

2013 NASA Annual IV&V Workshop
Fairmont, WV, USA
September 10 - 12, 2013

Modeling the Image- Processing Behavior of the NASA Voyager Mission with ASSL

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September 12, 2013

Outline

Presentation

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- 2. Voyager and Our Research Objectives**
- 3. ASSL**
- 4. ASSL Model for Voyager**
- 5. Discussion, Future Work, and Benefits**

Introduction

AC & Space Exploration

Autonomic Computing (AC) – a solution to software complexity:

- ✓ Helps to implement self-adaptive and autonomic systems (ASs);
- ✓ Autonomic elements (AEs) – the architectural components of an autonomic system (AS)
- ✓ AC may handles complexity in spacecraft computer systems

The new age of space exploration: NASA embarks in AC

- ✓ AC software helps to build the next generation of unmanned spacecraft;
- ✓ Autonomous Nano-Technology Swarm (ANTS) concept mission;
- ✓ Deep Space One (DS1) mission;

Introduction

Our Approach – Prototyping with ASSL

AC-based Voyager-like missions:

- ✓ Investigate hypotheses about the design and implementation of future Voyager-like missions based on the AC principles.
- ✓ Build prototype software models:
 - ✓ help in the comparison of features and issues of the actual Voyager mission with hypothesized possible autonomic approaches;
 - ✓ bring significant benefits to the development of future space-exploration systems.
- ✓ We experiment with **ASSL** (Autonomic System Specification Language) to realize these goals.

Voyager and Our Research Objectives

The Voyager Mission

- ✓ an extremely successful example for future space missions;
- ✓ designed for exploration of the Solar System;
- ✓ continue to explore the space: now on the special **Voyager Interstellar Mission**;



Voyager Spacecraft [The Planetary Society, “Space topics: Voyager – the story of the mission”]

Factors of success:

- ✓ rigorous spacecraft design and implementation;
- ✓ spacecraft hardware was designed to allow for enhanced remote control programming;
- ✓ autonomous behavior persists in the Voyager requirements;

Voyager and Our Research Objectives

Objectives

Long-term objectives:

- ✓ model and implement with ASSL AS prototypes of future Voyager-like missions;
- ✓ benchmark experiments - compare prototyped autonomic features and issues with the actual Voyager Mission;
- ✓ validate features in question and perform further investigations based on practical results under simulated conditions;

First objective:

- ✓ specify with ASSL and generate a prototype model for the *image-processing behavior* observed in the Voyager mission.

Event-driven behavior: *Voyagers are able to detect space objects and take pictures of the same on-the-fly*

Specification Model

I. Autonomic System (AS)

- AS Service-Level Objectives
- AS Self-Management Policies
- AS Architecture
- AS Actions
- AS Events
- AS Metrics

II. AS Interaction Protocol (ASIP)

- AS Messages & Negotiation Protocol
- AS Communication Channels
- AS Communication Functions

III. Autonomic Element (AE)

- AE Service-Level Objectives
- AE Self-Management Policies
- AE Friends
- AE Interaction Protocol (AEIP)
 - AE Messages & Negotiation Protocol
 - AE Communication Channels
 - AE Communication Functions
 - AE Managed Resource Interface
- AE Recovery Protocols
- AE Behavior Models
- AE Outcomes
- AE Actions
- AE Events
- AE Metrics

- scalable specification model;
- provides judicious selection and configuration of infrastructure elements and mechanisms for ASs;
- decomposes an AS in two directions – 1) into levels of functional abstraction; 2) into functionally related sub-tiers;
- presents the system from three different perspectives – 1) AS; 2) ASIP; 3) AE;
- meets the AS builders needs;
- flexible approach to specification.

Specifying and Generating Prototypes with ASSL

- ✓ ASSL tiers - intended to specify different aspects of an AS, but only a few are needed to come up with a working model;
- ✓ an ASSL specification is built around self-management policies, which make that specification AC-driven;
- ✓ a complete specification:
 - ✓ is validated with a built-in consistency checking tool;
 - ✓ is used to automatically generate a functional prototype.
- ✓ generated prototypes: fully-operational multithreaded event-driven applications with embedded messaging;

Specifying and Generating Prototypes with ASSL

- ✓ ASSL tiers - intended to specify different aspects of an AS, but only a few are needed to come up with a working model;

ASSL Policy Specification

- ✓ an ASSL policy, **SELF_MANAGEMENT** {
policies, **SELF_HEALING** {
management
en;

- ✓ a complete policy specification:
 - ✓ is valid
 - ✓ is usable

```

FLUENT inLosingSpacecraft {
  INITIATED_BY { EVENTS.spaceCraftLost }
  TERMINATED_BY { EVENTS.earthNotified }
}
MAPPING {
  CONDITIONS { inLosingSpacecraft }
  DO_ACTIONS { ACTIONS.notifyEarth }
}

```

- ✓ generate a working tool;
a prototype.
readed event-driven applications with embedded messaging;

ASSL Model for Voyager

Specified Image-Processing Behavior

1. The Voyager II spacecraft:

- uses its cameras to monitor space objects;
- takes a picture with its cameras;
- notifies Earth that an image transmission is about to start;
- applies color filters and sends the stream of pixels to Earth;
- notifies antennas on Earth for the end of each session.

2. Antennas on Earth:

- are prompted to receive the image by special messages (one per applied filter);
- receive image pixels;
- are prompted to terminate the image sessions by special messages;
- send the collected images to the Voyager Mission base on Earth.

3. The Voyager Mission base on Earth receives images from antennas.

ASSL Model for Voyager

ASSL Specification

- ✓ we specified Voyager at the three main ASSL tiers – AS tier, ASIP tier, and AE tier;
- ✓ we specified the Voyager II spacecraft and the antennas on Earth as AEs that:
 - ✓ follow their encoded autonomic behavior;
 - ✓ exchange predefined ASSL messages over predefined ASSL communication channels.
- ✓ the Voyager mission autonomic behavior is specified at both AS and AE tiers as a self-management policy:
 - ✓ the global autonomic behavior is determined by the specification of that policy at each AE and at the global AS tier.

ASSL Model for Voyager

ASSL Specification - AS Tier specification

✓ IMAGE_PROCESSING self-management policy

```
FLUENT inProcessingImage_AntSpain {  
  INITIATED_BY { EVENTS.imageAntSpainReceived }  
  TERMINATED_BY { EVENTS.imageAntSpainProcessed }  
}  
MAPPING {  
  CONDITIONS { inProcessingImage_AntAustralia }  
  DO_ACTIONS { ACTIONS.processImage("Antenna_Australia") }  
}
```

```
ACTION IMPL processImage {  
  PARAMETERS { string antennaName }  
  GUARDS {  
    ASSELF_MANAGEMENT.OTHER_POLICIES.  
    IMAGE_PROCESSING.inProcessingImage_AntAustralia  
    OR  
    ASSELF_MANAGEMENT.OTHER_POLICIES.  
    IMAGE_PROCESSING.inProcessingImage_AntJapan  
    ...  
  }  
  TRIGGERS {  
    IF antennaName = "Antenna_Australia" THEN  
      EVENTS.imageAntAustraliaProcessed  
    END ELSE ...  
  }  
}
```

```
EVENT imageAntSpainReceived {  
  ACTIVATION {  
    RECEIVED { ASIP.MESSAGES.msgImageAntSpain }  
  }  
}  
EVENT imageAntSpainProcessed {}
```

ASSL Model for Voyager

ASSL Specification – AE Voyager

✓ IMAGE_PROCESSING self-management policy

```
AESELF_MANAGEMENT {  
  OTHER_POLICIES {  
    POLICY IMAGE_PROCESSING {  
      FLUENT inTakingPicture {  
        INITIATED_BY { EVENT S.timeToTakePicture }  
        TERMINATED_BY { EVENT S.pictureTaken }  
      }  
      FLUENT inProcessingPicturePixels {  
        INITIATED_BY { EVENT S.pictureTaken }  
        TERMINATED_BY { EVENT S.pictureProcessed }  
      }  
      MAPPING {  
        CONDITIONS { inTakingPicture }  
        DO_ACTIONS { ACTIONS.takePicture }  
      }  
      MAPPING {  
        CONDITIONS { inProcessingPicturePixels }  
        DO_ACTIONS { ACTIONS.processPicture }  
      }  
    }  
  }  
} // AESELF_MANAGEMENT
```

```
EVENT timeToTakePicture {  
  ACTIVATION {  
    CHANGED { METRICS.interestingObjects }  
    OR  
    PERIOD { 60 SEC }  
  }  
}
```

```
METRIC interestingObjects {  
  METRIC_TYPE { RESOURCE }  
  METRIC_SOURCE { AEIP.MANAGED_ELEMENTS.  
    wideAngleCamera.countInterestingObjects }  
  THRESHOLD_CLASS { integer [ 0 ~ ) }  
}
```

```
MANAGED_ELEMENT wideAngleCamera {  
  ...  
  INTERFACE_FUNCTION countInterestingObjects {  
    RETURNS { integer }  
  }  
}
```

```
INTERFACE_FUNCTION takePicture { }
```

ASSL Model for Voyager

ASSL Specification – Antenna AEs

✓ IMAGE_PROCESSING self-management policy

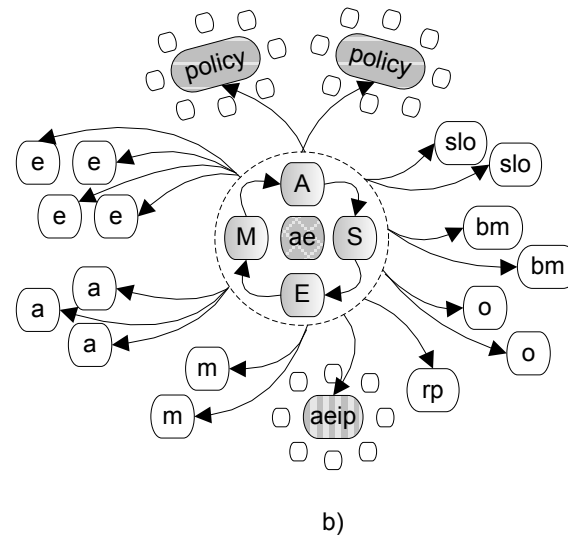
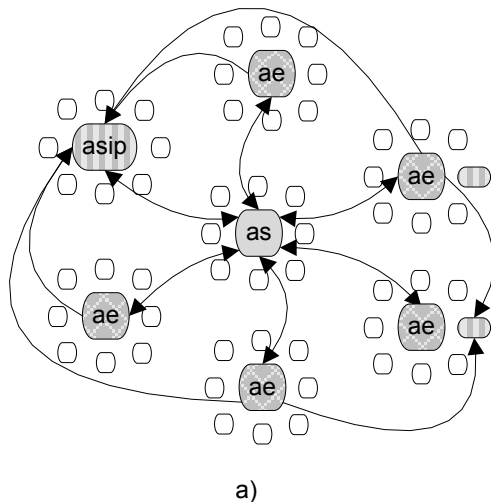
```
FLUENT inStartingGreenImageSession {  
  INITIATED_BY { EVENTS.greenImageSessionIsAboutToStart }  
  TERMINATED_BY { EVENTS.imageSessionStartedGreen }  
}  
FLUENT inCollectingImagePixelsBlue {  
  INITIATED_BY { EVENTS.imageSessionStartedBlue }  
  TERMINATED_BY { EVENTS.imageSessionEndedBlue }  
}
```

```
EVENT greenImageSessionIsAboutToStart {  
  ACTIVATION { SENT { AES.Voyager.AEIP.MESSAGES.  
    msgGreenSessionBeginAus } }  
}  
EVENT imageSessionStartedBlue {  
  ACTIVATION { RECEIVED { AES.Voyager.AEIP.MESSAGES.  
    msgBlueSessionBeginAus } }  
}
```

ASSL Model for Voyager

Structure of the Generated Prototype

- ✓ a pure software solution – both spacecraft and antennas are implemented as interacting components in a Java application;
- ✓ has a multi-granular structure composed of instances (objects) of the specified tiers in the ASSL specification:
 - ✓ a hierarchical composition where sub-tier instances are grouped around instances of major tiers.



ASSL Model for Voyager

Behavior of the Generated Prototype

- ✓ log records show important state-transition operations ongoing in the system;
- ✓ these records help to trace and evaluate the behavior of the generated prototype model;

Test results:

The run-time behavior of the generated prototype model for the Voyager II mission strictly followed that specified with the ASSL IMAGE_PROCESSING self-management policy.

ASSL Model for Voyager

Behavior of the Generated Prototype

✓ log records show important state-transition operations

ongoing

✓ these

generated

Test results

*The run-
Voyager
IMAGE_*

```
99) EVENT 'as.aes.voyager.events.TIMEOTAKEPICTURE': has occurred
100) FLUENT 'as.aes.voyager.aeself_management.image_processing.INTAKINGPICTURE':
    has been initiated
101) ACTION 'as.aes.voyager.actions.TAKEPICTURE': has been performed
102) EVENT 'as.aes.voyager.events.PICTURETAKEN': has occurred
103) FLUENT 'as.aes.voyager.aeself_management.image_processing.INTAKINGPICTURE':
    has been terminated
104) FLUENT 'as.aes.voyager.aeself_management.image_processing.
    INPROCESSINGPICTUREPIXELS': has been initiated
105) ACTION 'as.aes.voyager.actions.PROCESSFILTEREDPICTURE': has been performed
106) ACTION 'as.aes.voyager.actions.PROCESSFILTEREDPICTURE': has been performed
107) ACTION 'as.aes.voyager.actions.PROCESSFILTEREDPICTURE': has been performed
108) ACTION 'as.aes.voyager.actions.PROCESSPICTURE': has been performed
109) EVENT 'as.aes.voyager.events.PICTUREPROCESSED': has occurred
110) EVENT 'as.aes.antenna_japan.events.BLUEIMAGESESSIONISABOUTTOSTART': has
    occurred
111) EVENT 'as.aes.antenna_spain.events.REDIMAGESESSIONISABOUTTOSTART': has
    occurred
112) FLUENT 'as.aes.antenna_spain.aeself_management.image_processing.
    INSTARTINGREDIMAGESESSION': has been initiated
113) FLUENT 'as.aes.antenna_japan.aeself_management.image_processing.
    INSTARTINGBLUEIMAGESESSION': has been initiated
114) EVENT 'as.aes.antenna_spain.events.BLUEIMAGESESSIONISABOUTTOSTART': has
    occurred
115) FLUENT 'as.aes.voyager.aeself_management.image_processing.
    INPROCESSINGPICTUREPIXELS': has been terminated
....
```

Behavior of the

*Model for the
the ASSL*

Discussion, Future Work, Benefits

Discussion & Future Work

- ✓ image-processing - programmed as an autonomic policy, but does not extend the original event-driven behavior observed in the Voyager Mission;
- ✓ the Voyager's prototype abstracts most of the spacecraft components;
- ✓ the next prototype model:
 - ✓ will specify the spacecraft's radio, antenna, and two cameras as distinct managed elements - this will allow the evaluation of component behavior (via ASSL metrics and events);
 - ✓ will extend the IMAGE_PROCESSING policy with other self-management features – two scenarios are planned: *remote-assistance self-healing* and *on-board self-healing*.

Discussion, Future Work, Benefits

Future Work Goals

- ✓ further prototype development:
 - ✓ detailed specification of the Voyager spacecraft components;
 - ✓ new autonomic features - self-healing, self-protecting, and self-adapting policies;
- ✓ construct an intelligent Voyager-like system able to react automatically to hazards in space by finding possible solutions and applying those on-board with no human interaction;
- ✓ a new ASSL model checking mechanism is currently under development – this will allow for automatic feature validation and discovery of design flaws;

Discussion, Future Work, Benefits

Benefits For Space Systems

- ✓ both the ASSL specifications and the generated prototypes can be extremely useful for the design and implementation of future Voyager-like missions;
- ✓ the ability to compare features and issues with the actual mission and with hypothesized possible autonomic approaches gives significant benefit;
- ✓ we develop Voyager prototypes incrementally where each new prototype includes new autonomic features - this helps to evaluate the performance of each feature and gradually construct a model of a future Voyager-like system;
- ✓ this approach helps to discover eventual design flaws in both the original system and the prototype models;

Questions

Thank You!