EXECUTIVE BRIEFING

URBAN AIR MOBILITY (UAM) MARKET STUDY

Presented to: National Aeronautics and Space Administration - Aeronautics Research Mission Directorate

OCTOBER 5, 2018
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Introduction
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This document is confidential and intended solely for the client to whom it is addressed.
EXECUTIVE SUMMARY

Our analysis focused on three potential UAM markets: Airport Shuttle, Air Taxi, and Air Ambulance using ten target urban areas\(^1\) to explore market size and barriers to a UAM market. Our results suggest the following:

- Airport Shuttle and Air Taxi markets are **viable markets** with a significant total available market value of \(\$500B\)^2 at the market entry price points in the best-case unconstrained scenario

- Air Ambulance market served by eVTOLs is **not a viable market** due to technology constraints, but utilization of hybrid VTOL aircraft would make the market potentially viable

- Significant legal/regulatory, certification, public perception, infrastructure, and weather constraints exist which reduce market potential in near term for UAM

- After applying operational constraints/barriers, **0.5% of the total** available market worth \(\$2.5B\) can be captured in the near term

- Constraints can potentially be addressed through ongoing intragovernmental partnerships (i.e., NASA-FAA), government and industry collaboration, strong industry commitment, and existing legal and regulatory enablers

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\(^1\) New York, Washington DC, Miami, Houston, Dallas, Denver, Phoenix, Los Angeles, San Francisco, Honolulu

\(^2\) US Domestic Airline industry has an annual market value of \(\sim150B\) (Ibis, 2018)
### EXECUTIVE SUMMARY - CONSTRAINTS

**UAM MARKETS FACE SIGNIFICANT CHALLENGES AND CONSTRAINTS**

**Near Term - Immature Market**

<table>
<thead>
<tr>
<th>Technology Challenges</th>
<th>Non-Technological Challenges</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Economics:</strong> High cost of service (partially driven by capital and battery costs)</td>
<td><strong>Infrastructure:</strong> Lack of existing infrastructure and low throughput</td>
</tr>
<tr>
<td><strong>Weather:</strong> Adverse Weather can significantly affect aircraft operations and performance</td>
<td><strong>Competition</strong> from emerging technologies and concepts like shared Electric and Autonomous Cars, and fast trains</td>
</tr>
<tr>
<td><strong>Air Traffic Management:</strong> High density operations will stress the current ATM system</td>
<td><strong>Weather</strong> conditions that could compromise safety</td>
</tr>
<tr>
<td><strong>Battery Technology:</strong> Battery weight and recharging times detrimental to the use of eVTOLs for Air Ambulance market</td>
<td><strong>Social Mobility:</strong> New importance of travel time, increase in telecommuting, urbanization and de-congestion scenarios could reduce the viability of markets</td>
</tr>
<tr>
<td><strong>Impacts:</strong> Adverse energy and environmental impacts (particularly, noise) could affect community acceptance</td>
<td><strong>Preferences</strong> to fly with others they know in an autonomous UAM</td>
</tr>
</tbody>
</table>

**Longer Term - Mature Market**

| Impacts: Energy and Environmental Impacts of large-scale operations |
| Cybersecurity of Autonomous systems including vehicles and UTM |
| **Weather:** Disruptions to operations during significant adverse conditions |
| **New Entrants:** Large scale operations of new entrants like UAS, Commercial Space operations, private ownership of UAM vehicles could increase the complexity of airspace management and safety |

- **Infrastructure:** Lack of existing infrastructure and low throughput
- **Competition** from existing modes of transportation
- **Weather** conditions that could compromise safety
- **Public Perception:** Passengers concerned about safety and prefer security screening and preference UAM only for longer trips
- **Laws and regulations** for flying over people, BVLOS, and carrying passengers (among others) are needed
- **Certifications:** Gaps in the existing certification framework where UAM will experience challenges, particularly system redundancy and failure management

- **Weather:** Increase in some adverse conditions due to climate change may limit operations
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URBAN AIR MOBILITY ECOSYSTEM INCLUDES CITY CENTER, SUBURBAN AND EDGE CITY

AN EMERGING MODE OF TRANSPORTATION, THE SPECIFICS OF UAM ARE YET TO BE DEFINED

NASA defines UAM as a safe and efficient system for air passenger and cargo transportation within an urban area, inclusive of small package delivery and other urban Unmanned Aerial Systems (UAS) services, that supports a mix of onboard/ground-piloted and increasingly autonomous operations.

THE PROMISE OF URBAN AIR MOBILITY

- Decongest Road Traffic
- Improve Mobility
- Reduce Transport Time
- Decrease Pollution
- Reduced Strain on Existing Public Transport Networks
- Reduce Traffic Accidents

CITY CENTER

High-density downtown employment centers and surrounding neighborhoods

SUBURBAN

Predominantly lower density residential neighborhood with some mixed use facilities

EDGE CITY

Medium-density employment centers outside of the urban core

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UAM CONCEPT IS ENABLED BY KEY TRENDS

- **70+ manufacturers** worldwide including Boeing, Airbus and Bell Helicopters
- **Over $1 billion investment** made as of September 2018
- **High profile events** organized around the world in 2018 e.g. Uber Elevate (1200+ attendance, 10k+ online participants), LA City’s mayor gathering, etc.
STRATEGIC ADVISORY GROUP (SAG)

SAG
- The SAG is a diverse and independent group of Urban Air Mobility and/or related market experts and stakeholders that will inform key decision points in the project and help refine the market assessment methodology based on their expertise in the UAM space.

OBJECTIVES
- Create a community of UAM experts to inform strategic discussion.
- Review project analysis and conclusions.
- Validate the market assessment methodology.
- Inform key decision points.

Note: Details about members available in Appendix 1.
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THREE FOCUS MARKETS

OUR METHODOLOGY CENTERS ON EVALUATING MARKETS WITH INTERESTING BARRIERS

As we walk through our process, the team screened and prioritized markets that will be most relevant for further study as part of the initial and final assessments.

### STEP 1: IDENTIFY MARKETS

<table>
<thead>
<tr>
<th>Market Category</th>
<th>Market Type</th>
<th>Category</th>
</tr>
</thead>
<tbody>
<tr>
<td>First Response  (Public Services)</td>
<td>Ambulance</td>
<td>Natural Disaster and Armed Conflict Response</td>
</tr>
<tr>
<td>Air Commute</td>
<td>Privately Owned Train</td>
<td>Taxi</td>
</tr>
<tr>
<td>Air Shuttle</td>
<td>Air Taxi (Mass Market)</td>
<td>Company Shuttle</td>
</tr>
<tr>
<td>Entertainment and Media</td>
<td>Film/TV/Radio Stations</td>
<td>Tourism</td>
</tr>
<tr>
<td>Real Estate and Construction</td>
<td>Aerial Showcasing, Inspections And Survey</td>
<td></td>
</tr>
<tr>
<td>Asset/Building Maintenance</td>
<td>Utilities asset maintenance</td>
<td></td>
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</tbody>
</table>

### STEP 2: MARKET CALIBRATION CRITERIA

<table>
<thead>
<tr>
<th>Market Summary</th>
<th>Market Size</th>
<th>Overall market size of legacy market in 2017</th>
</tr>
</thead>
<tbody>
<tr>
<td>Market Growth Rate</td>
<td>Expected growth rate of legacy market</td>
<td></td>
</tr>
<tr>
<td>Technology Cost</td>
<td>Price point for legacy technology, R&amp;D, Capital and Operating cost</td>
<td></td>
</tr>
<tr>
<td>Challenges</td>
<td>Willingness to Pay, Competitive Price Pressure, Investments</td>
<td></td>
</tr>
<tr>
<td>Societal</td>
<td>Noise annoyance and community acceptance</td>
<td></td>
</tr>
<tr>
<td>Legal &amp; Regulatory</td>
<td>Air Traffic Management, Local, state and federal laws</td>
<td></td>
</tr>
</tbody>
</table>

### STEP 3: SCREENED MARKETS

- Airport Shuttle (Early Market)
- Air Taxi (Mass Market)
- Air Ambulance (Complex Market)

Note: Detailed Methodology available in Market Selection Deliverable
FOCUSED TEN URBAN AREAS

All analysis is focused on the following ten urban areas from a shortlisted pool of 40 urban areas. These 10 urban areas are representative of the US and will illuminate a wide set of barriers for UAM that could be operated with human pilots or autonomously.

Note: Detailed Methodology available in Initial Analysis Deliverable
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LEGAL AND REGULATORY BARRIERS - SUMMARY

• Surveyed and analyzed the Federal Acts, Federal regulations, State laws, and local ordinances for each of the three UAM urban markets, identified legal barriers, along with the gaps and path to certification.

• Air Taxi, Ambulance, and Airport Shuttle UAM markets share common regulatory barriers.

• There will be challenges in determining which of the existing FAA certification standards apply to the types of vehicles being considered for the Air Taxi or Air Ambulance UAMs, and/or how existing certification standards can be met or should be amended.
  - Air Ambulances will require further evaluation due to the requirements of an operator’s air ambulance procedures and air-ambulance-specific sections of their General Operations Manual (GOM).

• Gaps in current certifications mean that new standards will need to be developed, especially in areas related to system redundancy and failure management.

*Additional details on the legal and regulatory analysis can be found in the accompanying ‘Legal/Regulatory – Interim Analysis’ document.
LEGAL AND REGULATORY BARRIERS

Air Taxi, Ambulance, and Airport Shuttle UAM Markets share common Regulatory Barriers

Remotely piloted and autonomous UAM markets require the following aviation regulations (either modification of existing regulations, or new regulations), as the current regulatory structure does not fully allow for these activities to be performed:

- Regulations for beyond visual line of sight (currently only with lengthy waiver process)
- Regulations for operations over people, streets, etc. (currently only with lengthy waiver process)
- Regulations for when air cargo is being carried commercially and across state lines
- Regulations for when a passenger or patient is being transported in a UAM (remotely or autonomously piloted) either within visual line of sight or beyond
- Regulations for flight in instrument conditions
- Regulations for airworthiness certification of remotely piloted and autonomous aircraft
- Training and knowledge requirements for pilots and operators

A legal framework for addressing privacy concerns should be developed outside of the aviation regulatory framework.
STATE AND LOCAL LAWS – RANGING FROM NO DRONES TO PROTECTING UAS OPERATIONS

California has a law favoring first responders
• In 2016, SB 807 was chaptered - Provides immunity for first responders who damage a UAS that was interfering with the first responder while he or she was providing emergency services.
• AB 1680 – Makes it a misdemeanor to interfere with the activities of first responders during an emergency.

Hawaii has a law that prohibits UAS except for law enforcement
• SB 2608 – Prohibits the use of unmanned aircraft, except by law enforcement agencies, to conduct surveillance and establishes certain conditions for law enforcement agencies to use an unmanned aircraft to obtain information.

Arizona has a law favoring first responders
• In 2016, SB 1449 – Prohibits certain operation of UAS, including operation in violation of FAA regulations and operation that interferes with first responders. The law prohibits operating near, or using UAS to take images of, a critical facility. It also preempts any locality from regulating UAS.

Colorado – None

Texas
• HB 1424 – Prohibits UAS operation over correctional and detention facilities. It also prohibits operation over a sports venue except in certain instances.
• HB 1481 makes it a Class B misdemeanor to operate UAS over a critical infrastructure facility if the UAS is not more than 400 feet off the ground.

Florida
• SB 92 – Prohibiting a law enforcement agency from using a drone to gather evidence or other information.

Washington, DC has a no drone zone.

New York, NY – Drones are more formally known as unmanned aerial vehicles (UAV) and are illegal to fly in New York City.
CERTIFICATION GAPS AND STRATEGIES

There are some gaps in the existing certification framework where UAM will experience challenges, particularly along system redundancy and failure management:

• The standards and methods required to meet **system redundancy and failure management** requirements for complex software could be onerous to meet (e.g., DO-178C testing requirements for the large number of states **automation software** can take)

• A **multi-copter** will need a standard for how subsystems, such as distributed electric propulsion and energy storage, will address **redundancy and failures** (e.g., helicopters may have redundant engines and can autorotate to handle certain failures)

• Determining the **standard for a failure scenario for an autonomous vehicle** (e.g., will a pilot or remote operator need to be available to take over, and what are the medical requirements for any “pilot/operator”)

• Defining **how an autonomous vehicle makes judgements in a failure scenario**, based on the literal standard, such as when to “land immediately,” vs. “when practical,” vs. “closest available airport” in the context of the operating environment

Strategies to enable certifications by considering existing framework:

• We reviewed **domestic and international (e.g., EASA, NATO) airworthiness regulations** and supporting industry standards and identified potential strategies

• **Strategies depend on vehicle characteristics**, such as propulsion and aircraft design, and may leverage Part 21.17(b) to take portions of **Parts 23, 27, 33, and 35**. Platforms similar to ZeeAero may be closer to Part 23 than 27, while Volocopter-like designs may borrow more from Part 27.

• **Part 23 amendment 64** provides great flexibility for SDOs to develop new technology requirements to support certification. ASTM, SAE, RTCA are actively working on standards in many topics that will benefit UAM airworthiness.
KEY FINDINGS

Enabling UAM highlights critical legal, regulatory, and certification challenges that must be addressed in order to bring urban air transportation to the market. This analysis draws comparison of legal and regulatory challenges for enabling UAM with Unmanned Aircraft Systems (UAS).

- **Legal Environment**: Dynamic legal environment with many unresolved challenges, especially establishing where federal, state, and local authorities take lead

- **Breadth of Challenges**: UAM pose legal challenges that touch on most aspects of aviation, especially in the areas of air traffic control and management and flight standards, but also environmental policy, public use, land use, and local restrictions.

- **Legal Barriers for Remotely Operated and Automated Piloting System**: Current legal framework does not address issues related to operations over people, beyond visual line of sight, commercial operations carrying cargo or people, and airworthiness certifications. Assured autonomy remains a challenging technical and legal problem.

- **Diversity in Approaches**: States and locales are undertaking legal experiments through a mix of approaches, ranging from designating UAS launch sites to hyperlocal restrictions. **State and local laws** range from laws prohibiting drones to laws protecting UAS operations.

- **Certification**: Many efforts are underway at FAA, ASTM, RTCA, SAE, and elsewhere to provide **methods of aircraft certification for UAM**, but there is still no clear certification path and several gaps in means of compliance. Opportunities may exist to:
  - Develop a roadmap to airworthiness that considers the range of potential UAM aircraft and paths to certification
  - Study and leverage international efforts (e.g., NATO, EASA)
  - Study and leverage efforts from similar domains, such as autonomous cars (e.g., SAE Validation and Verification Task Force)
  - Explore other certification challenges for operator and operations certification.

- **Strategies moving forward**: Enabling strategies can be employed to **accelerate the development** of a UAM legal framework:
  - NASA – FAA cooperation, such as the Research Transition Teams
  - FAA Aviation Rulemaking Committee
  - FAA UAS Integration Pilot Program
  - Leveraging strategies from automobile automation, such as voluntary standards may help UAM deployment
SOCIETAL BARRIERS – KEY FINDINGS

Key Concerns:

• Safety
  - Unruly and/or violent passengers
  - “Lasing”
  - Aircraft sabotage (by passengers or people on the ground)
• Privacy and Noise
• Preference for piloted aircraft
• Presence of flight attendant did not impact willingness to fly for automated or remote piloted UAM aircraft
• A flight attendant did increase confidence in automated and remote piloted operations from the non-user perspective (someone on the ground)
• Preference for short inter-regional travel
  - DC to Baltimore; LA to San Diego
• Possible market for peer-to-peer (P2P) operations that could provide additional supply to scale a UAM market (similar to Lyft and Uber)
SOCIETAL BARRIERS – METHODOLOGY

• **Research Process**
  - Literature Review, Focus Groups, Survey

• **Why Do We Do Research on Societal Barriers?**
  - Understand potential viability of use cases, business model, partnership, and impacts
  - Identify problems to address, hypotheses, and/or key metrics
  - Predictive understanding of supply/demand patterns
  - Inform proactive policy development (maximize benefits and minimize adverse effects)

• **How Do We Conduct Research on Societal Barriers?**
  - Self-reported surveys can inform how public could respond to the advent of an innovative transportation technology, such as UAM
OVERVIEW OF THE STEPS FRAMEWORK

STEPS Framework was developed by the Booz Allen Hamilton and TSRC, UC Berkeley team for the USDOT to guide assessments on societal barriers for innovative and emerging transportation technologies.

- **Spatial:** Factors that compromise daily travel needs (e.g., excessively long distances between destinations, lack of public transit within walking distance)
- **Temporal:** Travel time barriers that inhibit a user from completing time-sensitive trips, such as arriving to work (e.g., public transit reliability issues, limited operating hours, traffic congestion)
- **Economic:** Direct costs (e.g., ownership, operational, and indirect costs) and indirect costs that create economic hardship or preclude users from completing basic travel
- **Physiological:** Physical and cognitive limitations that make using standard transportation modes difficult or impossible (e.g., infants, older adults, and disabled)
- **Social:** Cultural, perceptions, safety, security, and language barriers that inhibit a user’s comfort with using transportation (e.g. Am I safe sharing this mode with other passengers that I don’t know?)

*Note: With UAM, trip length/range is both spatial and temporal factor (distance and flight time)*
SOCIETAL BARRIERS – KEY FINDINGS FROM LITERATURE

Public Perception (Based on Existing Literature):

- **Trust in Automation/Airaviation Systems**: Passengers are less willing to fly on-board a solely automated aircraft as compared to the hybrid cockpit or the traditional two-pilot cockpits.
- **Trust in Automation Based on Branding**: Differences in people’s trust of the system based upon whether the system was made by a well-known company vs. a “small, startup company.”
- **Trust in Pilots**: Negative gender biases and racial or other stereotypes could have an influence on passengers’ willingness to fly based on the composition of a flight crew.
- **Trust in Air Traffic Controllers**: In the U.S., study participants trusted older controllers (55 years old) more than the younger counterparts (25 years old) regardless of gender.
- **Willingness to Fly**: Scale consists of seven items using a 5-point Likert scale ranging from −2 (strongly disagree) to +2 (strongly agree) with a neutral option (0).
Focus Group Key Findings

• **Public perception of fully automated aircraft is one of the largest barriers.**
  - Lack of willingness to fly on fully automated aircraft OR aircraft designed by small companies lacking brand recognition
  - Influence of factors, such as pilot and crew age / perceived experience

• **Cost is a primary consideration for public users when choosing a transportation mode.**

• **Personal security** was an important factor. Personal security includes confidence in aircraft, as well as feeling of security / safety from flying with potentially dangerous or unruly passengers.

• Some participants expressed **privacy concerns** (people flying overhead, sight lines into homes/yards) and increased noise levels as detractors.

• **Most would use UAM for short inter-regional trips** (DC to Baltimore, LA to OC) rather than inter-city.

See Appendix 3 for more details on focus group methodology and demographics
Survey Overview

- Research team obtained CPHS/IRB approval in Spring 2018
- Exploratory survey target approximately 1,700 respondents in five U.S. cities (~350 respondents per city)
- Cities selected based on a variety of demography, geography, weather, availability of past or present air taxi services, built environments/densities, traffic, etc.

Survey Structure

- Respondent Demographics
- Recent Travel Behavior
- Typical Commute Behavior
- Familiarity with Aviation
- Existing Aviation Experience & Preferences
- Familiarity with UAM
- Perceptions about UAM
- Perceptions toward Technology and UAM
- Weather
- Market Preferences
- Perceptions from Non-User Perspective

See Appendix 3 for more details on respondents demographics
Survey Key Findings

• Generally, neutral to positive reactions to the UAM concept

• Respondents most comfortable flying with passengers they know; least comfortable flying with passengers they do not know

• Some willingness and apprehension about flying alone (particularly in an automated/remote piloted context)

• Strong preference for piloted operations; may need offer mixed fleets and/or a discount for remote piloted/automated operations to gain mainstream societal acceptance

• Presence of a flight attendant did not impact willingness to fly on an automated or remote piloted UAM aircraft.

• However, presence of a flight attendant did increase confidence in automated and remote piloted operations from the non-user perspective

<table>
<thead>
<tr>
<th>GEOGRAPHIC LOCATION</th>
<th>Excited</th>
<th>Happy</th>
<th>Neutral</th>
<th>Confused</th>
<th>Concerned</th>
<th>Surprised</th>
<th>Skeptical</th>
<th>Amused</th>
<th>Survey Results</th>
</tr>
</thead>
<tbody>
<tr>
<td>Houston, N = 344</td>
<td>32%</td>
<td>24%</td>
<td>27%</td>
<td>8%</td>
<td>9%</td>
<td>11%</td>
<td>19%</td>
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<td></td>
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<tr>
<td>San Francisco Bay Area, N = 337</td>
<td>33%</td>
<td>25%</td>
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<td>9%</td>
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<td>20%</td>
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<td></td>
</tr>
<tr>
<td>Los Angeles, N = 345</td>
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<td>9%</td>
<td>11%</td>
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<td>Washington, D.C., N = 341</td>
<td>32%</td>
<td>24%</td>
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<tr>
<td>New York City, N = 344</td>
<td>32%</td>
<td>24%</td>
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<td>9%</td>
<td>11%</td>
<td>19%</td>
<td>3%</td>
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</tbody>
</table>

Please select whether you would be willing to travel in an Urban Air Mobility aircraft in the following situations (i.e., piloted, remotely piloted, or automated) by yourself, and/or with other people on board.
Survey Key Findings

• **Preference for longer inter-city flights** (e.g., DC to Baltimore; LA to San Diego)

• Survey and focus groups suggest some resistance to very short trips due to cost and potential inconvenience (e.g., modal transfers, competitive travel times and price of other modes)

• Some desire among younger and male respondents to pay a premium to fly alone

• There could be a market for peer-to-peer operations that could help provide additional supply to scale the market (similar to Lyft and Uber)

• Existing noise concerns focus on traffic noise during the night and early morning; noise from UAM could pose a more notable barrier in future as electric vehicles become more mainstream (potentially causing a reduction in overall ambient noise, making UAM more noticeable)
WEATHER ANALYSIS – MOTIVATION

• Weather can influence many components of Urban Air Mobility, creating a variety of potential barriers
  - **Operations**: Reduction or cessation of operations during adverse conditions may occur due to safety concerns
  - **Service Supply**: Conditions may extend trip distance or reduce battery life
  - **Passenger Comfort**: May be impacted due to conditions such as extreme temperatures and winds
  - **Community Acceptance**: Could lead to passenger apprehension toward flying in certain conditions
  - **Infrastructure**: Consistent adverse weather may increase wear and reduce viability of vertiports
  - **Traffic Management**: Conditions such as wind shear and storms could disrupt flow patterns and structure

• Need to evaluate underlying frequent adverse weather conditions to assess range of potential barriers
CLIMATOLOGY DATA SOURCES

• Surveyed available weather observation data sources in and near focus urban areas (UA)
  - Limited availability of reliable observations collected directly in urban environment (e.g., heliports)
• Computed seasonal average conditions from historical archives of several standard data sources which contain routinely collected weather observations
  - Meteorological Aerodrome Report (METAR) point surface observations which are taken hourly and provide conditions at takeoff/landing
  - Vertical soundings generated from weather balloons launched at 00Z and 12Z which provide conditions aloft that would be experienced during flight or at elevated vertiports
  - Pilot Reports (PIREP) of weather conditions encountered during flight which provide supplemental ad hoc information on weather deemed impactful by pilots

<table>
<thead>
<tr>
<th>METAR</th>
<th>IFR, VFR</th>
</tr>
</thead>
<tbody>
<tr>
<td>Storms, winter weather, rain, etc.</td>
<td></td>
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</table>

<table>
<thead>
<tr>
<th>Vertical Sounding</th>
<th>Winds Aloft</th>
</tr>
</thead>
<tbody>
<tr>
<td>Temperature</td>
<td></td>
</tr>
<tr>
<td>Dew Point</td>
<td></td>
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</table>

PIREP Output

<table>
<thead>
<tr>
<th>Airport</th>
<th>Location</th>
<th>Time</th>
<th>Flight Level</th>
<th>Aircraft Type</th>
<th>Remark</th>
</tr>
</thead>
<tbody>
<tr>
<td>TEB UA /OV TEB010003/TM 1931/FLDURD/TP E35L/RM LLWS +/-10KT</td>
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</table>
DATA SPATIAL COVERAGE – EASTERN AND CENTRAL UA

- Extensive overlap between standard observation locations and Eastern and Central urban areas
  - Many located in close proximity, so observations may not represent full urban area (i.e., northern Miami)

*Urban area maps based on U.S. Census definition*
RESULTS – SAN FRANCISCO UA

- Instrument Flying Rules (IFR) conditions and strong winds most frequent adverse weather across all stations
  - Frequency of strong winds (>20 kts) significantly greater at SFO than OAK in afternoon for all seasons except Winter.
  - Strong winds possible in afternoon for most seasons across all stations
  - IFR conditions frequent during morning hours in summer
RESULTS – NEW YORK UA

• Several adverse weather conditions frequent for most hours and seasons which could impact UAM operations
  - Strong winds common in afternoon across most of UA in winter and spring, most frequent at JFK across all seasons
  - IFR conditions occur often during morning hours in all seasons
  - Strong winds and shear (change in winds with height) aloft observed above 500 ft during morning in winter
RESULTS – DALLAS UA

• Several adverse conditions possible in all seasons
  - Median temperature exceeds 90° F for all hours after 12PM in summer
  - Storms frequent during afternoon of spring and summer
  - IFR conditions frequent during morning of all seasons, most common in winter and spring
  - Changes in wind speed with height during fall may impact UAM during takeoff and landing
KEY RESULTS

- Weather mostly favorable for UAM operations in **Western** urban areas with potential for impacts due to low visibility, high temperatures, and strong surface winds
  - Strong surface winds may disrupt takeoff/landing during afternoon in Honolulu, San Francisco, and Phoenix UA’s
  - Median temperature exceeds 90⁰ F across most of the day in Phoenix during summer which could contribute to reduced battery life and creates need to cool vehicle for passenger comfort
  - Frequent low visibility conditions during morning hours in summer may reduce visual operations or warrant instrumentation equipage
  - Conditions **highly unfavorable** for UAM operations in Denver due to frequent adverse weather across all phenomena

- Storms and low visibility conditions are primary adverse weather impacting **Eastern** urban areas
  - Storms are frequent during summer afternoons in Washington, DC and Miami which may disrupt UAM operations
  - Low visibility conditions are most common during morning hours
  - Strong winds at the surface and aloft likely disrupt UAM operations in New York during winter and spring

- High temperatures, storms, low visibility, and wind shear (low level jet) may impact UAM operations in **Texas** urban areas
  - Temperatures and storms primary impact during afternoon in summer
  - Low visibility conditions occur most frequently during morning of winter and spring
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SYSTEM LEVEL FRAMEWORK IS REQUIRED

Modeling Framework

- Public
  - Noise Population Exposure
  - Emissions
- Demand for UAT services
  - Trip Generation
  - Trip Distribution
  - Mode-Choice (Market Size)
- Supply (operator)
  - Aircraft Classification
  - Direct Operating Cost
  - Indirect Operating Cost
- Airports/Vertiports (number & location)
  - Existing Heliports
  - Existing Airports (small or large)
  - New Infrastructure
- Infrastructure Capacity Constraints
  - Ground Infrastructure
  - Air Traffic Management
- Legal / Regulatory Environment
  - Federal
  - State / Local

Analysis Framework

- Scenario-based Analyses
- Sensitivity Analyses

Results (by stakeholders)

- Public
  - Noise footprint around vertiport
  - Emissions
- Passengers
  - Cost vs time savings
  - Number of Passengers
- Operators
  - Operating Cost per passenger mile
  - Fleet
- Infrastructure Providers
  - Vertiports Use & Distribution
  - Use/Capacity Constraints

Iterative Loop
KEY OPERATION RELATED ASSUMPTIONS

For the first few years of operations, analysis assumes a pilot on-board that controls the aircraft (i.e., no autonomy) although aircraft are expected to be fully autonomous from the beginning.

We assume a longest mission of 50 miles in single charge. All other assumptions for Monte Carlo analysis are available in later sections.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Definition</th>
<th>Minimum</th>
<th>Maximum</th>
<th>Source</th>
</tr>
</thead>
<tbody>
<tr>
<td>Seats</td>
<td>Number of seats in aircraft. First few years of operation assumes a pilot on-board, hence there is one seat less available to be occupied by a passenger</td>
<td>1</td>
<td>5</td>
<td></td>
</tr>
<tr>
<td>Load Factor (%)</td>
<td>Refers to passenger load factor and measures the capacity utilization of eVTOL</td>
<td>50%</td>
<td>80%</td>
<td>SAG Interviews¹</td>
</tr>
<tr>
<td>Utilization for 2+ seat aircraft (number of flight hours per year)</td>
<td>Average numbers of hours in a year that an aircraft is actually in flight. Conservative utilization numbers are used to take into account battery recharging/swapping times</td>
<td>1000</td>
<td>2000</td>
<td>BAH Assumption²</td>
</tr>
<tr>
<td>Utilization for 2-seat aircraft (number of flight hours per year)</td>
<td>For 2-seat aircraft (only one passenger seat), aircraft is only flown when the passenger seat is filled. Therefore, utilization range is adjusted by multiplying with load factor of 2+ seat aircraft i.e. 1000<em>50%, 2000</em>80%</td>
<td>500</td>
<td>1600</td>
<td></td>
</tr>
<tr>
<td>Max Reserve (mins)</td>
<td>Minimum energy required to fly for a certain time (outside of mission time) at a specified altitude</td>
<td>20</td>
<td>30</td>
<td>Part 91 requirements³</td>
</tr>
<tr>
<td>Deadend Trips (%)</td>
<td>Ratio of non-revenue trips and total trips</td>
<td>25%</td>
<td>50%</td>
<td>BAH Assumption</td>
</tr>
<tr>
<td>Detour Factor (%)</td>
<td>Factor to represent actual flight distance above great circle distance</td>
<td>5%</td>
<td>15%</td>
<td></td>
</tr>
<tr>
<td>Cruise Altitude (ft)</td>
<td>Cruise altitude for eVTOL</td>
<td>500</td>
<td>5000</td>
<td>NASA Study⁴</td>
</tr>
</tbody>
</table>

¹BAH conducted interviews with SAG members in February/April 2018. Their feedback is documented in deliverable ‘SAG Interview and Workshop summary’
²BAH assumption based on the literature review. See Air Taxi Deliverable for detailed reasoning
³FAA. Details available at https://www.law.cornell.edu/cfr/text/14/91.167
⁴Patterson, M. A Proposed Approach to Studying Urban Air Mobility Missions Including an Initial Exploration of Mission Requirements, 2018

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PRICE COMPARISON WITH OTHER MODES OF TRANSPORTATION

- 5-seat eVTOL passenger price per mile is expected to be more expensive than luxury ride sharing on the ground.
- 2-seat eVTOL aircraft is comparable to current limo type services. Operators like Blade and Skyride charges ~$30 per passenger mile while Voom charges ~$10 per passenger mile.

### Mode of Transportation

<table>
<thead>
<tr>
<th>Mode of Transportation</th>
<th>Source</th>
</tr>
</thead>
<tbody>
<tr>
<td>Limo</td>
<td>Limos¹</td>
</tr>
<tr>
<td>Luxury Ride Sharing</td>
<td>Uber², Fare Estimator³</td>
</tr>
<tr>
<td>Economy Ride Sharing</td>
<td>Uber, Fare Estimator</td>
</tr>
<tr>
<td>Taxi</td>
<td>MarketWatch⁴</td>
</tr>
<tr>
<td>Autonomous Taxi</td>
<td>MarketWatch</td>
</tr>
<tr>
<td>Vehicle Ownership</td>
<td>AAA⁵</td>
</tr>
<tr>
<td>Uber Air Launch, Helicopter</td>
<td>Uber Elevate⁶</td>
</tr>
</tbody>
</table>

¹Limos.com assessed on 1/12/2018
²Uber Estimate available at http://uberestimate.com/prices/San-Francisco/
³Fare Estimator available at https://estimatefares.com/rates/san-francisco
⁴Driverless cars could cost 35 cents per mile for the Uber consumer, MarketWatch, 2016
⁵AAA Reveals True Cost Of Vehicle Ownership, AAA, 2017/
⁶Presented at Uber Elevate, May 2018.
DEMAND SCENARIO DEFINITIONS

• **Unconstrained Scenario** – Refers to the case where:
  - **Infrastructure** to take-off and land is available at every tract and is not constrained by capacity;
  - **Cost is also not a constraint** i.e., demand is not constrained by willingness to pay;
  - Demand calculated in this scenario refers to the total available market at the market entry price points.

• **Infra + WTP Constraint** – This scenario utilizes existing infrastructure in the form of heliports and airports (assuming only one landing take-off pad) and is cost constrained.

• **Capacity Constraint** – Refers to the demand reduction due to existing infrastructure’s operational capacity on per hour basis.

• **Time of Day Constraint** – Demand reduction due to operations in specific time of day.

• **Weather Constraint** – Initial operations are expected to be under Visual Flight Rules (VFR) conditions. 
OVERALL AIR TAXI BASE YEAR DEMAND COMPARISON FOR ALL URBAN AREAS

- On average ~0.5% of unconstrained trips are captured after applying constraints. **New York, Los Angeles, Houston and Dallas** are potential urban areas of high daily demand (see appendix 4 for details on E&E impacts and ATM barriers).

<table>
<thead>
<tr>
<th>City</th>
<th>Unconstrained</th>
<th>Infra + WTP Constrained</th>
<th>Capacity Constraint</th>
<th>Time of Day Constraint</th>
<th>Weather Constraint</th>
</tr>
</thead>
<tbody>
<tr>
<td>New York</td>
<td>1,421,000</td>
<td>127,000</td>
<td>11,000</td>
<td>8,800</td>
<td>8,000</td>
</tr>
<tr>
<td>Los Angeles</td>
<td>1,380,000</td>
<td>145,000</td>
<td>10,500</td>
<td>8,400</td>
<td>7,500</td>
</tr>
<tr>
<td>Dallas</td>
<td>717,000</td>
<td>47,000</td>
<td>6,700</td>
<td>5,360</td>
<td>4,750</td>
</tr>
<tr>
<td>Miami</td>
<td>587,000</td>
<td>47,000</td>
<td>3,400</td>
<td>2,720</td>
<td>2,470</td>
</tr>
<tr>
<td>Houston</td>
<td>673,000</td>
<td>47,000</td>
<td>7,000</td>
<td>5,600</td>
<td>4,890</td>
</tr>
<tr>
<td>San Francisco</td>
<td>606,000</td>
<td>47,000</td>
<td>1,800</td>
<td>1,440</td>
<td>1,250</td>
</tr>
<tr>
<td>Washington DC</td>
<td>600,000</td>
<td>59,000</td>
<td>1,100</td>
<td>880</td>
<td>780</td>
</tr>
<tr>
<td>Phoenix</td>
<td>422,000</td>
<td>23,000</td>
<td>3,200</td>
<td>2,560</td>
<td>2,230</td>
</tr>
<tr>
<td>Denver</td>
<td>358,000</td>
<td>16,000</td>
<td>2,000</td>
<td>1,600</td>
<td>1,460</td>
</tr>
<tr>
<td>Honolulu</td>
<td>161,000</td>
<td>16,000</td>
<td>700</td>
<td>560</td>
<td>550</td>
</tr>
</tbody>
</table>
OVERALL MARKET SIZE AND VALUE

Air Taxi market has a potential demand of ~55k daily trips (or ~80k daily passengers) across the US that can be served by ~4k aircraft. Based on near term market entry assumptions, annual market value is projected to be ~$2.5 bn for the first few years of operation.

<table>
<thead>
<tr>
<th>Daily Trips</th>
<th>Daily Passengers</th>
<th>Total Number of Aircraft</th>
<th>Annual Market Value (in bn $)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Unconstrained</td>
<td>11,000,000</td>
<td>16,000,000</td>
<td>850,000</td>
</tr>
<tr>
<td>Infra + WTP</td>
<td>1,000,000</td>
<td>1,500,000</td>
<td>80,000</td>
</tr>
<tr>
<td>Capacity Constraint</td>
<td>80,000</td>
<td>120,000</td>
<td>6,000</td>
</tr>
<tr>
<td>Time of Day Constraint</td>
<td>60,000</td>
<td>90,000</td>
<td>4,500</td>
</tr>
<tr>
<td>Weather Constraint</td>
<td>55,000</td>
<td>82,000</td>
<td>4,100</td>
</tr>
</tbody>
</table>

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LARGE DEMAND MAY BE ACHIEVED BY HIGH NETWORK EFFICIENCY BUT AUTONOMOUS CARS ARE EXPECTED TO PROVIDE STRONG COMPETITION

- Autonomous vehicle and reduced importance of travel time may severely constrain the demand for Air Taxis. Telecommuting further reduces the demand marginally.
- High network efficiency, increased importance of travel time, autonomous eVTOL, technology improvements, and increased available infrastructure/capacity may all increase demand.

Appendix 5 provide details about all the scenarios
CONTENTS

Executive Summary
Introduction
Market Selection
Legal and Regulatory
Societal Barriers
Weather Analysis

Market Analysis

• Airport Shuttle and Air Taxi
  • Air Ambulance

Conclusions

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# AIR AMBULANCE IS A COMPLEX POTENTIAL MARKET

## AIR AMBULANCE OVERVIEW

**Definition:** The Air Ambulance market includes travel to/from the hospital for emergencies and potentially hospital visits. Both public and private operations are considered.

**Selection Criteria:** A complex market and likely to highlight technology barriers in terms of technical capabilities needed on board the aircraft, in addition to other legal and regulatory barriers. Air Ambulances have high public acceptability.

**Value Proposition:** Lifeline; public safety; reduction of travel time by 1.5-2 times, hence reducing fatalities

**Market Dynamics:**

- **Market Size:** Relatively limited market; however, the services are of high value

- **Market Drivers:**
  - Events i.e. Accidents, health related events etc.
  - Demographic trends
  - Healthcare legislation
  - Changes in insurance policies

- **Potential Business Models at Play:** Insurance subscription, hospital ownership, fleet operators, pay per ride

**Connected Markets:** Emergency Response markets such as law enforcement, natural disaster response, and firefighting

Source: BAH Analysis; Ibis, 2016
A typical air ambulance mission consists of three sub-missions; Response (A-F), Transport (H-M) and Return to Service (N-R). We assume that each of these sub-missions are flown at similar speeds and follow similar profiles i.e., Taxi, Hover Climb, Climb, Cruise, Descend, Hover Descend and Taxi. For the fourth mission (Scene) we assume an air ambulance in Taxi mode. Total Flight time is given by (1).

After completing the transport, the air ambulance returns to its base (N-R) and is prepared for service (R-Q). For this analysis, time required to complete mission N-R is assumed to be 5-15 mins while eVTOL preparation time (R-Q) refers to time required to recharge batteries completely (assuming battery swapping is not possible).

\[
\text{Total Flight Time} = \text{Response (B - F)} + \text{Transport (H - M)} + \text{Return Time (N - R)}.
\]  

\[\text{(1)}\]

1Literature suggests that ground ambulances are operated at different speeds for all three sub-missions (i.e., Response speed > Transport Speed > Return to Service speed. However, there is little literature to support a similar trend for Air Ambulances).

Source: NEMSIS, 2018
REFERENCE AIRCRAFT ASSUMPTIONS

- eVTOL and Hybrid aircraft, like the current rotor wing market, may be used mainly for 1-patient emergency medical transports, both from accident scenes and between hospitals. Therefore, we consider a 5-8 seat size equivalent eVTOL that can fly a cruise altitude of 500-5000 ft.

- According to FAA duty hour requirements, a single emergency eVTOL will require 4 full time pilots, 4 full time flight nurses, and 4 full time paramedics with CAMTS Accreditation. Each crew goes through annual training requirements.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Sub Parameter</th>
<th>Minimum</th>
<th>Maximum</th>
<th>Source</th>
</tr>
</thead>
<tbody>
<tr>
<td>Aircraft Assumptions</td>
<td>Cruise Speed (for eVTOL) ¹</td>
<td>125 mph</td>
<td>175 mph</td>
<td>MIT Study</td>
</tr>
<tr>
<td></td>
<td>Cruise Speed (for Hybrid) ²</td>
<td>200 mph</td>
<td>300 mph</td>
<td>BAH Literature review, XTI Aircraft</td>
</tr>
<tr>
<td></td>
<td>Equivalent Number of Seats ²</td>
<td>5</td>
<td>8</td>
<td>Helicopter Market Literature Review</td>
</tr>
<tr>
<td></td>
<td>Reserve (mins)</td>
<td>20</td>
<td>30</td>
<td>Part 91 requirements</td>
</tr>
<tr>
<td></td>
<td>Range (miles)</td>
<td>50 + Reserve</td>
<td>200 + Reserve</td>
<td>BAH Assumption</td>
</tr>
<tr>
<td></td>
<td>Battery Capacity (kWh)</td>
<td>100 kWh</td>
<td>150 kWh</td>
<td>Nykvist et al, 2015</td>
</tr>
<tr>
<td></td>
<td>Annual number of Transports ³</td>
<td>300</td>
<td>400</td>
<td>AAMS, 2017</td>
</tr>
<tr>
<td>Crew/Payroll Assumptions</td>
<td>Pilot Salary ($ per year)</td>
<td>$60,000</td>
<td>$100,000</td>
<td>US Bureau of Labor Statistics</td>
</tr>
<tr>
<td></td>
<td>Paramedic ($ per year)</td>
<td>$50,000</td>
<td>$75,000</td>
<td></td>
</tr>
<tr>
<td></td>
<td>EMT ($ per year)</td>
<td>$60,000</td>
<td>$90,000</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Mechanic Salary ($ per year) ⁴</td>
<td>$50,000</td>
<td>$90,000</td>
<td></td>
</tr>
</tbody>
</table>

¹Cruise Speed is use to calculate Trip Speed, which is a parametric function of average distance, LTO speed and Cruise Speed

²Based on helicopter market to accommodate one patient

³Standard unit for Air Ambulance utilization

⁴Air ambulances generally have one full time mechanic onsite
TOTAL COST PER TRANSPORT

After performing 10,000 iterations of Monte Carlo, the median cost of operating an eVTOL air ambulance is ~$9,000 per transport and hybrid air ambulance is ~$9,800 as compared to ~10,000 for rotary wing helicopter (source: AAMS) and ~$500 for ground ambulance. About 80% is fixed cost.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Min</th>
<th>Max</th>
</tr>
</thead>
<tbody>
<tr>
<td>Cruise Altitude (ft)</td>
<td>500</td>
<td>5,000</td>
</tr>
<tr>
<td>Medical Equipment Weight (lb)</td>
<td>200</td>
<td>400</td>
</tr>
<tr>
<td>Pilot Training ($ per year)</td>
<td>10,000</td>
<td>30,000</td>
</tr>
<tr>
<td>Paramedic and EMT Training ($ per yea)</td>
<td>10,000</td>
<td>20,000</td>
</tr>
<tr>
<td>Indirect Operating Cost (% of DOC)</td>
<td>5%</td>
<td>50%</td>
</tr>
<tr>
<td>Bad Debt (% of Operating Cost)</td>
<td>10%</td>
<td>20%</td>
</tr>
<tr>
<td>Electricity Price ($/kwh)</td>
<td>0.1</td>
<td>0.3</td>
</tr>
<tr>
<td>Profit Margin (% of Cost)</td>
<td>10%</td>
<td>30%</td>
</tr>
<tr>
<td>Disembarkation Time (in mins)</td>
<td>3</td>
<td>5</td>
</tr>
<tr>
<td>Climb Descend Distance (miles)</td>
<td>1</td>
<td>2</td>
</tr>
<tr>
<td>Energy Conversion Efficiency (%)</td>
<td>90%</td>
<td>98%</td>
</tr>
</tbody>
</table>
DEMAND SCENARIOS: REVISED CONOPS AND BATTERY SWAPPING

Scenario 1: Revised ConOps

- Under Transport phase, patient is transported from the scene to the medical facilities. Our analysis explores charging during patient disembarkation (~5 mins) to reduce range requirement (hence, battery requirement) combined with fast recharging from scenario 1. This phase is represented by ‘M’ in the figure below.

- Under this scenario, total range required reduces to 30-180 miles as opposed to 50-200 miles. Average battery weight reduces to ~3, 200 lb (as opposed to ~3, 500 lb).

Scenario 2: Battery Swapping

- Given high re-charging times, air ambulances may rely on swapping batteries when eVTOL returns to the base after each mission to reduce the total call time (increasing dispatch reliability). Battery swapping is expected to take ~5 minutes (Georgia Tech Study).

- Median price of battery cost per transport was calculated to be ~$300, which will be added to the operating cost. Staff and equipment required to swap the batteries can be considered as a part of indirect operating costs.
BOTH EVTOL AND HYBRID AIRCRAFT HAVE HIGH RETURN TIMES DUE TO HIGH BATTERY RE-CHARGING TIME

Dispatch, Chute and Scene time remains the same for RW and eVTOL/hybrid while scene response and transport time changes due to differences in speed. Return time increases significantly for eVTOL due to high battery recharging times.

Total call time in Battery swapping scenario is comparable to current Rotary Wing market while total call time for all other scenarios far exceeds to that of RW.
**DISPATCH RELIABILITY VS NUMBER OF TRANSPORTS**

- Air Medical Transport follows a certain dispatch protocols that considers the need of minimization of time, weather considerations, availability, safety etc. before deploying a RW aircraft.

- Cost per transport of air ambulances decrease significantly as number of transports increases. However, increased use of an air ambulance (i.e., less availability) decreases dispatch reliability.

- Dispatch reliability is calculated at an event interval of one hour assuming that an RW Air Ambulance total call time ~2 hours:

\[
\text{Dispatch Reliability} = \frac{\text{Number of events for which ambulance is available (A)}}{\text{Total number of events (T)}}
\]

where,

\(A = T - NA\) (number of events for which ambulance is unavailable)

e.g. Case of NA

- \(E1\) = Emergency event 1 satisfying RW dispatch protocol. RW dispatched
- \(E2\) = Emergency event 2 satisfying RW dispatch protocol

\[\text{RW unavailable for } E2\]

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MARKET SIZE CAPTURE UNDER DIFFERENT OPERATION SCENARIOS

Due to high recharging time, dispatch reliability of eVTOLs for 90% of the market may be below the acceptable standard. Therefore, under current technology, eVTOLs may not be an attractive option for air ambulances. Fast Recharging and Battery Swapping capabilities may propel the capture of available RW market for eVTOLs.

Fast Recharging:
- Assumes a scenario where battery recharging rate increases with respect to current rates
- On increasing Battery recharge rate approximately 4 times to current rate, eVTOLs may address the total available RW market because of the following
  - Dispatch reliability similar to current RW market achieved
  - Cost per transport less than current RW market

Battery Swapping:
- ~100% of RW market is available for eVTOLs with Battery Swapping capabilities
CONCLUSION – SUMMARY OF KEY FINDINGS

UAM markets have strong potential but face significant challenges and constraints that could severely limit the available market. Our results suggest the following:

- Airport Shuttle and Air Taxi markets are viable markets with a significant total available market value of $500B at the market entry price points in the best case unconstrained scenario.

- In the near term, a 5-seat piloted eVTOL will cost $6.25 per passenger mile. However, in the long term, high operational efficiency, autonomy, technology improvements may decrease the cost by ~60%.

- Infrastructure availability and capacity combined with high cost is a major barrier to fully capture the available demand.

- Air Ambulance market served by eVTOLs is not a viable market due to technology constraints. Hybrid VTOL aircraft is a more attractive option to serve air ambulance markets.

- Legal and Regulatory analysis found all markets share the same regulatory barriers.

- Public perception is a large obstacle. Safety is the greatest concern with “unruly” passengers, “lasing” of pilots, and aircraft sabotage being main contributors.

- Weather poses significant challenges to UAM operations at several focus urban areas with low visibility, strong winds, and storms being the most frequent adverse conditions.
APPENDIX
APPENDIX 1: SAG MEMBERS - FEDERAL GOVERNMENT

NAN SHELLABARGER
Executive Director
FAA Aviation Policy & Plans Office
• Responsible for setting direction and overseeing operations for FAA’s Policy organization
• Previously the Manager of the Planning Analysis Division at FAA where she was responsible for facilitating agency-wide strategic planning, developing long range aviation forecasts, and analyzing airline delays

DR. KARLIN TONER
Director of Global Strategy
FAA Office of International Affairs
• Provides executive leadership in the development, implementation and evaluation of program policies, goals, and objectives for US international aviation
• Master’s Degree and Ph.D. in Aerospace Engineering along with honorary Ph.D. in Science
• Oversees the development of a data-informed process to enable the FAA to most effectively prioritize future international engagement

EARL LAWRENCE
Director
FAA UAS Integration Office
• Director of the UAS Integration office responsible for the facilitation of all regulations, policies, and procedures required to support FAA’s UAS integration efforts
• Previously served as the Manager of the FAA’s Small Airplane Directorate where he managed airworthiness standards, continued operational safety, policy, and guidance for small aircraft, gliders, light sport aircraft, airships, and balloons

DR. JIM HILEMAN
Chief Scientific and Technical Advisor for Environment
FAA
• Ph.D. and Master’s Degree in Mechanical Engineering
• Previously the Principal Research Engineer within MIT’s Department of Aeronautics and Astronautics and its Associate Director, Partnership for Air Transportation Noise and Emission Reduction
• Research focused on modeling the impacts of alternative jet fuel and innovative aircraft concepts on efficiency, noise, air quality and global climate change

CHRISTOPHER HART
Former Chairman
NTSB
• Former Deputy Director of Air Traffic Safety Oversight Service at FAA
• Former Assistant Administrator for System Safety at FAA
• Former Deputy Assistant General Counsel to DOT
• Former Attorney with the Air Transport Association
• Master’s Degree in

JULIET PAGE
Acoustics & Sonic Boom Expert
Volpe (DOT)
• SME in the field of acoustics / aerospace engineering including sonic boom, atmospheric propagation, aircraft, rotorcraft, tiltrotor, space and launch vehicle noise
• Experience conducting scientific research, regulatory standards and model development and validation for air and ground based transportation systems through analytic development, experimentation and measurements

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APPENDIX 1: SAG MEMBERS - STATE AND LOCAL GOVERNMENT

BASIL YAP
UAS Program Manager
North Carolina DOT

• 9+ years of experience in airport development
• 4+ years experience in UAS Program Management
• UAS SME
• Designs, establishes, and conducts studies and makes recommendations relative to the UAS policies, programs, methods and procedures currently in place

DARHAN DIVAKARAN
UAS Program Engineer and Geospatial Analyst
NCDOT Division of Aviation

• Unmanned aviation expert with expertise in unmanned flight operations, flight safety, remote sensing, geospatial analysis and project management
• Experience developing best practices and procedures for safe and efficient unmanned aviation operations
• Previously Research Associate – Flight Operations with NGAT and AirTAP at the ITRE in NC

MEERA JOSHI
Chair and CEO
NYC’S Taxi & Limousine Commission

• Previously served as the Frist Deputy Executive Director of the NYC Civilian Complaint Review Board, an agency tasked with investigating complaints of police misconduct
• Responsible for initiation of a landmark prosecution program that resulted in the agency’s ability to independently prosecute founded complaints against police officers

ALEX PAZUCHANICS
Assistant Director
Department of Mobility and Infrastructure – City of Pittsburgh

• Policy Advisor for Pittsburgh Mayor William Peduto
• Led Pittsburgh’s response to the USDOT Smart City Challenge
• Manages the City’s designation as an Autonomous Vehicle Proving Ground and is a member of the PennDOT Autonomous Vehicle Policy Task Force

MARK DOWD
Executive Director
Smart Cities Lab

• Previously worked for the White House as the Senior Advisor for the Office of Management and Budget
• Responsible for creating and executing the USDOT’S Smart City Challenge that changed the way cities use technology and innovation to drive change and solve problems related to mobility
• Broad experience in policy development and implementation related to technology, mobility, smart cities, public-private partnerships, energy, and environmental issues

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APPENDIX 1: SAG MEMBERS - STATE AND LOCAL GOVERNMENT

ADRIENNE LINDGREN
Economic Policy & UAS/UAM Integration
LA City
• Oversees the implementation of public-private partnerships for industrial innovation and cluster development, in partnership with the U.S. Departments of Energy and Commerce
• Leads the development of testing and demonstration zones for urban aviation, including the integration of UAV and AV policy strategy, in partnership with the Los Angeles Department of Transportation, LA Fire Department, the Port of LA, Los Angeles World Airports, and the Federal Aviation Administration.

JUSTIN ERBACCI
Chief Innovation and Technology Officer
Los Angeles World Airports
• Responsible for implementing LAWA’s overall Information Technology vision and strategy, in addition to leveraging innovative technologies and processes to enhance operations at Los Angeles International (LAX) and Van Nuys general aviation airports.
• Prior to his appointment with LAWA, he served as Vice President of Customer Experience & Technology for Star Alliance, a global airline network comprised of 28 airlines serving 640 million passengers annually.

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APPENDIX 1: SAG MEMBERS - LEGAL AND REGULATORY

GRETCHEN WEST
Senior Advisor in the Global Unmanned Aircraft Systems
Hogan Lovells
• Policy advocate for the commercial drone industry over a decade working to reduce barriers to entry
• Works with companies to assist in understanding market trends and develop strategies for market growth
• Co-leads the Commercial Drone Alliance, a non-profit association
• Previously served as AUVSI’s Executive VP overseeing AUVSI’s global business development initiatives and government relations efforts for the unmanned systems and robotics industry

LISA ELLMAN
Co-Executive Director of Commercial Drone Alliance
Hogan Lovells
• Co-chair of firm’s UAS practice
• Counsels businesses and trade groups on UAS issues in industries ranging from newsgathering, aerial photography, energy, precision agriculture and insurance, higher education, drone technology, to construction
• Held variety of positions at top levels of executive branch at the White House and the U.S. Department of Justice (DOJ)

DAVID ESTRADA
Chief Legal Counsel
ZEE Aero
• Previously VP of Government Relations at Lyft and helped establish a legal and regulatory framework for TNCs in the US
• Previously held Legal Director role at Google X, leading the legal efforts behind Google’s self-driving cars, Google Glass, and drone delivery program
• While at Google, helped create the first state laws and regulations governing self-driving cars in Nevada, California, and Florida

MATTHEW DAUS
Partner, Chair of Transportation Practice Group
Windels Marx LLP
• Practice focuses on transportation law, counseling clients on a wide range of matters including regulatory compliance, strategic planning, procurement, litigation, regulatory due diligence, expert witness testimony and reports, administrative law and public policy
• Previously served as Commissioner and Chairman of NYC TLC
• Formerly served as General Counsel to the Commission and Deputy Commissioner for Legal Affairs
• Served as Special Counsel to the TLC Chair – supervising over 75 lawyers and Administrate Law Judges

MARK AITKEN II
Senior Policy Advisor
Akin Gump Strauss Hauer & Feld LLP
• Leads advocacy for the inclusion of association priorities in House and Senate versions of FAA reauthorization and associated appropriation measures
• Influences to safely expedite the US framework for integrating UAS into the NAS for commercial opportunities
• ACRP 03-42 Panel Member

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APPENDIX 1: SAG MEMBERS - EDUCATIONAL INSTITUTIONS

JOHN HANSMAN
T. Wilson Professor of Aeronautics & Astronautics
Massachusetts Institute of Technology
• Head of the Humans and Automation Division at MIT
• Director of the MIT International Center for Air Transportation
• Current research interests focus on advanced cockpit information systems, including Flight Management Systems, Air-Ground Datalink, Electronic Charting, Advanced Alerting Systems, and Flight Crew Situational Awareness

PARKER VASCIK
Ph.D. Candidate, Aeronautics and Astronautics
Massachusetts Institute of Technology
• Conducting research in collaboration with the NASA On Demand Mobility and UAS Traffic Management (UTM) programs
• Research areas include Unmanned Aircraft System Traffic Management, On-Demand Mobility Aviation, Design for Ilities under Uncertainty, and Technology Infusion Analysis

JESSIE MOOBERY
Technologist
Peace and Innovation Lab at Stanford
• Expert in humanitarian UAV design and operations
• Built and served as VP of Uplift Aeronautics, first cargo drone nonprofit
• Founded SwarmX, an enterprise drone company
• Commercial drone pilot
• Mentor for Ariane de Rothschild Social Enterprise Fellowship

BRIAN J. GERMAN
Associate Professor
Georgia Tech
• Ph.D. in Aerospace Engineering
• Senior Member of the American Institute of Aeronautics and Astronautics
• Research areas are multidisciplinary design, multi-objective optimization, and decision methods applied to air vehicle design and systems engineering
• Also conducts research in aerodynamic, propulsion, subsystem, and performance models suitable for aircraft concept studies

DR. JUAN ALONSO
Professor, Department of Aeronautics & Astronautics
Stanford University
• Founder and director of the Aerospace Design Laboratory where he specializes in the development of high-fidelity computational design methodologies to enable the creation of realizable and efficient aerospace systems
• Research involves manned and unmanned applications including transonic, supersonic, and hypersonic aircraft, helicopters, turbomachinery, and launch and re-entry vehicles
• Ph.D. in Mechanical & Aerospace Engineering

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APPENDIX 1: SAG MEMBERS - MANUFACTURERS

DR. BRIAN YUKTO
VP of Research & Development
Aurora Flight Sciences, a Boeing Company
• Responsible for Aurora’s R&D business unit which advances Aurora's capabilities in the areas of autonomy, next generation, air vehicle design, advanced electric propulsion, and operations of intelligent flight systems in the national airspace

DR. ERIC ALLISON
CEO
Zee Aero
• Previously served as Zee Aero’s Director of Engineering
• Thesis covered ultrasonic propulsion
• Ph.D. in Aeronautics and Astronautics from Stanford University

TRAVIS MASON
VP Public Policy
Airbus
• Master’s Degree in Public Policy
• Leading Public Policy for our future of flight projects across A³ by Airbus, Airbus Aerial, the Corporate Technology Office urban air mobility group and with Airbus Defense & Space

DR. CARL C. DIETRICH
Co-founder and CTO
Terrafugia
• Focused on development of future product concepts and establishment of new R&D center for Terrafugia
• BS, MS and Ph.D. from the Department of Aeronautics and Astronautics at MIT

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APPENDIX 1: SAG MEMBERS - MANUFACTURERS

PETER BERGER II
Director of Innovation,
Silicon Valley
Embraer Business Innovation Center
• Former CEO of Contact IQ, Alitora Systems and Topicmarks
• Advised numerous startups and Fortune 500 companies such as Orange Telecom and Qualcomm
• Undergraduate degree from California Polytechnic and a law degree from Rutgers University

DAVID ROTTBLATT
Business Development Director
Embraer
• Experience in large multinational corporations
• Recent projects have focused on business model design and execution, strategic marketing, market development and international project management
• Developed in-depth knowledge of aviation market and customer needs to identify new ventures for Embraer to pursue

BOB LABELLE
CEO
XTI Aircraft Company
• 25+ years experience in top-level aviation management and strategy, aircraft development and operations
• Responsible for development of the TriFan 600 aircraft
• Led the drive to incorporate hybrid-electric propulsion in the TriFan 600 and championed other enhancements in order to better position the aircraft in the future
• Former Chairman and CEO of AgustaWestland North America

JOEBEN BEVIRT
Founder
Joby Aviation
• Master’s Degree in Mechanical Engineering Design from Stanford
• Founded Joby Aviation to develop a compact electric personal aircraft designed for efficient high speed flights
• Former Co-Founder of Velocity11 which developed high-performance laboratory equipment
• Former Director of Engineering of Incyte Corporation where he built a team to develop robotics to improve the throughput and efficiency of Incyte’s laboratories

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APPENDIX 1: SAG MEMBERS

OPERATORS

MARK MOORE
Engineering Director of Aviation
Uber Elevate
- Mark D. Moore worked for NASA for over 32 years before joining Uber, the entire time focusing on conceptual design studies of advanced aircraft concepts.
- His research focused on understanding how to best integrate the emerging technology area of electric propulsion and automation to achieve breakthrough on-demand aviation capabilities.

JUSTIN ERLICH
Head of Policy, Autonomous Vehicles & Urban Aviation
Uber Elevate
- Subject matter expertise includes transportation, sustainability, smart open data, and smart cities, with an academic background in law, government, and behavioral science.
- Previously worked on the leadership team of former California Attorney General (currently Senator) Kamala Harris managing technology policy, strategy, and operations.

INTERNATIONAL

CHRISTOPHER PETRAS
Legal Officer at the ICAO Legal Bureau
International Civil Aviation Organization (ICAO)
- Provides legal advice to ICAO’s Secretary General on international law, air law, commercial law, labor law and related issues.
- Former Chief Counsel for International Law for the U.S. Air Force’s Air Mobility Command and NORAD.
- LL.M. in Air and Space Law (McGill University).

RESEARCH ORG.

MATTHIAS STEINER
Director Aviation Applications Program
NCAR Research Applications Laboratory
- Expertise in mitigating weather impacts on the aviation industry.
- Leading efforts to understand weather sensitivities and requirements for the rapidly growing interests in urban air mobility and using unmanned aerial systems for wide-ranging applications and safe integration into the national airspace system.
APPENDIX 1: SAG MEMBERS - INSURANCE AND REAL ESTATE

BRYANT DUNN
Assistant Vice President
Global Aerospace
- Experience in aviation insurance, underwriting, aircraft and airport operations, market research, marketing, sales, finance, and flight instruction
- Specialized in corporate flight department hull & liability program, aviation manufacturer products liability, airport liability, and unmanned aircraft systems

TOM PLAMBECK
Underwriter
Global Aerospace
- Active Pilot
- Expert in underwriting of drones and light aircraft
- Bachelor’s Degree in Aviation Management

ERIC ROTHMAN
President
HR&A Advisors
- 20+ years in transportation planning and transit-oriented development
- Expertise in strategic planning, transportation planning and development, economic development, capital program management, financial management, and program implementation
- Leads the firm’s work creating transit-oriented development strategies anchored by station redevelopment across the US

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APPENDIX 1: SAG MEMBERS - VENTURE CAPITAL

FRANCOIS CHOPARD
CEO
Starburst Aerospace Accelerator
• 20+ years of experience in strategy consulting, entrepreneurship, and business development
• Specializes in the Aviation Aerospace and Defense industries featuring high stakes technology and has developed a wide experience of innovation-related issues
• Works on topics like future trends, product strategy, open innovation for companies mainly from the aerospace industry as well as investment funds
• Master’s Degree in Electrical Engineering

VAN ESPAHBODI
Aerospace Ventures / International Business Development
Starburst Aerospace Accelerator
• Bringing technology + investment + design together to improve the way aerospace infrastructure operates
• Focus areas include: Corporate and Strategy Development, Corporate Venturing and Open Innovation, Partnerships & Alliances, International Sales, Government Affairs, Competitive Intelligence Analysis

KEN STEWART
Entrepreneur in Residence
GE VENTURES
• 20+ years of business development, strategic planning, sales/marketing, and product development/line-of-business management experience

BARRY MARTIN
Senior Manager – Business Development & Strategy
The Boeing Company
• Coordinates internal functional groups (Legal, Contracts, Intellectual Property, Supplier Management, Communications) to place agreements with customers/partners/suppliers
• Previously Avionics Integration Project Manager at Boeing and responsible for managing cross-functional teams for various F/A-18 avionics system upgrades

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## APPENDIX 2: TYPE CERTIFICATION COMPARISON TABLE

<table>
<thead>
<tr>
<th>Fixed Wing</th>
<th>Rotary</th>
<th>Hybrid Or Special</th>
<th>Engines</th>
<th>Propellers</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>FAA</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Part 21 – Certification Procedures for Products and Parts</td>
<td>Part 27 – Small Rotorwing</td>
<td>Part 21.17(b) – Designation of applicable regulations</td>
<td>Part 33 – Aircraft Engines</td>
<td>Part 35 – Aircraft Propellers</td>
</tr>
<tr>
<td>Part 23 – Small Fixed Wing</td>
<td>Part 29 – Transport Category Rotorcraft</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Part 25 – Transport Category Airplanes</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>EASA</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>CS-22-Sailplanes and Powered Sailplanes</td>
<td>CS-27 – Small Rotorcraft</td>
<td>CS-VLA- Very light aircraft</td>
<td>CS-E - Engines</td>
<td>CS-P - Propellers</td>
</tr>
<tr>
<td>CS-23- Normal, utility, aerobic, and commuter aeroplanes</td>
<td>CS-29 – Large Rotorcraft</td>
<td>CS-VLR- Very Light Rotorcraft</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CS-25 – Large Aeroplanes</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>NATO</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>STANAG 4671 – UAV System Airworthiness Requirements (USAR), Fixed wing aircraft weighing 150kg to 20,000 kg</td>
<td>STANAG 4702 – Rotary wing unmanned aircraft systems</td>
<td>Draft STANAG 4746- Vertical Take-off and landing (VTOL)</td>
<td>Referenced in STANAG 4703</td>
<td>Referenced in STANAG 4703</td>
</tr>
<tr>
<td>STANAG 4703 – Light unmanned aircraft systems</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Comparison</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Terminology such as: proof of structure FAA Fixed and rotary aircraft factor in additional engine part certification (Part 33)</td>
<td>STANAG 4702 is based on Parts 23, 27, and CS-23</td>
<td>CS-VLA has similarities to PART 21.178 Draft STANAG 4746 is based on EASA Essential Airworthiness and is Harmonized with STANAG 4703. 4746 and 4703 Use EASA CS-VLR as a basis; Includes Electric Propulsion Certification Requirements</td>
<td>CS-E shares similar standards to Part 33- Testing covers all thrust ratings Development assurance for software &amp; airborne Electronic Hardware under policy draft review</td>
<td>CS-P shares similar standards to Part 35- Bird Impact-Both require demonstration that the propeller can withstand the impact of a 4-pound bird for all airplanes.</td>
</tr>
</tbody>
</table>
APPENDIX 3A: SOCIETAL BARRIERS - FOCUS GROUPS METHODOLOGY

Process
- The Washington D.C. and Los Angeles focus groups were completed on June 7 and June 14, 2018 respectively
- A total of 15 people participated in both focus groups
- A written summary of findings is included in final report

Focus Group Structure
Focus group protocol followed the following structure:
- Pre-Focus Group Questionnaire
- Familiarity with Air Taxi and Urban Air Mobility
- Thoughts and Impressions about Urban Air Mobility
- Automation and Electrification
- Ownership versus Sharing
- Security and Safety
- Privacy
- Concerns as a Non-User
APPENDIX 3B: SOCIETAL BARRIERS - FOCUS GROUPS

Overview of Participant Demographics

- **Income:** Both focus groups contained a small number of very low-income participants with household incomes of less than $15,000 per year and larger numbers of middle-to-upper income participants earning more than $75,000 per year
- **Highest Level of Educational Attainment:** 60% of participants had a college degree; the remaining participants were evenly split between those with a high/school diploma or vocational training and those with some post-graduate studies
- **Age:** 47% of participants were 18 to 29 years old; the median across all focus group participants was 33 (average age 36)
- **Gender:** 60% Female; 40% Male
- **Race and Ethnicity:**
  - Los Angeles - 67% of the focus group participants were Caucasian compared to just 17% in Washington D.C.
  - Washington D.C. - 50% of focus group participants were African-American compared to 0% in Los Angeles
APPENDIX 3C: SOCIETAL BARRIERS – SURVEY DEMOGRAPHICS

Overview of Participant Demographics

- **Income**: Income distribution of respondents representative of present populations across the cities; closely matched the 2016 American Community Survey distribution
- **Age**: Wider age distribution than focus groups. 51% of respondents were over the age of 45.
- **Gender**: 57% Female; 43% Male
- **Highest Level of Educational Attainment**: More than 60% of participants had a college degree, with more than 30% either currently in the process of obtaining or possessing a graduate degree
- **Race and Ethnicity**: Slight underrepresentation of Latinos, ~14% overrepresentation of Caucasian/White alone across cities

<table>
<thead>
<tr>
<th>Race/Ethnicity</th>
<th>Total, N = 1688</th>
<th>Houston, N = 335</th>
<th>San Francisco Bay Area, N = 339</th>
<th>Los Angeles, N = 332</th>
<th>Washington, D.C., N = 338</th>
</tr>
</thead>
<tbody>
<tr>
<td>Hispanic or Latino alone</td>
<td>16%</td>
<td>18%</td>
<td>15%</td>
<td>15%</td>
<td>16%</td>
</tr>
<tr>
<td>Caucasian/White alone</td>
<td>55%</td>
<td>55%</td>
<td>54%</td>
<td>54%</td>
<td>54%</td>
</tr>
<tr>
<td>African American alone</td>
<td>10%</td>
<td>12%</td>
<td>12%</td>
<td>12%</td>
<td>12%</td>
</tr>
<tr>
<td>American Indian or Alaskan Native alone</td>
<td>1%</td>
<td>0%</td>
<td>0%</td>
<td>1%</td>
<td>1%</td>
</tr>
<tr>
<td>Asian alone</td>
<td>3%</td>
<td>3%</td>
<td>3%</td>
<td>3%</td>
<td>3%</td>
</tr>
<tr>
<td>Native Hawaiian or Pacific Islander alone</td>
<td>1%</td>
<td>2%</td>
<td>2%</td>
<td>2%</td>
<td>2%</td>
</tr>
<tr>
<td>Other alone</td>
<td>1%</td>
<td>1%</td>
<td>1%</td>
<td>1%</td>
<td>1%</td>
</tr>
<tr>
<td>Two or more races (excluding Hispanic)</td>
<td>0%</td>
<td>0%</td>
<td>0%</td>
<td>0%</td>
<td>0%</td>
</tr>
<tr>
<td>Prefer not to answer</td>
<td>1%</td>
<td>1%</td>
<td>1%</td>
<td>1%</td>
<td>1%</td>
</tr>
</tbody>
</table>

What is your race or ethnicity?
APPENDIX 4A: AIRPORT SHUTTLE BASE YEAR DEMAND COMPARISON FOR ALL URBAN AREAS

- On average ~4.5% of daily unconstrained trips are captured after applying constraints.

- San Francisco, Denver and Dallas are potential urban areas of high daily demand. New York demand capture is highly restricted due to current airport capacity constraint.

<table>
<thead>
<tr>
<th>Urban Area</th>
<th>Unconstrained</th>
<th>Infra + WTP</th>
<th>Capacity Constraint</th>
<th>APT capacity Constraint</th>
</tr>
</thead>
<tbody>
<tr>
<td>New York</td>
<td>21,000</td>
<td>9,900</td>
<td>8,600</td>
<td>310</td>
</tr>
<tr>
<td>Los Angeles</td>
<td>12,000</td>
<td>1,100</td>
<td>1,100</td>
<td>530</td>
</tr>
<tr>
<td>Dallas</td>
<td>13,000</td>
<td>900</td>
<td>900</td>
<td>870</td>
</tr>
<tr>
<td>Miami</td>
<td>10,000</td>
<td>400</td>
<td>400</td>
<td>410</td>
</tr>
<tr>
<td>Houston</td>
<td>11,000</td>
<td>900</td>
<td>800</td>
<td>390</td>
</tr>
<tr>
<td>San Francisco</td>
<td>14,000</td>
<td>7,100</td>
<td>3,300</td>
<td>1,290</td>
</tr>
<tr>
<td>Washington DC</td>
<td>11,000</td>
<td>3,100</td>
<td>1,100</td>
<td>410</td>
</tr>
<tr>
<td>Phoenix</td>
<td>7,000</td>
<td>200</td>
<td>200</td>
<td>80</td>
</tr>
<tr>
<td>Denver</td>
<td>11,000</td>
<td>900</td>
<td>700</td>
<td>690</td>
</tr>
<tr>
<td>Honolulu</td>
<td>2,000</td>
<td>1,000</td>
<td>200</td>
<td>190</td>
</tr>
</tbody>
</table>
APPENDIX 4B: OVER AT LEAST 85% OPERATIONS MAY BE FLOWN IN CONTROLLED AIRSPACE

Our first order assessment shows that more than 85% of the operations in most urban areas may be flown under controlled airspace. Existing air traffic control may not have sufficient capacity to administer the large amount of operations. New technologies like UTM will be needed to serve the Air Taxi market.

<table>
<thead>
<tr>
<th>Urban Area</th>
<th>Not Controlled Airspace (A)</th>
<th>Controlled Airspace (B)</th>
</tr>
</thead>
<tbody>
<tr>
<td>New York</td>
<td>10%</td>
<td>90%</td>
</tr>
<tr>
<td>Los Angeles</td>
<td>10%</td>
<td>90%</td>
</tr>
<tr>
<td>Dallas</td>
<td>15%</td>
<td>85%</td>
</tr>
<tr>
<td>Miami</td>
<td>5%</td>
<td>95%</td>
</tr>
<tr>
<td>Houston</td>
<td>16%</td>
<td>84%</td>
</tr>
<tr>
<td>San Francisco</td>
<td>12%</td>
<td>88%</td>
</tr>
<tr>
<td>Washington DC</td>
<td>22%</td>
<td>78%</td>
</tr>
<tr>
<td>Phoenix</td>
<td>13%</td>
<td>87%</td>
</tr>
<tr>
<td>Denver</td>
<td>36%</td>
<td>64%</td>
</tr>
<tr>
<td>Hawaii</td>
<td>11%</td>
<td>89%</td>
</tr>
</tbody>
</table>

1 Our analysis assumes that a mission is completed on a great circle track. We simply add detour factor to take into account deviation in flight tracks based on airspace, noise, weather constraints etc. However, airspace design is a complicated process as shown by active researches done at MIT, NASA etc.

Note: Subset of the trips (>~1 trip/hr per infrastructure) shown for Dallas in the above figures.

In this case, O-D infrastructure are outside the controlled (B-E) airspace (CA). Since flight path may still intersect CA, operators can make a detour (captured under detour factor) and not fly great circle track to avoid CA.

In this case, either origin or destination infrastructure are in the controlled (B-E) airspace (CA). Therefore, CA cannot be avoided using detours or other track efficiency metrics.
APPENDIX 4C: LARGE PERCENTAGE OF OPERATIONS ARE IN THE AREAS OF LOW BACKGROUND NOISE

• Our preliminary first order noise analysis (available in ‘Air Taxi Interim Deliverable’) showed that noise exposure is expected to be more severe near the take-off and landing areas. Also, there may be ways to mitigate noise impacts while in flight by choosing routes and flying altitude of minimum impact.

• Urban areas like Washington DC, Los Angeles and Miami have most of their operations in areas of high background noise (greater than 50 dB as defined by Federal Highway Administration). Public acceptance to Air Taxi operations in these urban areas may be higher in comparison to New York, Hawaii or Denver
APPENDIX 4D: AIR TAXI WILL LIKELY ADD SIGNIFICANT AMOUNT OF WELL TO WAKE GHG EMISSIONS AS COMPARED TO ELECTRIC CARS

- On average, Air Taxi market at the system level is likely contribute 40-50% well-to-wake (WTW) GHG emissions as compared to Tesla Model S 75D when the same Air Taxi mission is performed by Tesla on the ground.

- To serve the near term Air taxi demand in Urban areas like New York and Los Angeles alone, more than 1,000 metric tonne of combined WTW CO$_2$ emissions might be added to the atmosphere based on current sources of electricity generation.
APPENDIX 5A: TECHNOLOGY AND INFRASTRUCTURE SCENARIOS

We outline a set of illustrative technology and infrastructure scenarios to measure the order-of-magnitude implications of improvements and investments in technology and infrastructure proposed to be used for Urban Air Mobility. Each of these scenarios are evaluated independently first and then in an integrated form.

**Technology Improvements**

This scenario includes improvements in battery technology and reduction of vehicle cost due to manufacturing learning and experience.

- Li-ion battery capacity specific cost is expected to fall to the $100/kWh to $150/kWh price range by 2025 at a $10/kWh annual reduction (Nykvist)
- On average, vehicle cost reduces by ~15% on doubling the production (source: NASA). We double the production every five years.

**High Network Efficiency**

Network efficiency parameters like load factor, utilization and dead-end trips are among the most significant parameters that influence the operating cost (slide 56). We consider following improvements in these factors:

- **Utilization**: ~7 hours/day (from ~4 hours/day) may be possible due to supercharging, higher system capacity, demand etc.
- **Load Factor**: ~80% (from ~65%) similar to commercial aviation
- **Deadend trips**: ~20% (from ~37.5%)

**Infrastructure Improvements**

This scenario assumes enhancement to the current air traffic system (or a developed UTM system), which allows in-part an increase of vertiport’s operations capacity

- Increase in number of vertiports is coupled with increase in capacity. We **double the number of vertiports and operational capacity every five years** to measure new demand.

**Autonomous eVTOL**

Most of the vehicles being developed are expected to have the capability to be fully autonomous. Given the pilot shortages facing the aviation industry and the scale of UAM operations anticipated, autonomy may play a key role to fully capture the realized demand. For this scenario we assume the following:

- **Pilot not required**, and therefore **all the seats are available to passengers**
- **An extra ground staff** required to do safety briefings, loading and unloading of passengers.
APPENDIX 5B: DEMAND SCENARIOS

We outline a set of illustrative scenarios to measure the order-of-magnitude implications of new technologies / concepts like autonomous cars, telecommuting trends and new importance to travel time due to other enabling teleconferencing technologies. Each of these scenarios are evaluated independently first and then in an integrated form.

**E  New importance of travel time**

Continuous advancement in Virtual Reality / Augmented Reality, large screens, new interiors in ground vehicles and other teleconferencing technologies may enhance the productivity of the human driver/passenger while in transit. Increased productivity may result in decrease in value of travel time, thereby affecting demand of Urban Air Taxis.

We evaluate the importance of travel time/cost by introducing a significance factor in the utility function (slide 83) and vary it between 0 and 1. ‘0’ represents no importance to travel time and the user is expected to chose the mode entirely based on price, comfort etc.

**F  Competition from other modes**

Autonomous cars, high speed rails and many new or improved existing modes of transportation may pose a potential challenge to the adoption / demand of urban air taxis. Under this scenario, we examine the emergence of fully autonomous vehicles (AVs) only.

BCG U.S. Self-Driving Cars survey 2014 showed strong willingness among the American consumers to buy autonomous cars. The analysis further shows a penetration rate of 0.5% and 10% in 2025 and 2035 for full AVs. At an average occupancy rate of ~65% (similar to eVTOL), we use ~$0.9 cost per passenger mile, which is ~35% less than current car ownership / operating costs in our mode choice model.

**G  Telecommuting**

Regular telecommuting grew 115% in the past decade (i.e. ~10% annual), nearly 10 times faster than the rest of the workforce. Current telecommuting population of 3.9 million (3% of total workforce) avoided 530 million trips or 7.8 vehicle miles annually (source: Global Workforce Analytics).

We consider a scenario where telecommuting continues to increase\(^1\) at a rate of ~10% every year to scope the available demand.

\(^1\)Several researches have shown a possible reverse trend in telecommuting where companies (like IBM) are restricting telework (source: Comcast, Blank Rome LLP, IBM).

**H  Congestion & Latent Demand**

eVTOLs can induce new mobility patterns including de-urbanization i.e. people moving out of the city due to faster transportation options available. We explore such a scenario using parametric analysis by varying average distances for each trip by -25% to +25% at an interval of 1%. Negative percentage indicates increased urbanization.

Finally, mega cities can get more congested over time. However, in some scenarios (more pooling, better public transportation etc.), cities can also de-congest. We explore such possibilities by varying average driving speed by -25% to 25% at an interval of 10%. Positive percent indicates increased congestion.
APPENDIX 6A: UAM PROJECT TEAM

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