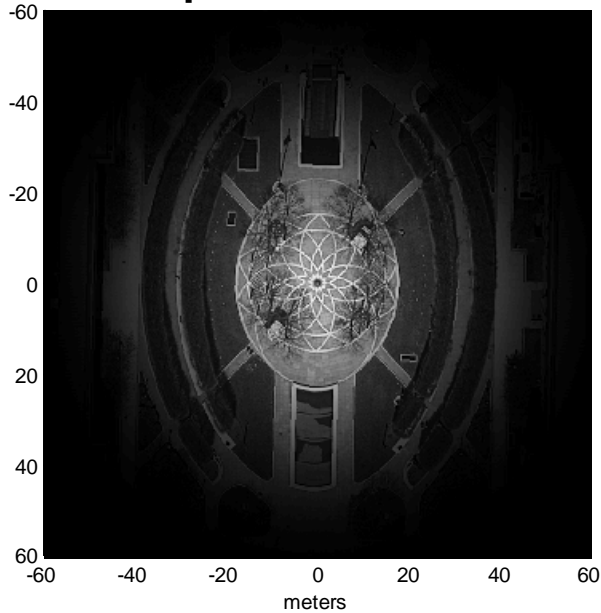
5. Reconstruct sub-image



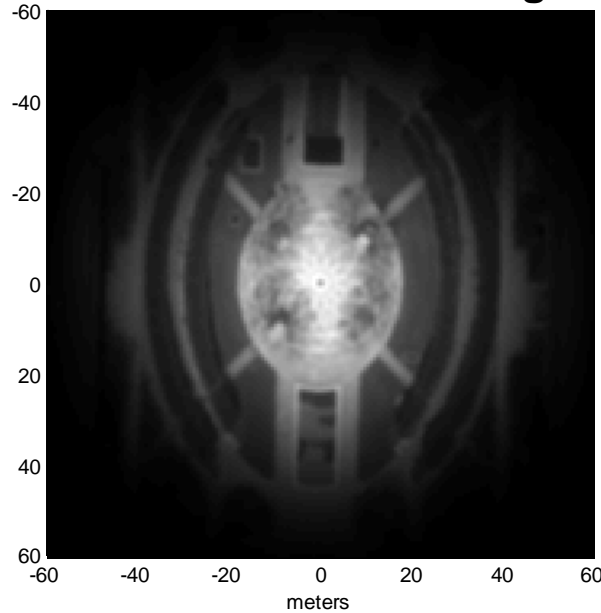
Sub-Image Comparisons



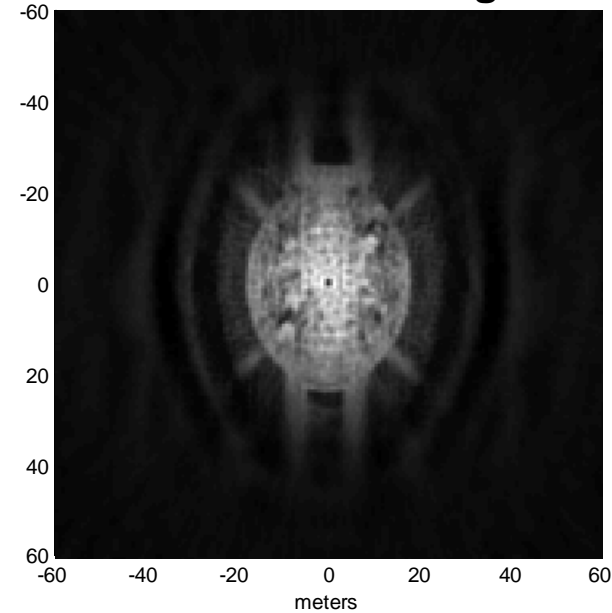
Apodized Scene



Conventional Sub-Image



SPIDER Sub-Image



***No Wiener filter applied**

SPIDER sub-image shows finer detail, but the point-spread function (PSF) sidelobes give a slightly noisy appearance (there was no measurement noise in the simulation)

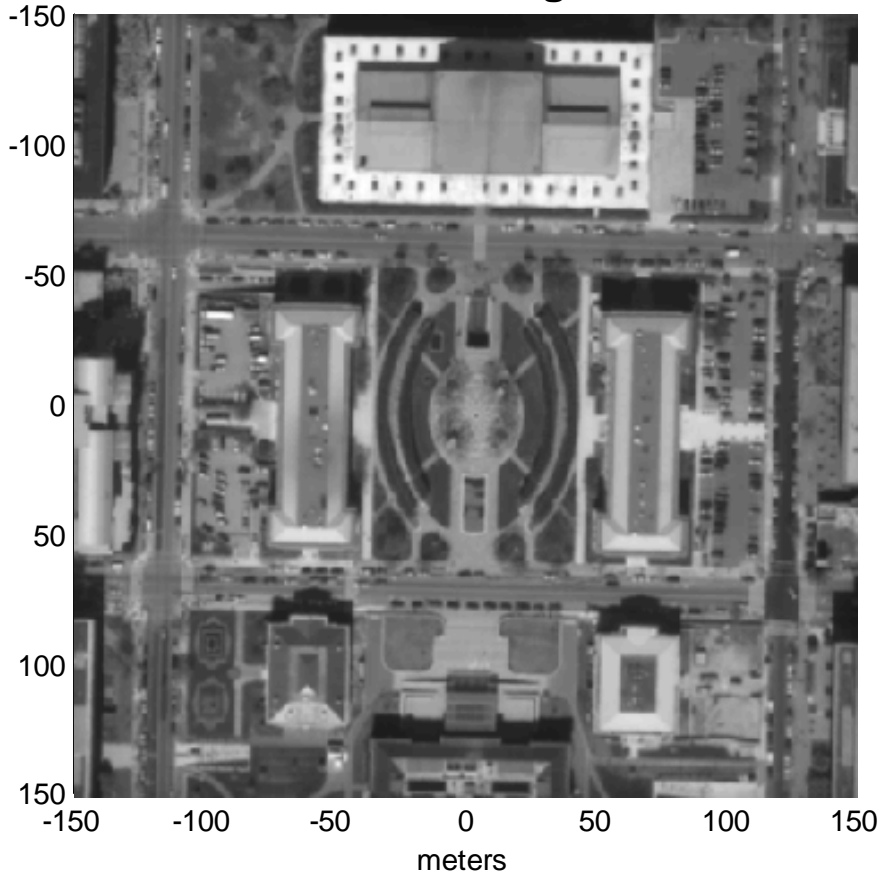
*Wiener filter is often used to remove blur in images due to linear motion or unfocussed optics

Lockheed Martin IRAD work

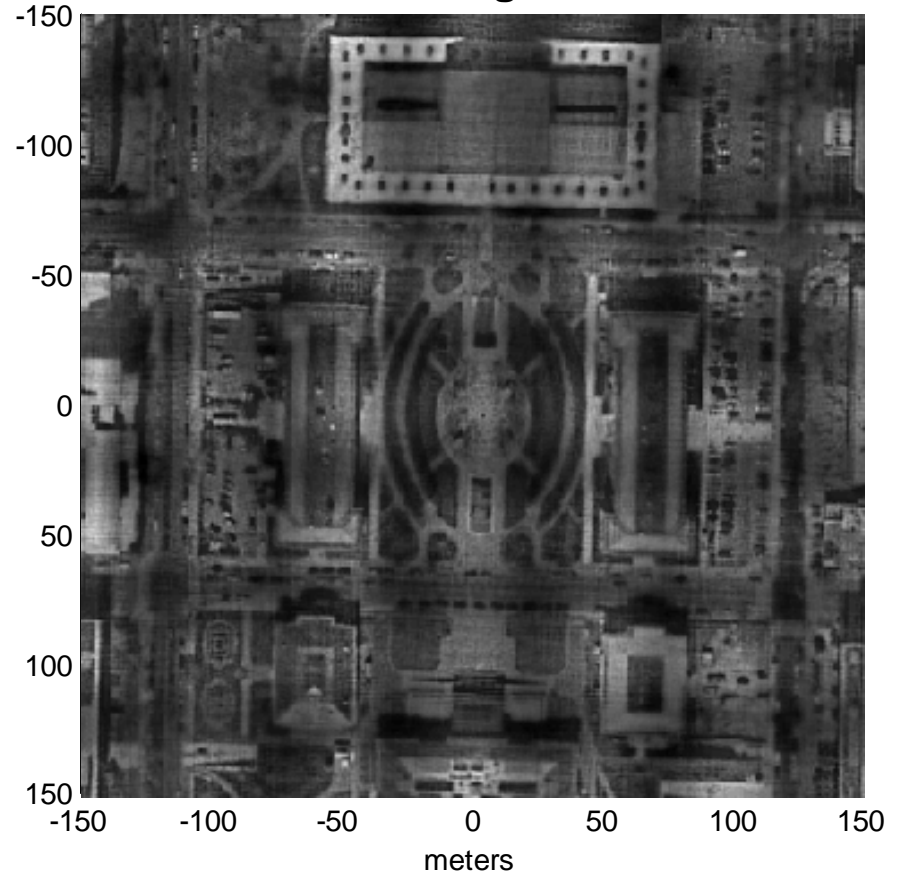
Image Mosaic Comparison



Conventional Image Mosaic



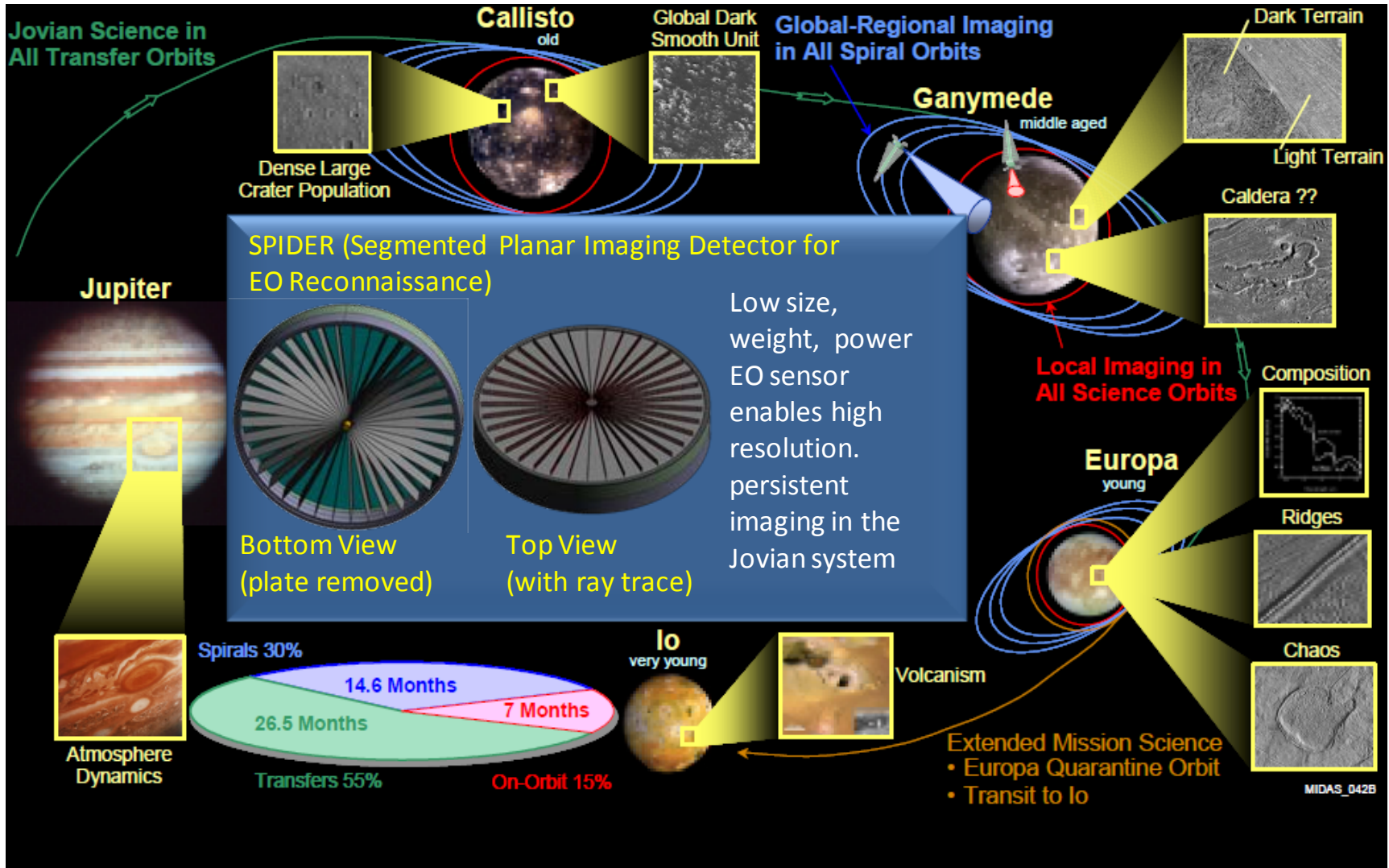
SPIDER Image Mosaic



The “banding” in the SPIDER image is likely due to the lack of low spatial frequency $u-v$ samples near DC

Lockheed Martin IRAD work

Jupiter Icy Moons Orbiter Reference Mission



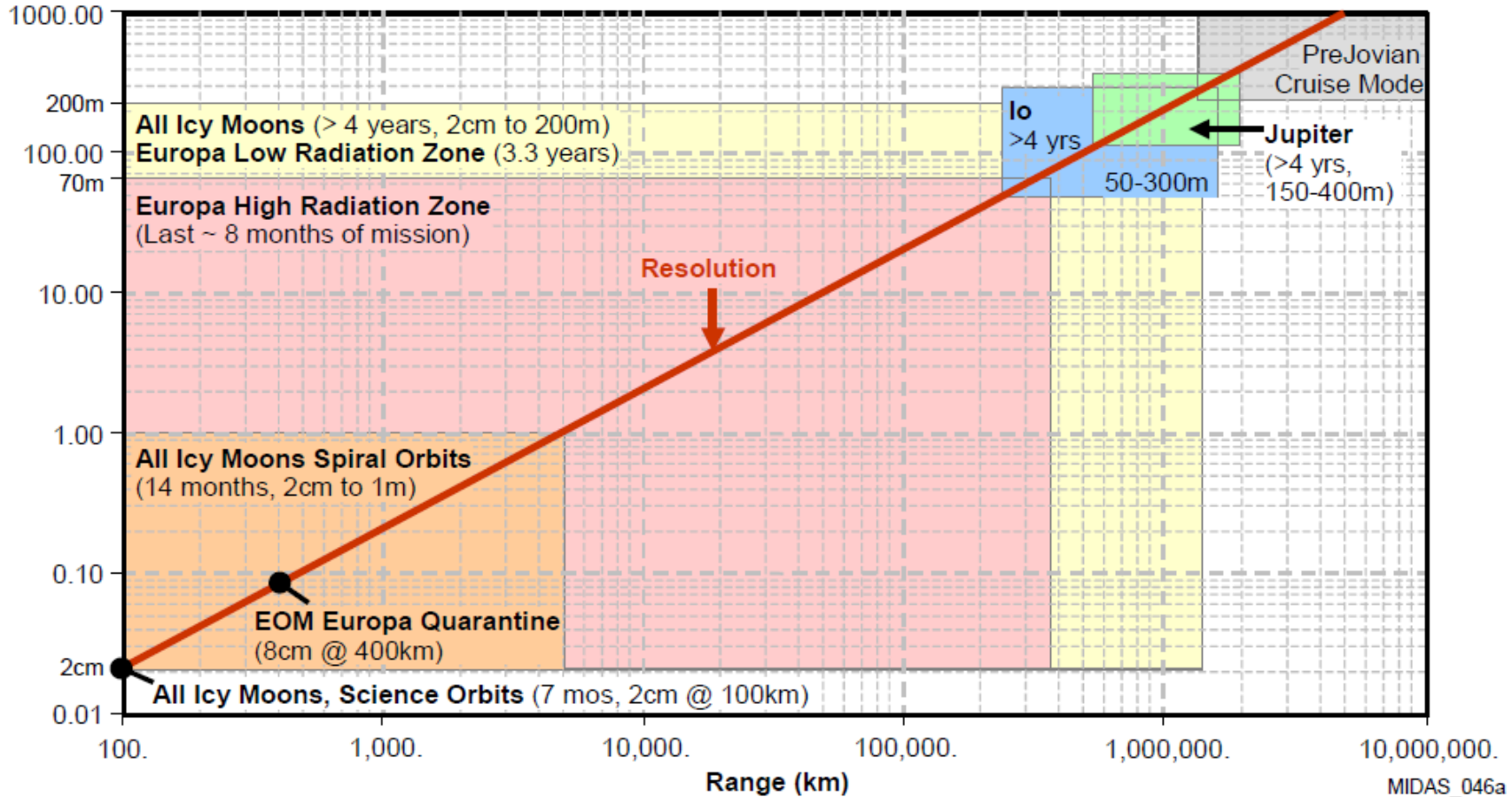
SPIDER Provides High Resolution Capability



1.5 m diameter aperture SPIDER

Resolution (meters)

Range of resolutions provided by SPIDER during 4 year Jovian mission



Europa Multiple Flyby Notional Topographical Imager (TI)



Europa Study 2012 Report – Europa Multiple Flyby Mission, JPL D-71990 (2012)

- **Proposed Traditional Imager**
 - 250 μ rad IFOV \rightarrow **25 m** Ground-Sampled-Distance (GSD) at 100 km
 - 4096 detectors, 5.5-ms integration time
 - **Push-broom mode collection**
 - **5x5x4-cm radiation shielded enclosure**
 - **2.5 kg unshielded mass**

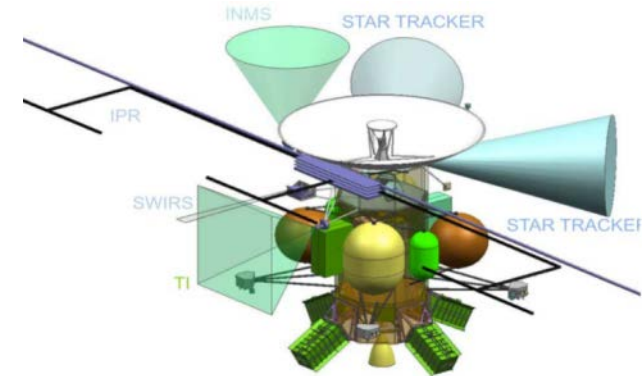
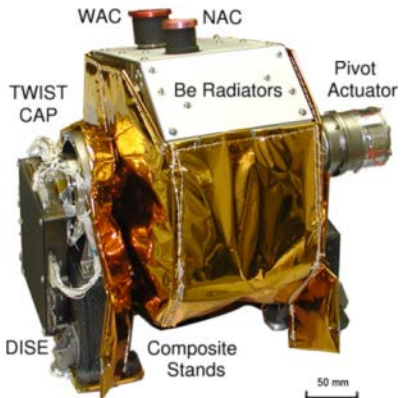
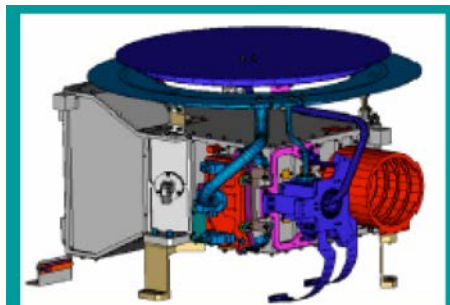


Figure C.2.2-1. Notional model payload accommodation and fields of view.

Similar Imagers



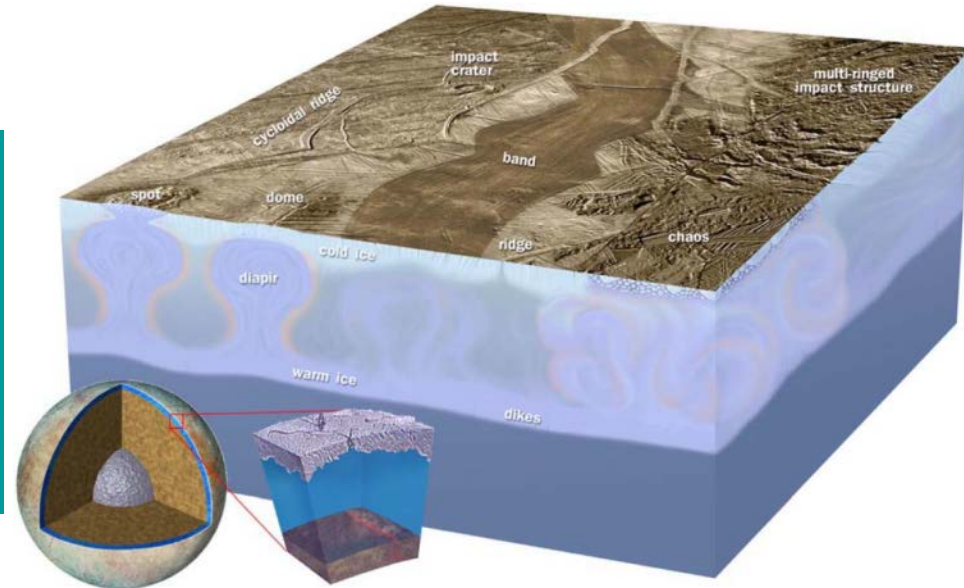
MRO Mars Color Imager (MARCI)



Ralph visible & IR imager, CBE mass 10.67 kg, power 5.3 W

New Horizons Multi-spectral Visible Imaging Camera (MVIC)

Diagram of Europa's ice shell



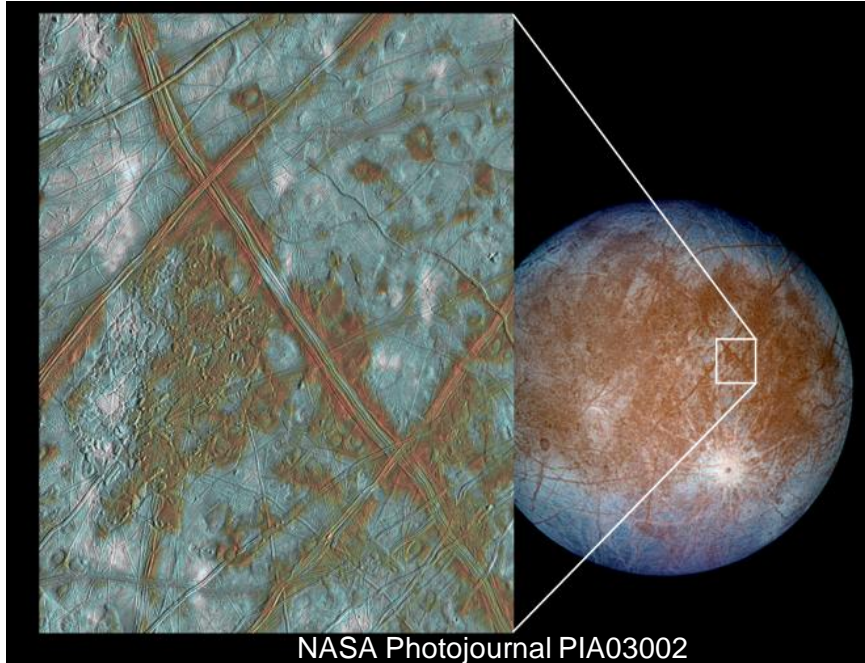
SPIDER-based Topographical Imager (TI)



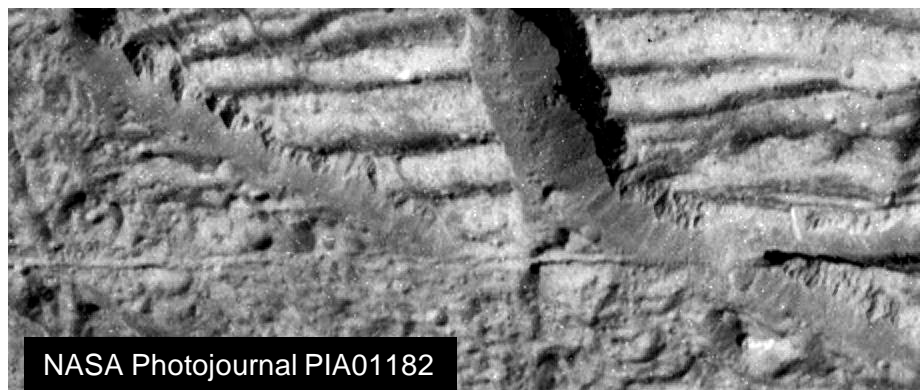
- SPIDER Topographical Imager
 - 4 cm diameter aperture (same enclosure)
 - 15 μ rad IFOV \rightarrow 1.5 m Ground-Sampled-Distance (GSD) at 100 km
 - 10 Mpixel area, 150-ms integration time



For the same mass, SPIDER could collect 10x the area on ground with 17x the resolution



NASA Photojournal PIA03002



NASA Photojournal PIA01182



Europa's Ridges

NASA Photojournal PIA00589

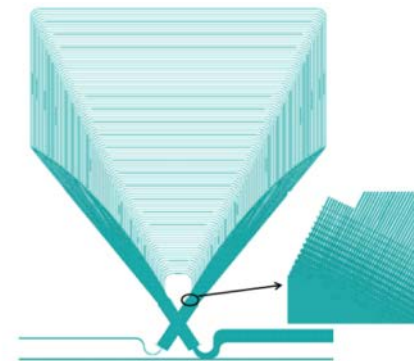
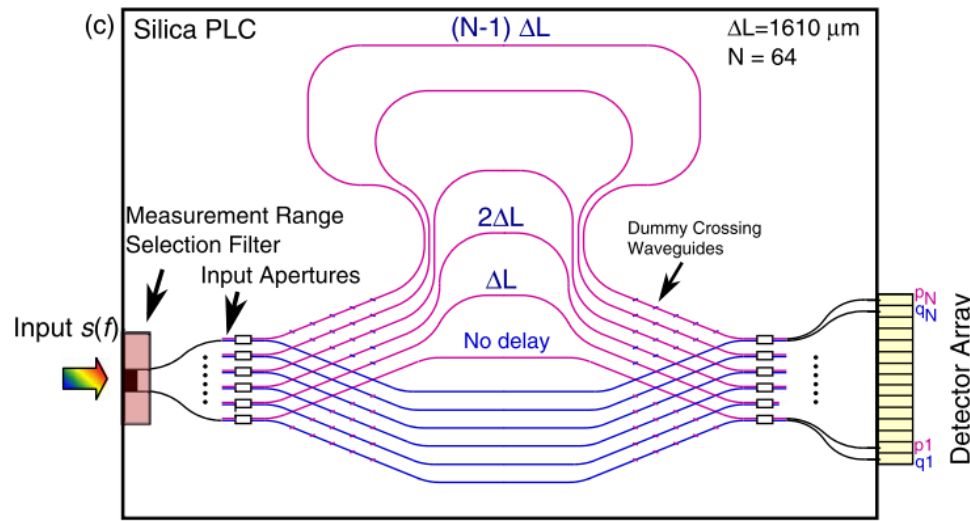
Ultrahigh Resolution Integrated Spectrometers

“Improved spectral observations at significantly higher spectral and spatial resolution than is presently available, together with detailed laboratory analyses under the appropriate temperature and radiation environment, are needed to fully understand Europa’s surface chemistry.”

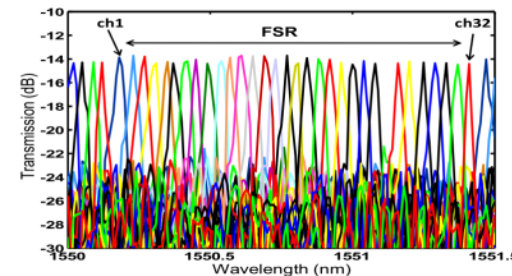
Europa Study 2012 Report – Europa Multiple Flyby Mission, JPL D-71990 (2012)

"Fourier-transform, integrated-optic spatial heterodyne spectrometer on a silica-based planar waveguide with 1 GHz resolution" by Nicolas K. Fontaine, Katsunari Okamoto, Tiehui Su, and S. J. B. Yoo, in *Optics Letters*, Vol. 36, No. 16, pp. 3124-3126, August, 2011.

5 GHz Channel Spacing InP-Based 32-Channel Arrayed-Waveguide Grating" by W. Jiang, K. Okamoto, F. M. Soares, S. Lourdudoss, and S. J. B. Yoo, in *OFC*, Paper OWO2, 2009.



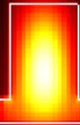
Number of Channels	32
Number of Arrayed Arms	104
Channel spacing (GHz)	5
Free spectral range (GHz)	160
Grating order	1095
Path length difference ΔL (μm)	527.142
Radius of slab region (μm)	3198.384
Bend radius of arrayed arms (μm)	500
Chip size (mm \times mm)	21 \times 22



Athermal Photonics and Spectrometers



Ridge height 250nm, ridge width 300nm, etch depth 250nm



$n_{eff} = 2.1669$, $n_g = 3.7392$,
 $A_{eff} = 0.224401$, $D = -6004.884$ ps/nm/km
 97% TE (3% minority field)
 FWHM horiz.= 92.5nm 1/e horiz.= 141.6nm

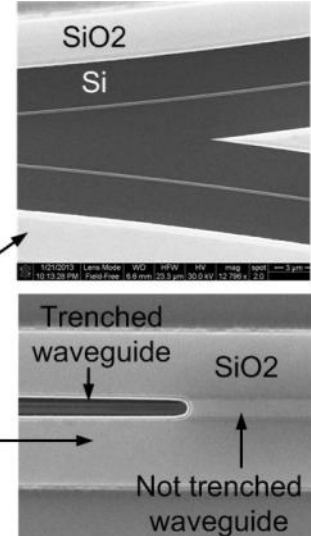
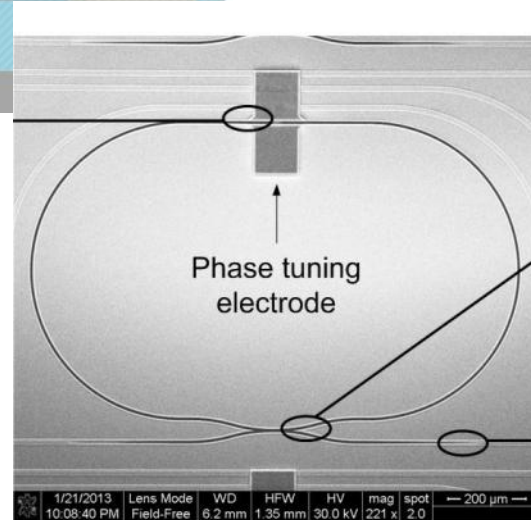
$$n_{eff} = \sum \Gamma_i \left(n_i + \frac{dn_i}{dT} \Delta T \right)$$

Athermalization means

$$\frac{dn_{eff}}{dT} = \sum \Gamma_i \left(\frac{dn_i}{dT} \right) = 0$$



BOx 3 μ m
 Substrate



	Thermo-Optic Coefficient (k ⁻¹)	Refractive index
Silicon	+1.8x10 ⁻⁴	3.467
SiO2	~ 10 ⁻⁵	1.444
PUA	-4.2x10 ⁻⁴	~1.45
TiO2	-3x10 ⁻⁴ -2.3x10 ⁻³	~2.483



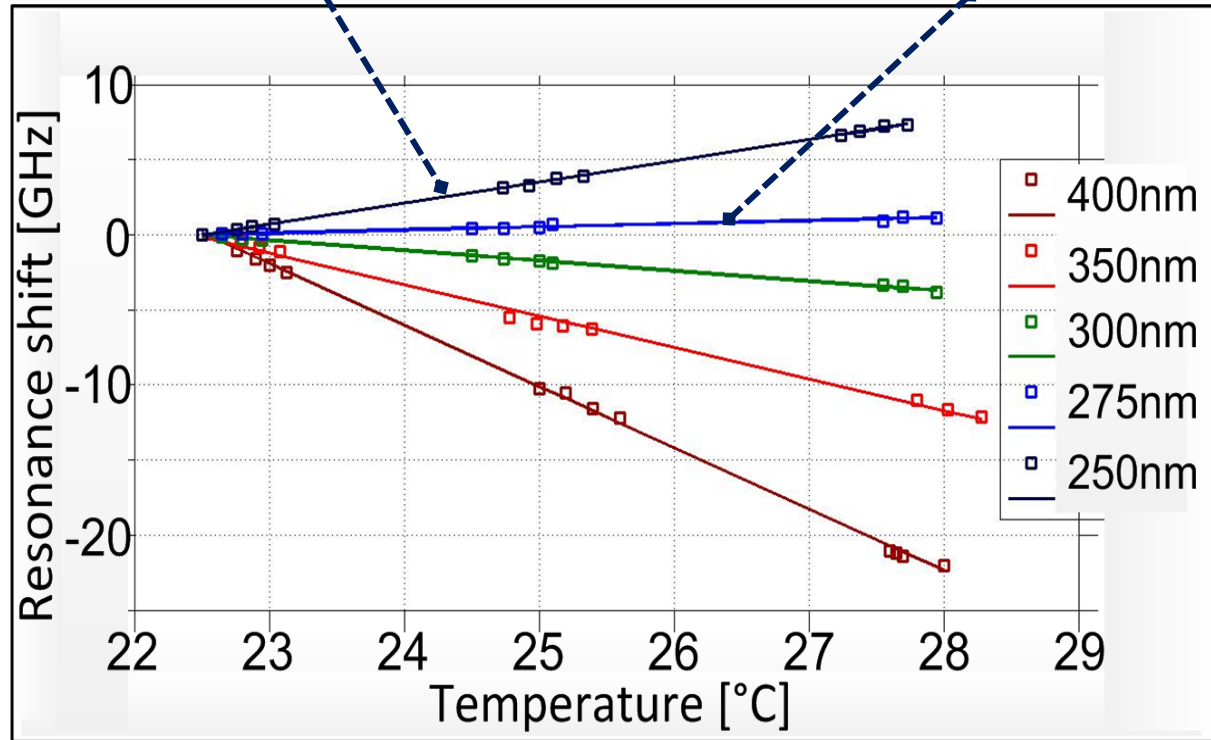
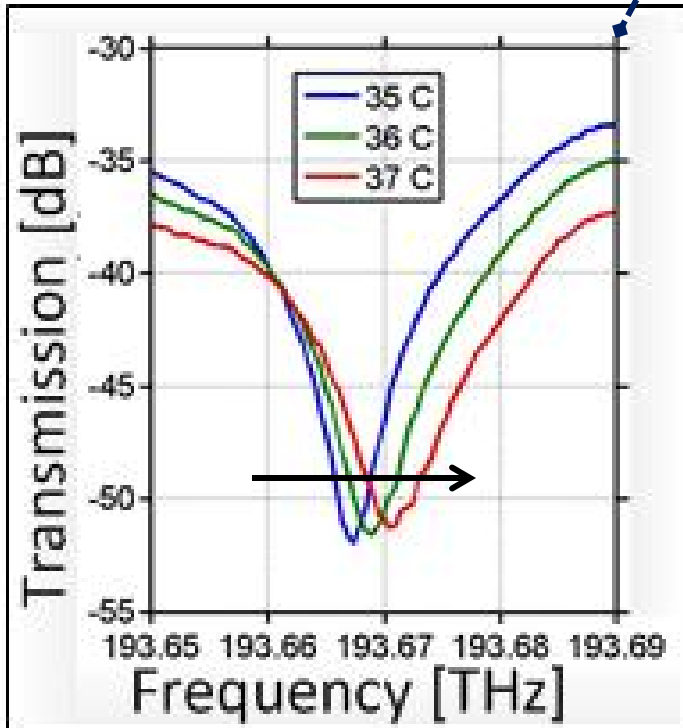
Athermal Photonics and Spectrometers

e.g. Silicon Photonic Resonator with TiO_2 overcladding

Ring resonator with 250nm wide waveguide

Blue shift
-11.3 pm/°C
(+1.41 GHz/°C)

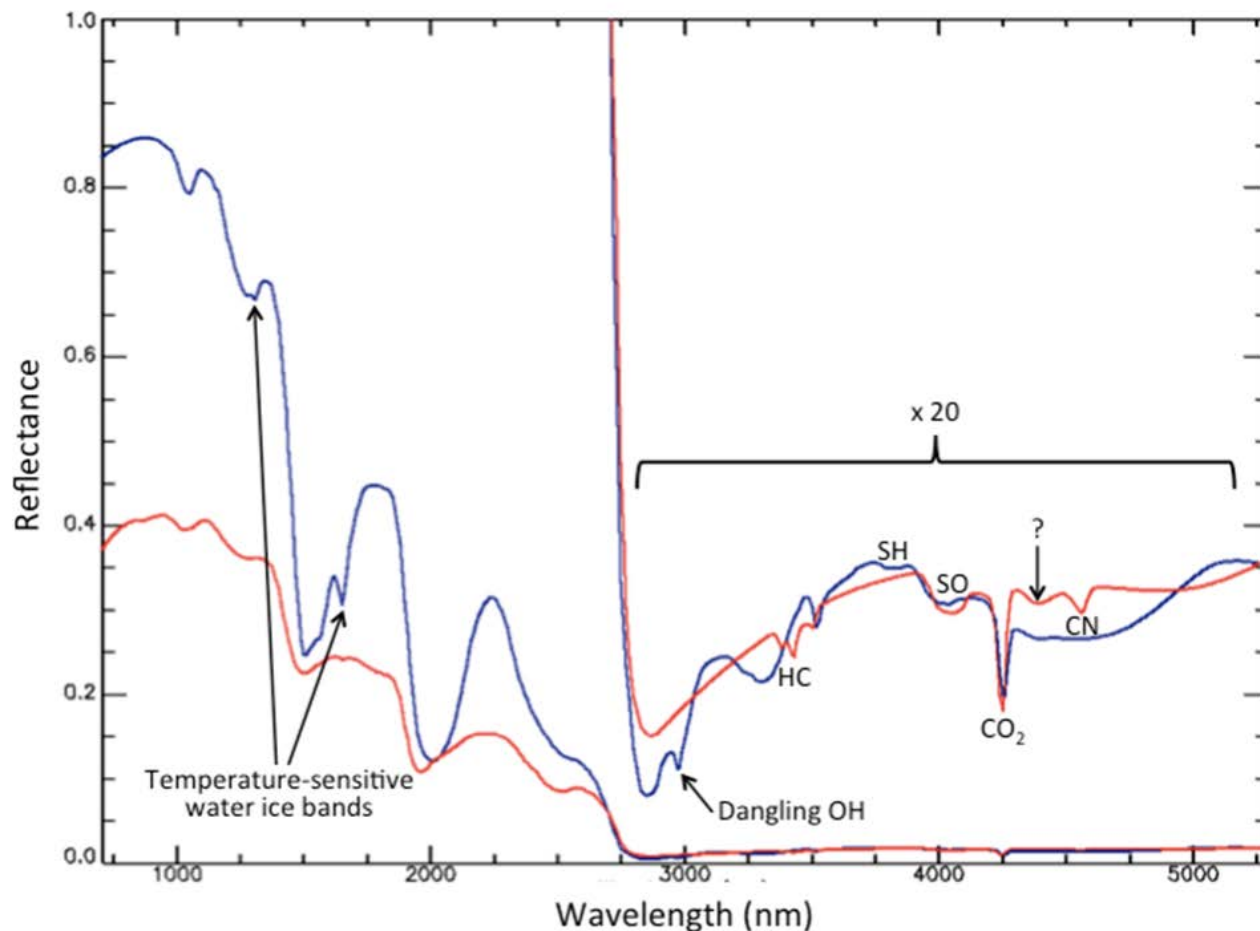
Blue shift
-1.60 pm/°C
(+0.20 GHz/°C)



Identifying Compounds on Europa

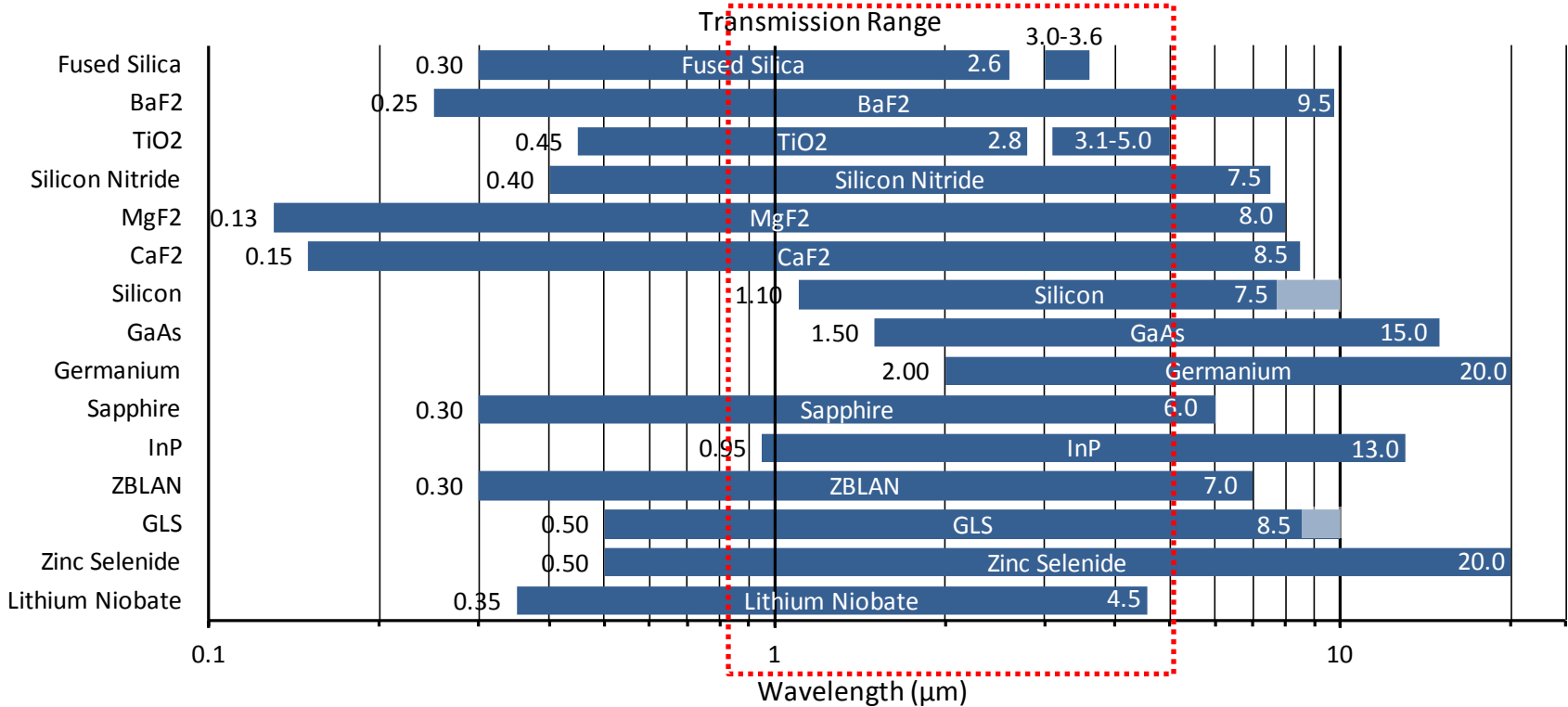


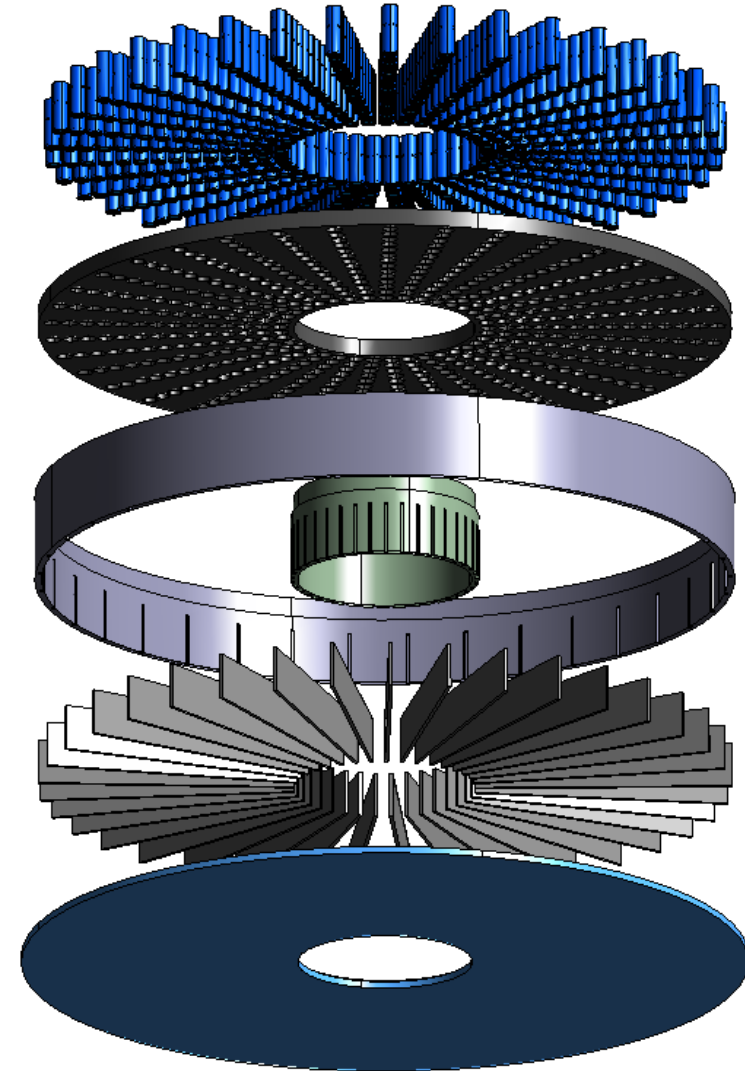
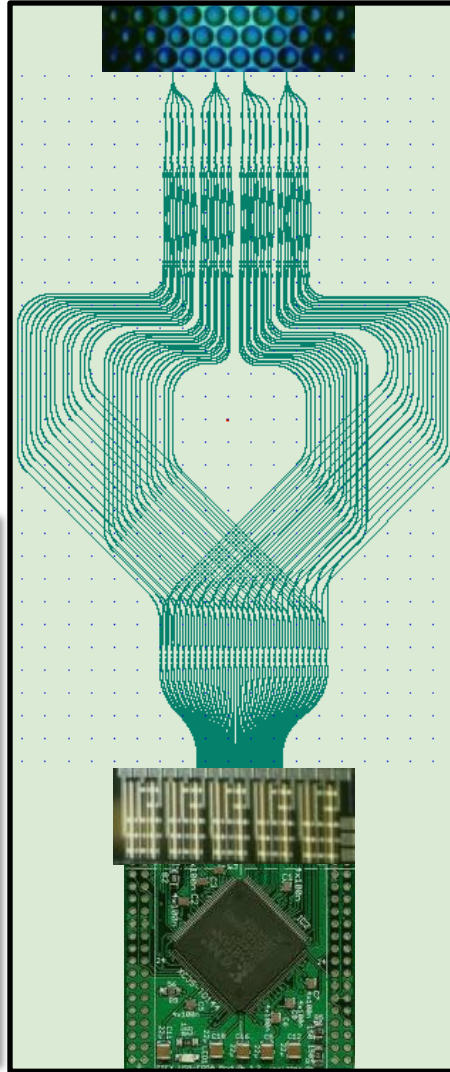
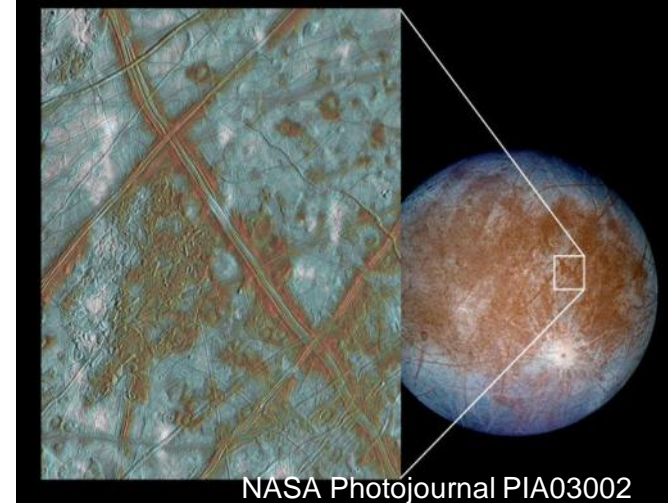
“Notional reflectance spectra for ice-rich regions (blue curves) and ice-poor regions (red curves) on Europa ... in the 1–5 μm spectral range.”



Europa Study 2012 Report – Europa Multiple Flyby Mission, JPL D-71990 (2012)

Transmission Range of Selected Materials







ID	Task	Objective	Benefit
1	Develop radiometry model of Europa	Provide input data to address required integration times for a realistic mission scenario (Europa Clipper).	Anchor results to a specific mission of interest (relevant to a broad class of “icy moons” type missions).
2	Develop SPIDER design	Tailor our design for the Europa Clipper reference mission to show potential and identify key technologies.	Showcase low cost and SWaP.
3	Evaluate various PIC material platforms and architectures	Provide data on waveguide coupling efficiencies and device losses to improve SPIDER model	Quantifies performance limitations due to current technology constraints.
4	Develop image reconstruction algorithm	Adapt existing algorithms to optimize performance for Europa reference mission.	Increases fidelity of critical algorithm required to generate science products.
5	Develop SPIDER model (predict raw signal characteristics including SNR)	Provide realistic data to enable high fidelity predictions of sensor performance.	Addresses performance limitations due to fundamental physics constraints.
6	Perform image simulations and evaluate predicted performance	Provide quantitative performance predictions to assess feasibility of meeting science goals.	Forms the basis for scaling design and performance to a broad class of imaging missions.
7	Develop a technology roadmap	Identify technology needs and provide a roadmap to guide further investigation and to show where there is significant leverage of existing technology.	Minimize development cost by leveraging Lockheed Martin IRAD, commercial industry and DARPA investments.