

# **Restore-L Mission Information**

Package for NASA Solicitation #NNH15HEOMD001 Spacecraft Bus Concepts To Support The Asteroid Redirect Robotic Mission And In Space Robotic Servicing

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### Content



This package contains relevant information about the NASA Restore-L mission concept to aid potential respondents to NASA Solicitation #NNH15HEOMD001.

### **Outline of contents:**

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- Restore-L Concept of Operations
- Restore Servicing Vehicle Notional Design
- Bus High-Level Requirements
- Servicing Payload Description
- Servicing Payload (SP) Mass and Power Budgets

All images are notional and all content is in draft form.

### **Overview of NASA's In Space Robotic Servicing Efforts**



### **Concept/Tech Development**

### **Mission Concept Studies**



**Restore-G** 2009-2014 study. GEO servicer.



**Restore-L** 2014 onwards study. LEO servicer.

### **Technology Development Areas**



#### **Restore Reviews**

Systems Engineering Aug 2012

Payload Systems Requirements Mar 2013

#### **Community Engagement & Research**

### **RFIs & RFQs**



### Ongoing engagement with:

- Legal community
- Investment bankers
- Commercial bus manufacturers
- Fleet owners/operators

# International Workshops 2010 & 2012



http://ssco.gsfc.nasa.gov/

# **Restore-L Mission Overview**

# NASA

### **Mission Objectives**

- Refuel Government-owned client satellite in low Earth orbit (LEO)
  - Notional client: Landsat 7
- Technology demonstration mission
  - Advance robotic servicing technologies to operational status
- Program Option to service additional satellites



Restore Servicing Vehicle (RSV) (bottom, with conceptual Bus shown) mated to notional client (top)

# **Restore-L Concept of Operations**



# **Restore-L High-Level Requirements**



Title	Description			
Design Life	Restore-L shall have a primary mission lifetime of 1 year.			
Rendezvous and Inspection	Restore-L shall rendezvous with and inspect a client satellite in Low Earth Orbit (LEO).			
Autonomous Capture	Restore-L shall perform an autonomous capture of a client satellite.			
Teleoperated Robotics	Restore-L shall perform teleoperated robotic servicing tasks.			
Refueling	Restore-L shall refuel a Government-owned satellite in LEO.			
Relocation	Restore-L shall demonstrate relocation of a client satellite.			
Re-deploy	Restore-L shall release and safely depart from a client satellite.			

# **Restore Servicing Vehicle – Notional Design**



### Servicing Payload

 Government Furnished Equipment



### Spacecraft Bus\*

- Electrical Power System
- Mechanical
- Propulsion
- Communication
- Data
- Thermal

\*See Bus functions on next slide

# **Bus High-Level Functions**



### **Electrical Power System**

- Support Servicing Payload Power (see Power Budget, slide 9)
- Low Voltage 28 + 4 VDC
- High Voltage 100 + 10 VDC
- Prime and Redundant Heater power
  - Native Bus voltage
  - Approximately 60 heater services

### Mechanical

 Support Servicing Payload Mass (see Mass Budget, slide 9)

### Propulsion

- 6-DOF chemical maneuverability
- Program Option: reduced-performance
  version of the ARRM SEP system

### Communication

- Assumes bus carries communication mass and power
- S-band low data downlink / high rate uplink for robot teleoperations
- Ka-band high data rate for video / TLM
- CCSDS protocols
- Encryption

### Data

- MIL-STD-1553B, RS-422, and/or RS-485 for bus-payload CMD & TLM interface
- LVDS for high speed data

### Thermal

- Payload thermally isolated from Bus
- Bus controls heaters on payload

# **Servicing Payload (SP) Mass and Power Budgets**



### SP Mass Budget

	Total Mass CBE* (kg)	Total Mass MEV** (kg)	
Client transferred hydrazine (per client)	100	100	
SP Total (dry)	785	940	
SP Total (wet)	885	1040	

No contingency

With contingency

\*CBE: Current Best Estimate

\*\*MEV: Maximum Expected Value

### **SP Power Budget**

	Heaters Only (W)	Rendezvous*** (W)	Capture*** (W)	Robotic Ops*** (W)	Refueling*** (W)
Total Avg.	540	870	1340	1055	1065
Total Peak	540	870	1790	1495	1145

\*\*\*Includes heater power